

QFT 570 Homework 6

Lorentz Symmetry

a.

Quickly following the hint to show that the property $\sigma_2 \sigma_i^T \sigma_2 = -\sigma_i$ is true through application of 1.) the pauli matrices' anti-commutation property $\{\sigma_i, \sigma_j\} = 0$ and 2.) the fact that they all square to the identity:

1. The transpose of σ_1 is itself:

$$\sigma_1 \sigma_2 + \sigma_2 \sigma_1 = 0 \longrightarrow \sigma_2 \sigma_1^T \sigma_2 = -\sigma_1$$

2. The transpose of σ_2 is negative itself:

$$\sigma_2 \sigma_2^T \sigma_2 = -\sigma_2$$

3. The transpose of σ_3 is itself:

$$\sigma_3 \sigma_2 + \sigma_2 \sigma_3 = 0 \longrightarrow \sigma_2 \sigma_3^T \sigma_2 = -\sigma_3$$

Thus,

$$\sigma_2 \sigma_i^T \sigma_2 = -\sigma_i$$

So we have a transformation of ϕ defined as

$$\phi_{is} \rightarrow \left[e^{i(\vec{\theta} + i\vec{\omega}) \cdot \vec{A}} \right]_{ij} \left[e^{i(\vec{\theta} - i\vec{\omega}) \cdot \vec{B}} \right]_{st} \phi_{jt} \equiv D_{ij}^{jA}(\vec{\theta}, \vec{\omega}) D_{st}^{jB}(\vec{\theta}, \vec{\omega}) \phi_{jt} \quad (1)$$

To write this transformation in matrix notation, we must order the indices leading to the necessity of a transpose operation on the second D .

$$\phi = \chi \sigma_2 \rightarrow D^{jA}(\vec{\theta}, \vec{\omega}) \phi D^{jB}(\vec{\theta}, \vec{\omega})^T \quad (2)$$

$$= D^{jA}(\vec{\theta}, \vec{\omega}) \chi \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} D^{jB}(\vec{\theta}, \vec{\omega}) \sigma_2 D^{jB}(\vec{\theta}, \vec{\omega})^T \quad (3)$$

$$= D^{jA}(\vec{\theta}, \vec{\omega}) \chi \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} D^{jB}(\vec{\theta}, \vec{\omega}) \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} \sigma_2 \quad (4)$$

$$= D^{jA}(\vec{\theta}, \vec{\omega}) \chi \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} \sigma_2 \quad (5)$$

$$\chi \rightarrow D^{jA}(\vec{\theta}, \vec{\omega}) \chi \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} \quad (6)$$

In the first line, I have inserted $\mathbf{1}$ between χ and σ_2 in the definition of $\phi = \chi \sigma_2$. In the next line, I use the equation in the hint to state $\sigma_2 \sigma_i^T = -\sigma_i \sigma_2$ and thus pulling σ_2 to the right causes the transposed transformation to become the inverse (ok, the added identity was completely unnecessary...). More rigorously, this may be shown by expanding D 's exponential form. From here, we may simply right-multiply by σ_2 on both sides to isolate the transformation of χ .

b.

If χ transforms as

$$\chi \rightarrow D^{jA}(\vec{\theta}, \vec{\omega}) \chi \left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1}$$

we can make a statement about the transformation property of the determinant by applying the fact $\det(\mathbf{AB}) = \det(\mathbf{A}) \det(\mathbf{B})$. Taking the determinant of both sides:

$$\det \chi \rightarrow \det \left[D^{jA}(\vec{\theta}, \vec{\omega}) \right] \det \left[\left(D^{jB}(\vec{\theta}, \vec{\omega}) \right)^{-1} \right] \det \chi \quad (7)$$

Imagine that the matrices representing the Lorentz transformation can be diagonalized. The determinant is simply the product of eigenvalues. The determinant of the inverse is the product of eigenvalues⁻¹. Eigenvalue-by-eigenvalue, this product will be unity and thus the determinant of χ is invariant under Lorentz transformation.

c.

