

# Viscous Effects on the Mapping of the Initial to Final State in Heavy Ion Collisions

F.Gardim, J.Noronha-Hostler, M.Luzum, FG, PRC91 (2015) 034902,  
F.Gardim, FG, M.Luzum, J.-Y.Ollitrault, PRC85 (2012) 024908.

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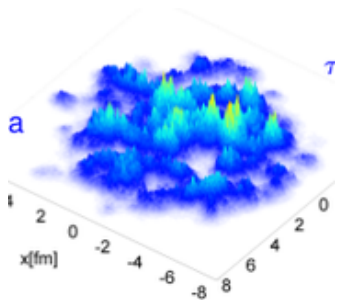
INT 2015

# Outline

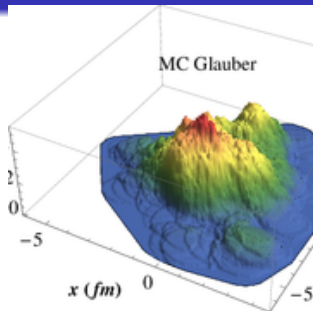
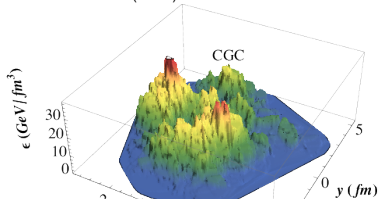
- 1 Introduction
- 2 Setting up the estimator
- 3 Computing the flow coefficients with hydro
- 4 Results for the mapping
- 5 Conclusion

# Examples of Initial Conditions

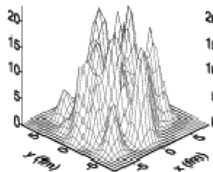
## Energy Density profile



Schenke, Tribedy, Venugopalan, Phys.Rev.Lett. 108 (2012) 252301



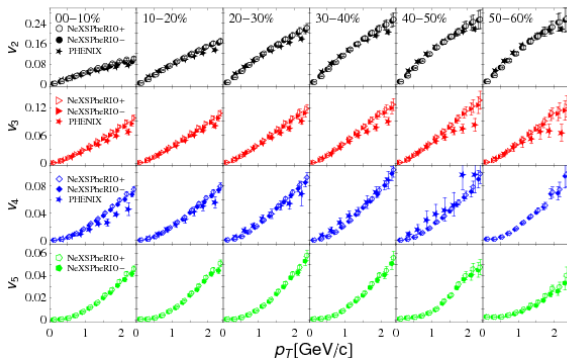
Drescher, Nara, Phys. Rev. C 75, 034905 (2007); ,76, 041903 (2007).



Drescher, Hladik, Ostapchenko, Pierog, Werner, Phys.Rept. 350, 93 (2001)

# Hydrodynamics prediction for flow harmonics

NeXSPheRIO (ideal hydro) fits the flow harmonics well



Gardim, Grassi, Luzum, Ollitrault, Phys.Rev.Lett. 109 (2012) 202302

So do models with shear viscosity and shear+bulk viscosities.

# Objective

Study the mapping between initial conditions and flow harmonics.

Many works on the subject:

- H. Petersen, G. Y. Qin, S. A. Bass and B. Muller, Phys.Rev. C82 , 041901 (2010)
- B. Schenke, S. Jeon and C. Gale, Phys. Rev. Lett.106, 042301 (2011)
- Z. Qiu and U. W. Heinz, Phys. Rev. C84 , 024911 (2011)
- Z. Qiu, C. Shen and U. Heinz, Phys. Lett. B707, 151(2012)
- B. Alver and G. Roland, Phys. Rev. C81, 054905 (2010) [Erratum-ibid. C82 , 039903 (2010)]
- B. H. Alver, C. Gombeaud, M. Luzum and J. Y. Ollitrault, Phys. Rev. C82, 034913 (2010)
- M. Luzum and H. Petersen, J. Phys. G41, 063102 (2014)
- F. G. Gardim, F. Grassi, M. Luzum and J. -Y. Ollitrault, Phys. Rev. C85, 024908 (2012)
- H. Niemi, G. S. Denicol, H. Holopainen and P. Huovinen, Phys. Rev. C87, 054901 (2013)
- ...

