



*Neutrino-Driven Convection and
Neutrino-Driven Explosions*

by
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1D simulations (Rad-hydro)

Wilson '85

Bethe & Wilson '85

Liebendoerfer et al. '01

Rampp & Janka '02

Buras et al. '03

Thompson et al. '03

Liebendoer et al. '05

Kitaura et al. '06

Burrows et al. '07



Neutrino mechanism suggested



No Explosions

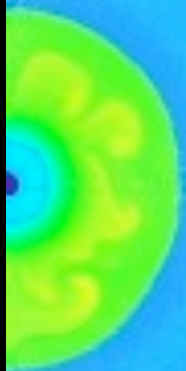
(Except lowest masses)

Spherical symmetry!

No GW emission?

Fundamental Question of Core-Collapse Theory

Steady-State
Accretion

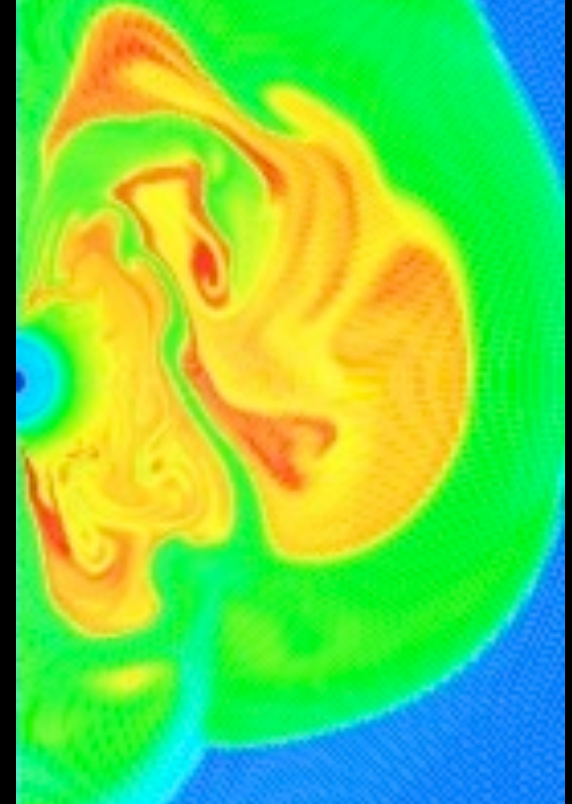


t=0.280 s

?



