Here I present some summary tables for various discrete variable representation (DVR) bases using the following notations and terminology (mostly following [1] with the exception that we use  $w_n \equiv 1/K_n$  for the integration weights).

$$
k_c : (momentum cutoff (UV))
$$
  
\n
$$
x_n : z_n \equiv k_c x_n
$$
 (abscissa and dimensionless abscissa)  
\n
$$
P : P = P^{\dagger} = P^2 = \sum_{|\kappa| < k_c} |k\rangle \langle k|
$$
 (projector)  
\n
$$
|x_n\rangle : \langle x|x_n\rangle = \delta(x - x_n)
$$
 (delta-function)  
\n
$$
|\Delta_n\rangle : |\Delta_n\rangle = P|x_n\rangle
$$
 (projected delta-function)  
\n
$$
w_n : w_n = 1/\langle \Delta_n | \Delta_n \rangle = 1/\Delta_n(x_n)
$$
 (quadrature weights)  
\n
$$
|L_n\rangle : |f\rangle = \sum_n f(x_n) |L_n\rangle, \langle L_m | \Delta_n \rangle = \delta_{mn}
$$
 (interpolating functions)  
\n
$$
|F_n\rangle : \langle F_m | F_n \rangle = \delta_{mn}
$$
 (orthonormal basis functions)

The conventional DVR bases satisfy  $|L_n\rangle = \sqrt{w_n} |F_n\rangle = w_n |\Delta_n\rangle$ : i.e. the projected delta-functions form an orthogonal basis:

$$
\langle \Delta_{m} | \Delta_{n} \rangle = \Delta_{m}(x_{n}) = w_{n}^{-1} \delta_{mn}.
$$
 (1)

In other words, the basis functions  $F_n(x)$  have nodes at all abscissa  $x = x_{m+n}$ . This is a non-trivial requirement and generally requires these bases to be built from orthogonal polynomials. The key to the utility of these DVR bases is that they are quasi-local: to express a function  $f(x)$  in the basis, one simply evaluates it at the abscissa. Likewise, the potential energy matrix can be approximated by a diagonal matrix. Coupled with the kinetic operator, this can yield exponential accuracy for the eigenvalues and eigenfunctions (for appropriate potentials and boundary conditions)

$$
|f\rangle = \sum_{n} f_n |F_n\rangle, \quad f_n = f(x_n)\sqrt{w_n}
$$
 (quasi-locality)  

$$
K_{mn} = \langle F_n | \widehat{\mathbf{K}} | F_m \rangle
$$
 (kinetic energy)  

$$
V_{mn} = \langle F_n | \widehat{\mathbf{V}} | F_m \rangle \approx \delta_{mn} V(x_n)
$$
 (potential energy)

## SELECTED REFERENCES

- [1] R. G. Littlejohn, M. Cargo, T. Carrington, Jr., K. A. Mitchell, and B. Poirier, J. Chem. Phys. **116**, 8691 (2002).
- [2] D. Baye, J. Phys. B **28**, 4399 (1995).
- [3] D. Baye, physica status solidi (b) **243**, 1095 (2006).
- [4] R. G. Littlejohn and M. Cargo, J. Chem. Phys. **117**, 27 (2002).
- [5] D. Baye and P.-H. Heenen, J. Phys. A **19**, 2041 (1986).
- [6] D. Baye, M. Hesse, and M. Vincke, Phys. Rev. E **65**, 026701 (2002).
- [7] H. Karabulut and E. L. Sibert III, J. Phys. B **30**, L513 (1997).
- [8] R. G. Littlejohn and M. Cargo, J. Chem. Phys. **116**, 7350 (2002).

Fourier Basis The simple Fourier basis over an interval of length  $L = Na$  is just a quasi-local rearrangement of the usual Fourier basis  $e^{ik_nx}$  with wave-vectors  $k_n = 2\pi n/L$  in terms of the "periodic sinc functions"  $psinc(z)$  (see [2]):

$$
p\text{sinc}(z) = \frac{\sin z}{N \sin \frac{z}{N}} = \frac{1}{N} \sum_{m=-(N-1)/2}^{(N-1)/2} e^{imz}, \tag{2a}
$$

$$
x_n = x_0 + \alpha n \Big|_{n = -(N-1)/2}^{(N-1)/2}, \quad k_c = \pi/a, \quad w_n = \pi/k_c = a,
$$
 (2b)

$$
L_n(x) = \text{psinc}\Big(k_c(x - x_n)\Big),\tag{2c}
$$

$$
K_{m \neq n} = \frac{2\pi^2 (-1)^{m-n}}{L^2} \frac{\cos \frac{k_c (x_m - x_n)}{N}}{\sin^2 \frac{k_c (x_m - x_n)}{N}}, \quad K_{n n} = \frac{\pi^2}{3a^2} \left(1 - \frac{1}{N^2}\right). \tag{2d}
$$

SINC FUNCTION BASIS For N abscissa, one can represent functions over an interval of length aN (non-periodic) with  $sinc(x) \equiv sin(x)/x$ functions. This follows from the Fourier basis in the limit  $N \rightarrow \infty$ (see [2]):

$$
x_n = x_0 + an, \quad k_c = \pi/a, \quad w_n = \pi/k_c = a,
$$
 (3a)

$$
L_n(x) = sinc(k_c(x - x_n)),
$$
 (3b)

$$
K_{m \neq n} = \frac{2(-1)^{m-n}}{(x_m - x_n)^2}, \quad K_{nn} = \frac{\pi^2}{3a^2}.
$$
 (3c)

Bessel Function Basis For central problems one expands the radial wavefunction  $u(r) = r^{(d-1)/2} \psi(r)$  for each angular momentum  $v = 1 + d/2 - 1$ . In practice, one can often use just a few basis: in d = 3 for example, one can use the  $l = 0$  basis for all even l and the  $l = 1$  basis for all odd l. The abscissa and basis functions are defined in terms of the Bessel functions  $J_{\nu}(z)$  (see [4]):

$$
\frac{d^2u(r)}{dr^2} - \frac{v^2 - 1/4}{r^2}u(r) + \frac{2m}{\hbar^2} [E - V(r)]u(r) = 0
$$
 (4a)

$$
J_{\nu}(z_{\nu n}) = 0
$$
,  $w_n = \frac{2}{k_c z_{\nu n} J_{\nu}'(z_{\nu n})^2}$ , (4b)

$$
F_n(r) = (-1)^{n+1} \frac{k_c z_{\nu n} \sqrt{2r}}{k_c^2 r^2 - z_{\nu n}^2} J_\nu(k_c r),
$$
 (4c)

$$
K_{m \neq n} = \frac{8k_c^2(-1)^{m-n}z_{\nu n}z_{\nu m}}{(z_{\nu n}^2 - z_{\nu m}^2)^2}, \quad K_{n n} = \frac{k_c^2}{3} \left[ 1 + \frac{2(\nu^2 - 1)}{z_{\nu n}^2} \right] \tag{4d}
$$