Here: systematic study.

# Characterizing the initial state

Use the cumulant expansion of Teaney & Yan PRC 83, 064904 (2011):

$\rho(\mathbf{x}) \sim$  energy or entropy density

$$\rightarrow \rho(\mathbf{k}) = \int d^2x \rho(\mathbf{x}) e^{i\mathbf{k}\cdot\mathbf{x}}$$

$$\rightarrow W(\mathbf{k}) \equiv \ln \rho(\mathbf{k}) = \sum_{n=-\infty}^{\infty} \sum_{m \geq |n|} W_{n,m} k^m e^{-in\phi_k}$$

Useful properties:

- $n$  specifies the rotation symmetry and only  $n \geq 0$  matters (because  $W_{-n,m} \propto W_{n,m}^*$ ),
- $m - n$  is even and  $m \geq n$ ,
- Hydro sensitive only to large scale  $\Rightarrow$  truncate the sum  $m \leq m_{max}$ .

Examples ( $\{\} =$  weighted average over  $\rho(\mathbf{x})$ ):

$W_{1,1} = 0$ ,  $W_{0,2} \propto \{r^2\}$ ,  $W_{2,2} \propto \{r^2 e^{i2\phi}\}$ ,  $W_{1,3} \propto \{r^3 e^{i\phi}\}$  etc.

So:  $\epsilon_2 = |2W_{2,2}/W_{0,2}|$ ,  $\epsilon_1 \propto |W_{1,3}|$  etc.

# Find a best estimator $V_{est,n}$

**Step 1:** Find  $V_{est,n}$  computed from the initial state properties, estimator for

$V_n = v_n e^{in\Psi_n}$ , complex flow coefficient, obtained from hydro.

Since  $W_{n \neq 0,m}$  small, write (including only cumulants leading to same rotation properties as  $V_n$ ):

$$V_{est,n} = \sum_{m=n}^{m_{max}} k_{n,m} W_{n,m} + \sum_{l=1}^{m_{max}} \sum_{m=l}^{m_{max}} \sum_{m'=|n-l|}^{m_{max}} K_{l,m,m'} W_{l,m} W_{n-l,m'} + O(W^3).$$

It is common to use the eccentricities to build estimators but they are not cumulants.  $\varepsilon_{n,m} e^{i\Phi_{n,m}} \equiv -\frac{\{r^m e^{in\phi}\}}{\{r^m\}}$  (We can revert to them in the end.)

## Step 2: Make the best estimator

For simplicity, suppose  $V_{est,n}$  has only one term and re-write

$$V_{est,n} = k_{n,m} W_{n,m} = k \mathcal{V}_{est,n}$$

with  $k$  a real scaling coefficient and  $\mathcal{V}_{est,n}$  unscaled.

Define the error vector  $V_n \equiv V_{est,n} + \mathcal{E}_n = k \mathcal{V}_{est,n} + \mathcal{E}_n$

Minimize  $\langle |\mathcal{E}_n|^2 \rangle$  in a given centrality bin

$$\Rightarrow \begin{cases} k = \frac{\text{Re} \langle V_n \mathcal{V}_{est,n}^* \rangle}{\langle |\mathcal{V}_{est,n}|^2 \rangle} \\ \langle |\mathcal{E}_n|^2 \rangle = \langle |V_n|^2 \rangle - \langle |V_{est,n}|^2 \rangle. \end{cases}$$

From this last equation, we define the quality of the estimator:

$$Q_n^2 \equiv \frac{\langle |V_{est,n}|^2 \rangle}{\langle |V_n|^2 \rangle} = 1 - \frac{\langle |\mathcal{E}_n|^2 \rangle}{\langle |V_n|^2 \rangle}$$

The closer  $Q_n$  to 1, the better the estimator.