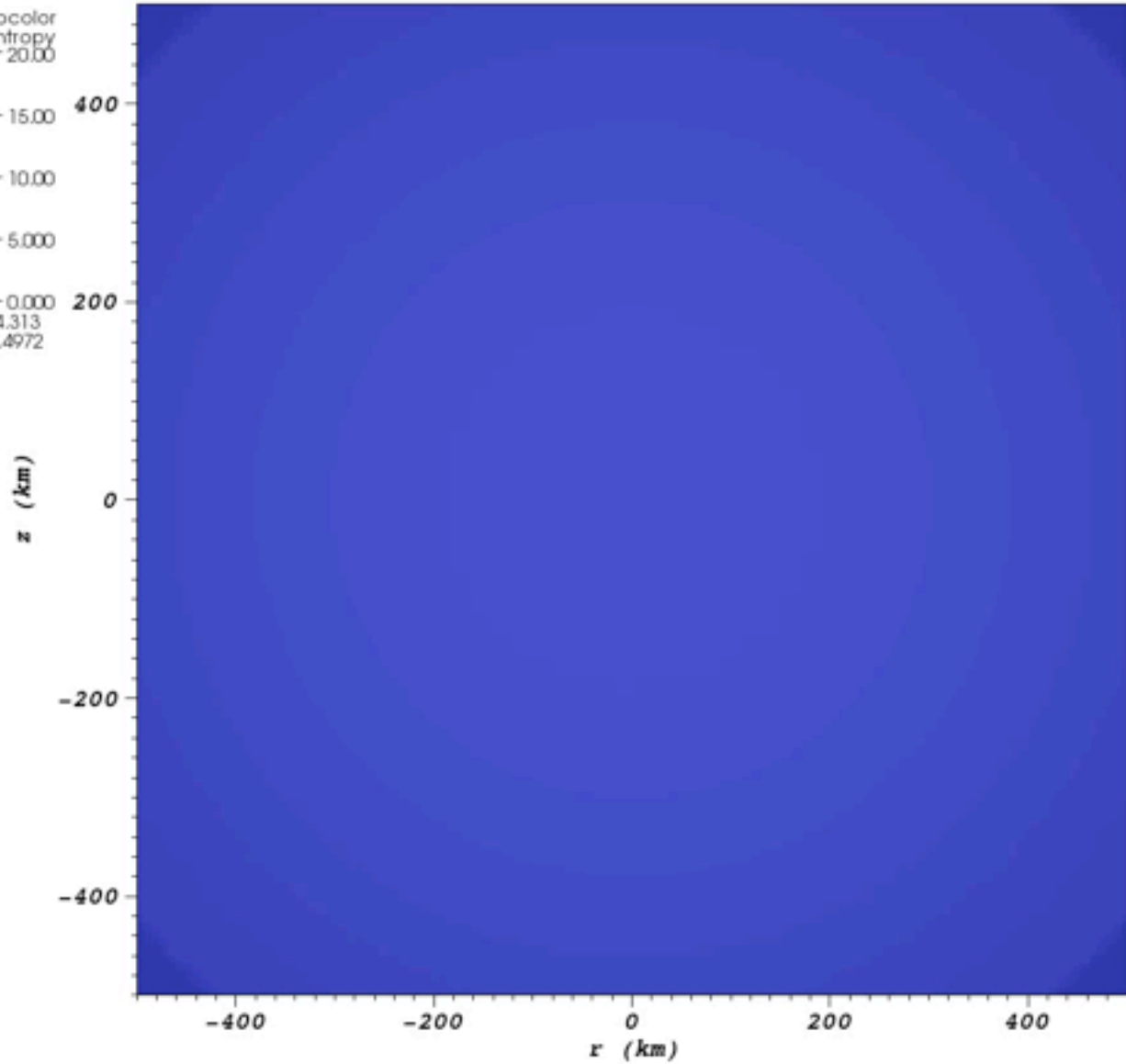
Explosion



t=0.750 s

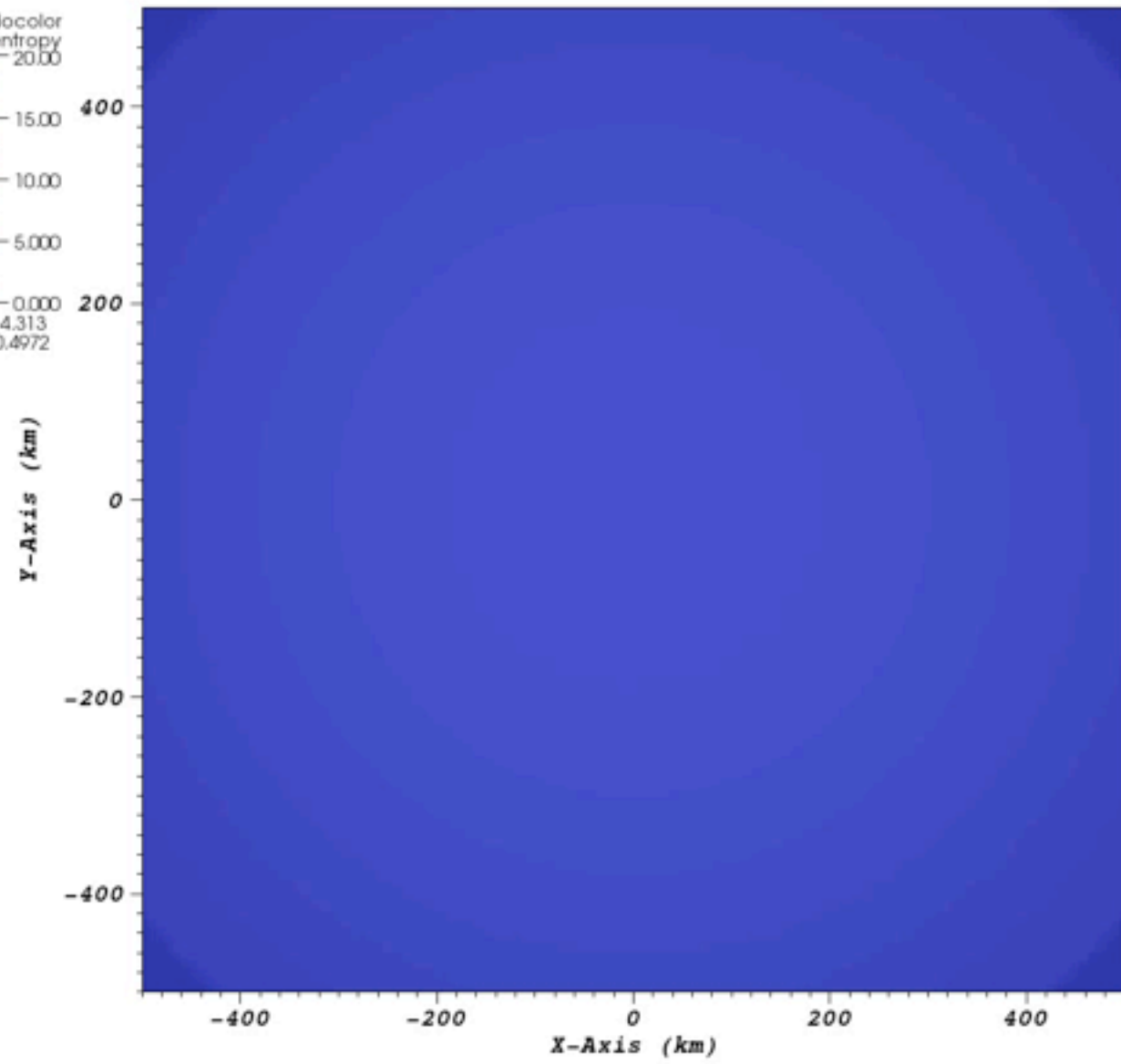
Relax 1D assumption?