Writing χ as $p_\mu \sigma^\mu$, χ is written as:

$$\chi = \begin{pmatrix} p_0 + p_3 & p_1 - ip_2 \\ p_1 + ip_2 & p_0 - p_3 \end{pmatrix} \quad \det \chi = p_0^2 - p_1^2 - p_2^2 - p_3^2 \quad (8)$$

When expressed in terms of a 4-vector notation, the determinant is suggestive of the dot product $p \cdot p$ in a mostly-minus metric and is thus not surprising that it is a lorentz invariant.

d. and e.

Under rotations where $\vec{\omega} = 0$ or boosts where $\vec{\theta} = 0$, the $(\frac{1}{2}, \frac{1}{2})$ transformation matrices simplify.

$$D_{ij}^{jA}(\vec{\theta}, 0) = \left[e^{\frac{i}{2} \vec{\theta} \cdot \vec{\sigma}} \right]_{ij} \quad D_{ij}^{jB}(\vec{\theta}, 0) = \left[e^{\frac{i}{2} \vec{\theta} \cdot \vec{\sigma}} \right]_{ij}$$

$$D_{ij}^{jA}(0, \vec{\omega}) = \left[e^{-\frac{1}{2} \vec{\omega} \cdot \vec{\sigma}} \right]_{ij} \quad D_{ij}^{jB}(0, \vec{\omega}) = \left[e^{\frac{1}{2} \vec{\omega} \cdot \vec{\sigma}} \right]_{ij}$$

We can show that χ 's transformation properties may be summarized into the 4-vector nature of p_μ in general by using Mathematica and looking at the following equalities:

$$\chi \rightarrow D^{jA}(\vec{\theta}, 0) \chi \left(D^{jB}(\vec{\theta}, 0) \right)^{-1} \stackrel{?}{=} \left[e^{i\vec{\theta} \cdot \vec{J}} \right]_\mu^\nu p_\nu \sigma^\mu \quad \text{and} \quad \chi \rightarrow D^{jA}(0, \vec{\omega}) \chi \left(D^{jB}(0, \vec{\omega}) \right)^{-1} \stackrel{?}{=} \left[e^{i\vec{\omega} \cdot (-\vec{K})} \right]_\mu^\nu p_\nu \sigma^\mu$$

```
J1 = SparseArray[{{3, 4} -> -i, {4, 3} -> i}];
J2 = SparseArray[{{2, 4} -> i, {4, 2} -> -i}];
J3 = SparseArray[{{2, 3} -> -i, {3, 2} -> i, {4, 4} -> 0}];
Jvec = {J1, J2, J3};
pmu = {p0, p1, p2, p3};
omu = {IdentityMatrix[2], PauliMatrix[1], PauliMatrix[2], PauliMatrix[3]};
ovec = {o1, o2, o3};
```

```
Simplify[Simplify[ExpToTrig[(MatrixExp[i ovec.Jvec].pmu).omu]] ==
Simplify[ExpToTrig[MatrixExp[ $\frac{i}{2}$  ovec.omu[[2 ;; 4]]].(pmu.omu).
MatrixExp[ $-\frac{i}{2}$  ovec.omu[[2 ;; 4]]]]]]
```

True

```
K1 = SparseArray[{{1, 2} -> -i, {2, 1} -> -i, {4, 4} -> 0}];
K2 = SparseArray[{{1, 3} -> -i, {3, 1} -> -i, {4, 4} -> 0}];
K3 = SparseArray[{{1, 4} -> -i, {4, 1} -> -i}];
Kvec = {-K1, K2, K3};
pmu = {p0, p1, p2, p3};
omu = {IdentityMatrix[2], PauliMatrix[1], PauliMatrix[2], PauliMatrix[3]};
ovec = {o1, o2, o3};
```

```
Simplify[
Simplify[ExpToTrig[MatrixExp[- $\frac{1}{2}$  ovec.omu[[2 ;; 4]]].(pmu.omu).
MatrixExp[- $\frac{1}{2}$  ovec.omu[[2 ;; 4]]]]] ==
Simplify[ExpToTrig[(MatrixExp[i ovec.Kvec].pmu).omu]]]
```

True