# Effect of viscosity on fluid evolution

Based on J.Noronha-Hostler et al. PRC88(2013)044916,  
PRC90(2014)034907

## Equations of Motion

### Conservation of Energy and Momentum

$$D_\mu T^{\mu\nu} = 0,$$

The energy-moment tensor contains a bulk viscous pressure  $\Pi$  and shear stress tensor  $\pi^{\mu\nu}$

$$T^{\mu\nu} = (\epsilon + \rho + \Pi) u^\mu u^\nu - (\rho + \Pi) g^{\mu\nu} + \pi^{\mu\nu}$$

### Using memory function method and minimal IS description

$$\tau_\Pi u^\mu D_\mu \Pi + \Pi = -(\zeta + \tau_\Pi \Pi) D_\mu u^\mu$$

$$\tau_\pi \Delta^{\mu\nu\lambda\rho} u^\alpha D_\alpha \pi_{\lambda\rho} + \pi^{\mu\nu} = \eta \sigma^{\mu\nu} - \tau_\pi \pi^{\mu\nu} D_\alpha u^\alpha \quad (\text{standard notations})$$

→ 4 transport coefficients  $\zeta$ ,  $\eta$ ,  $\tau_\Pi$ ,  $\tau_\pi$ , which depend on T.

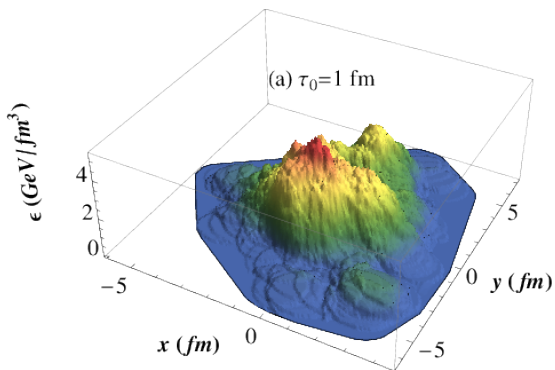
$\pi_{\text{Navier-Stokes}}^{\mu\nu} = \eta \sigma^{\mu\nu}$ : prevents deformations of fluid cell.

$\Pi_{\text{Navier-Stokes}} = -\zeta D_\mu u^\mu$ : negative pressure, slowing expansion

# Effect of viscosity on fluid evolution

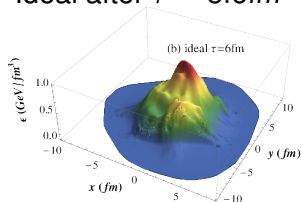
## Initial Conditions:

- MC-Glauber: energy density =  $cn_{coll}(\vec{r})$  ( $c$  adjusted to get midrapidity multiplicity)
- $\tau_0 = 1 \text{ fm}$  (tested)

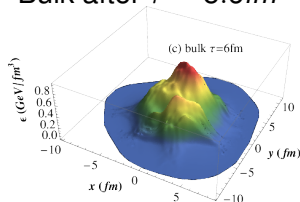


# Effect of viscosity on fluid evolution

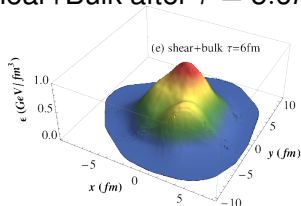
Ideal after  $\tau = 5.6 fm$



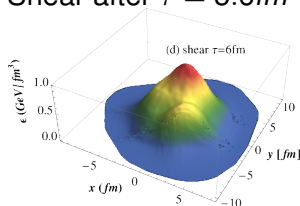
Bulk after  $\tau = 5.6 fm$



Shear+Bulk after  $\tau = 5.6 fm$



Shear after  $\tau = 5.6 fm$



- Viscosity attenuates other forces  $\rightarrow$  smearing of granularity.
- Shear dominates, bulk barely affects expansion ( $\zeta/s \ll \eta/s$ )

# Effect of viscosity on particle emission

Compute observables with Cooper-Frye formula:

Particle spectra:  $E \frac{d^3N}{dp^3} = \int_{f.o.} f(x, p) p^\mu d\sigma_\mu$

$$f = f_{eq} + \delta f_{shear} + \delta f_{bulk}$$

$\delta f_{shear}$

Common ansatz:  $\delta f_{shear} \sim \pi_{\mu\nu} p^\mu p^\nu / [(\epsilon + p) T^2]$ .

Navier-Stokes limit,  $\delta f_{shear} \propto (\eta/s) p^2$

→ stronger effect for larger  $\eta/s$  and  $p$ .