Pseudocolor
Var: entropy
20.00
15.00
10.00
5.000
0.000
Max: 4.313
Min: 0.4972



Time = -0.2600 s after bounce

Pseudocolor
Var: entropy
20.00
15.00
10.00
5.000
0.000
Max: 4.313
Min: 0.4972



Time = -0.2600 s after bounce

Neutrino Mechanism:

- Neutrino-heated convection
- Standing Accretion Shock Instability (SASI)
- Explosions? Maybe

Acoustic Mechanism:

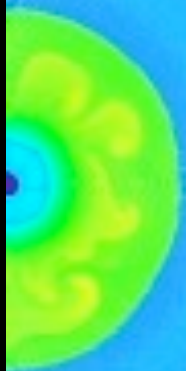
- Explosions but caveats.

Magnetic Jets:

- Only for very rapid rotations
- Collapsar?

Fundamental Question of Core-Collapse Theory

Steady-State
Accretion

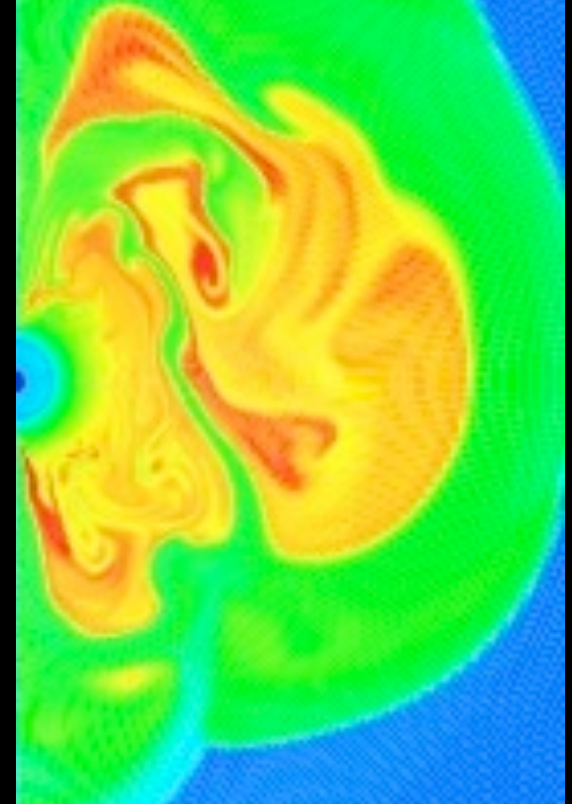


t=0.280 s

?