$\delta f_{bulk}$

Using method of moments as in Denicol, Niemi NPA904-905 (2013) 369c

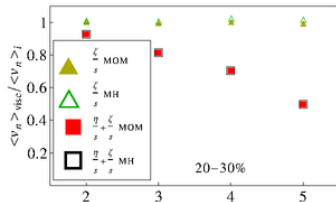
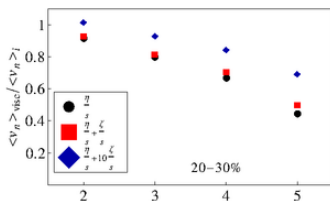
$$\delta f_{bulk}^{(\pi)} = f_{eq} \times \Pi \times [B_0^{(\pi)} + D_0^{(\pi)} u \cdot p + E_0^{(\pi)} (u \cdot p)^2]$$

where

$$B_0^{(\pi)} = -65.85 \text{ fm}^4, D_0^{(\pi)} = 171, 27 \text{ fm}^4 / \text{GeV}, E_0^{(\pi)} = -63.05 \text{ fm}^4 / \text{GeV}^2$$

# Effect of viscosity on particle emission

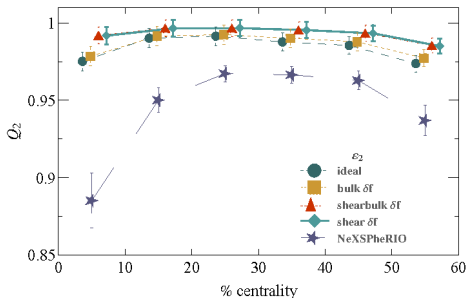
## Integrated $V_n$ 's



- sensitive to value of viscosities
- not to choice of  $\delta f_{bulk}$  (though the  $V_n(p_T)$ 's are).

## $v_2$ from $\varepsilon_2$

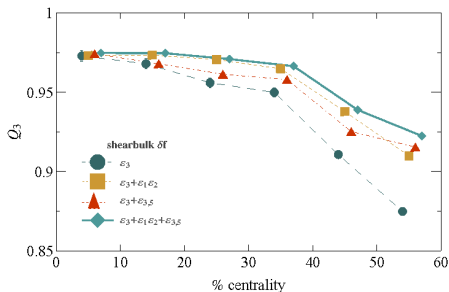
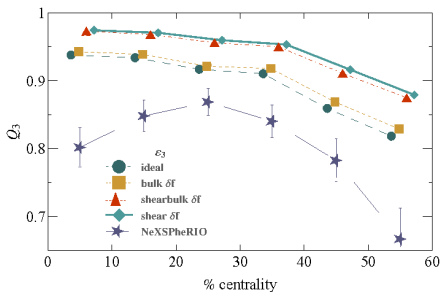
$$V_2 \sim V_{est,2} = k_{2,2} W_{2,2} + O(W^3) \sim k \varepsilon_2 e^{i2\Phi_2} \text{ if } m_{max} = 2.$$



- $Q_2 \sim 1$ :  $v_2 \propto \varepsilon_2$  and  $\Psi_2 \sim \Phi_2$
- Shear viscosity improves the estimator
- NeXSPheRIO “~ worst-case scenario”: ideal + initial transverse flow and rapidity-dependent fluctuations (not treated in this approach).

## $v_3$ from $\varepsilon_3$

$$V_{est,3} = k_{3,3} W_{3,3} + k_{3,5} W_{3,5} + K_{132} W_{1,3} W_{2,2} + O(W^2).$$

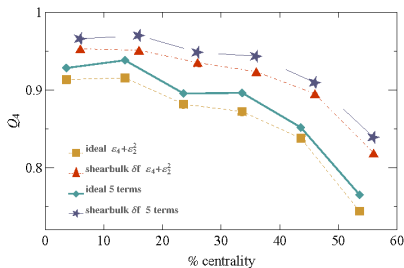
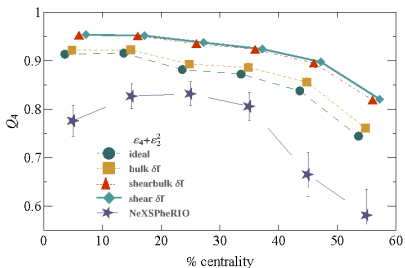


- $\varepsilon_3$  and  $v_3$  are strong correlated
- Shear viscosity improves estimator
- $\varepsilon_1 \varepsilon_2$  and  $\varepsilon_{3,5}$  help for peripheral collisions
- NeXSPheRIO again below.

Obs.: To get unscaled cumulants, we should use  $W_{0,2}^{3/2}$  but it makes little difference to use  $\{r^3\}$  and revert to eccentricities.

# $v_4$ from $\epsilon_4$ , $\epsilon_2^2$ and $\Phi_2 - \Phi_4$

$V_{est,4} = k_{4,4} W_{4,4} + K_{2,2,2} W_{2,2} W_{2,2} + O(W^2)$ : both terms important



- Well predicted with two terms (better if there is viscosity).

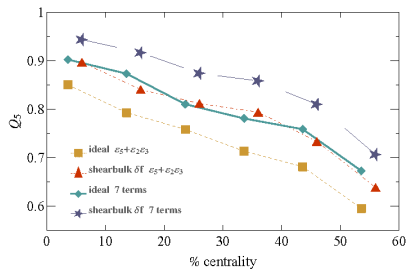
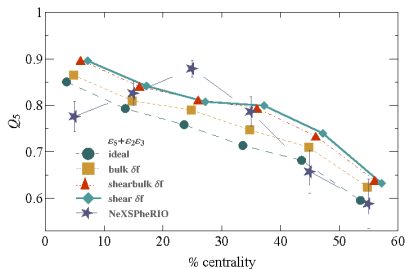
- $v_4^2 = |V_4|^2 = k^2 \epsilon_4^2 + k'^2 \epsilon_2^4 + 2kk' \epsilon_4 \epsilon_2^2 \cos 4(\Phi_2 - \Phi_4)$

- Small improvement with more terms (5):

$$V_{est,4} = k_{4,4} W_{4,4} + K_{2,2,2} W_{2,2} W_{2,2} + K_{2,4,2} W_{2,4} W_{2,2} + K_{2,4,4} W_{2,4} W_{2,4} + K_{1,3,3} W_{1,3} W_{3,3} + O(W^2)$$

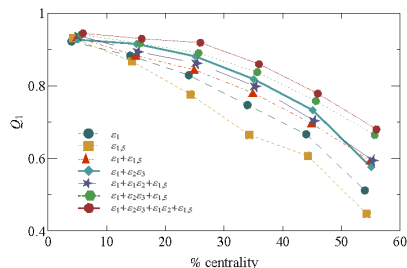
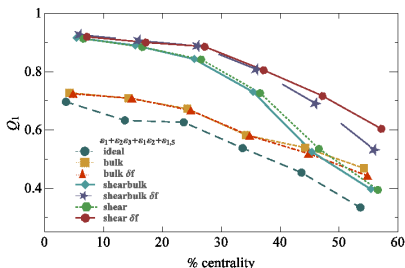


# $v_5$ from $\varepsilon_5$ , $\varepsilon_2\varepsilon_3$ and $\Phi_5 - (2\Phi_2 + 3\phi_3)$



- Two terms OK for central collisions, not peripheral.
- Improvement with more terms (7)

$$\varepsilon_5 + \varepsilon_3\varepsilon_2 + \varepsilon_{3,5}\varepsilon_2 + \varepsilon_{3\varepsilon_2,4} + \varepsilon_{3,5\varepsilon_2,4} + \varepsilon_{1\varepsilon_4} + \varepsilon_{1,5\varepsilon_4}$$

$v_1$ 

- $v_1$  predicted by  $\varepsilon_1$  for central collisions.
- Both higher order terms (sensitive to smaller scale) and non-linear terms necessary for non-central collisions.
- Large effect of viscosities.
- $v_1(p_T)$  changes sign. Smaller  $p_T$  range improves estimator

# Conclusion

- $\eta/s$  and  $\zeta/s$  improve the mapping of the initial state onto the final flow harmonics.  
Correlation between  $v_n$  and  $\epsilon_n$  larger than for ideal hydro.
- NeXSPheRIO results generally below v-USPhydro.  
Central collisions more sensitive to this.  
(NeXSPheRIO has non-zero initial transverse flow and rapidity-dependant fluctuations.)
- More higher order eccentricities and non-linear terms are necessary for peripheral collisions (**what about pA?**)