Explosion



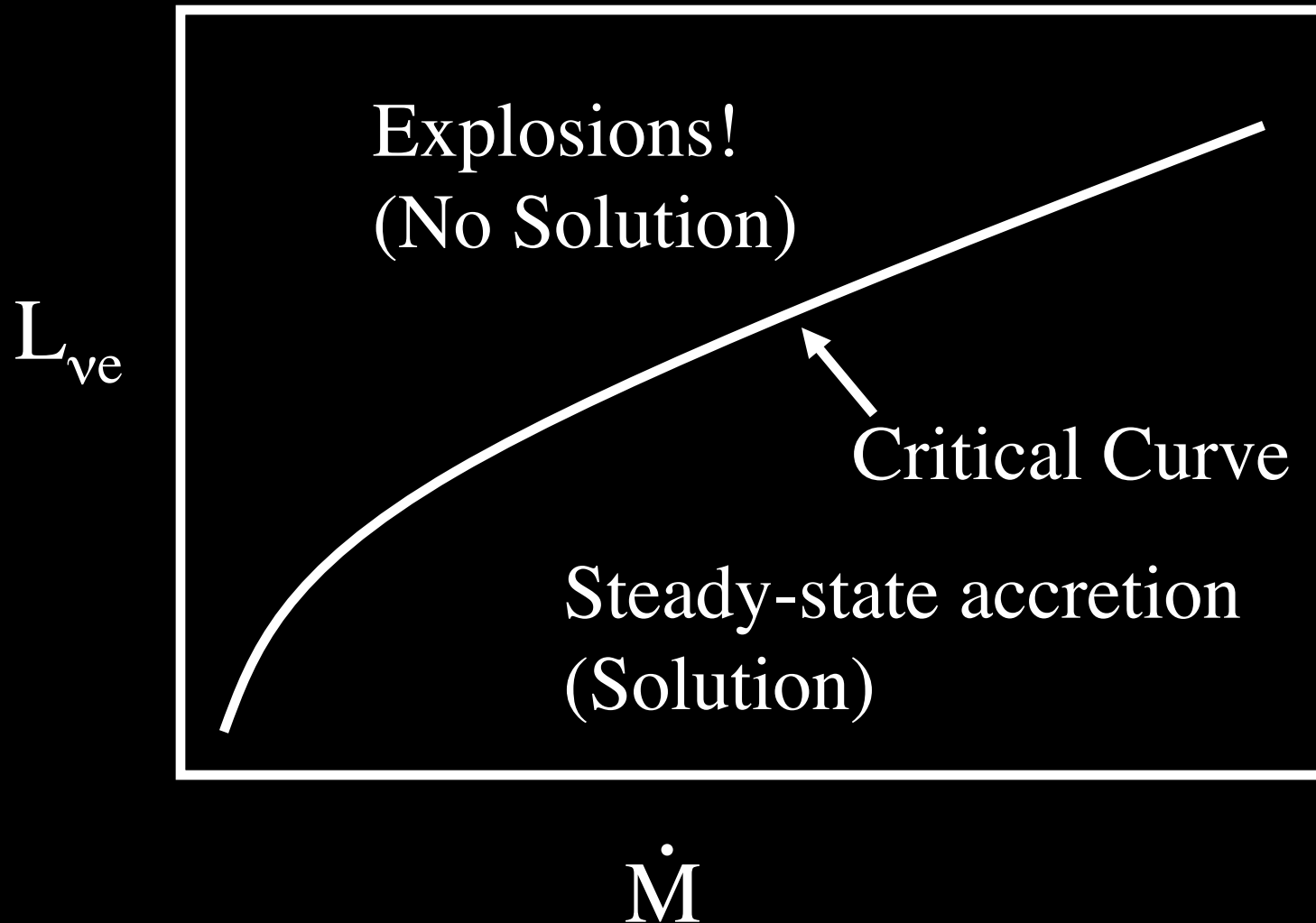
t=0.750 s

*Why is it easier to explode in 2D
compared to 1D?*

Two Paths to the Solution

- Detailed 3D radiation-hydrodynamic simulations (“Accurate” energies, NS masses, nucleo., etc.)
- Parameterizations that capture essential physics (Tease out fundamental mechanisms)

Burrows & Goshy '93
Steady-state solution (ODE)



Explosion is a global, boundary-value problem

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In other words:

What neutrino forcing is required to change the global structure between the NS and shock such that explosions occur?

Explosion is a global, boundary-value problem

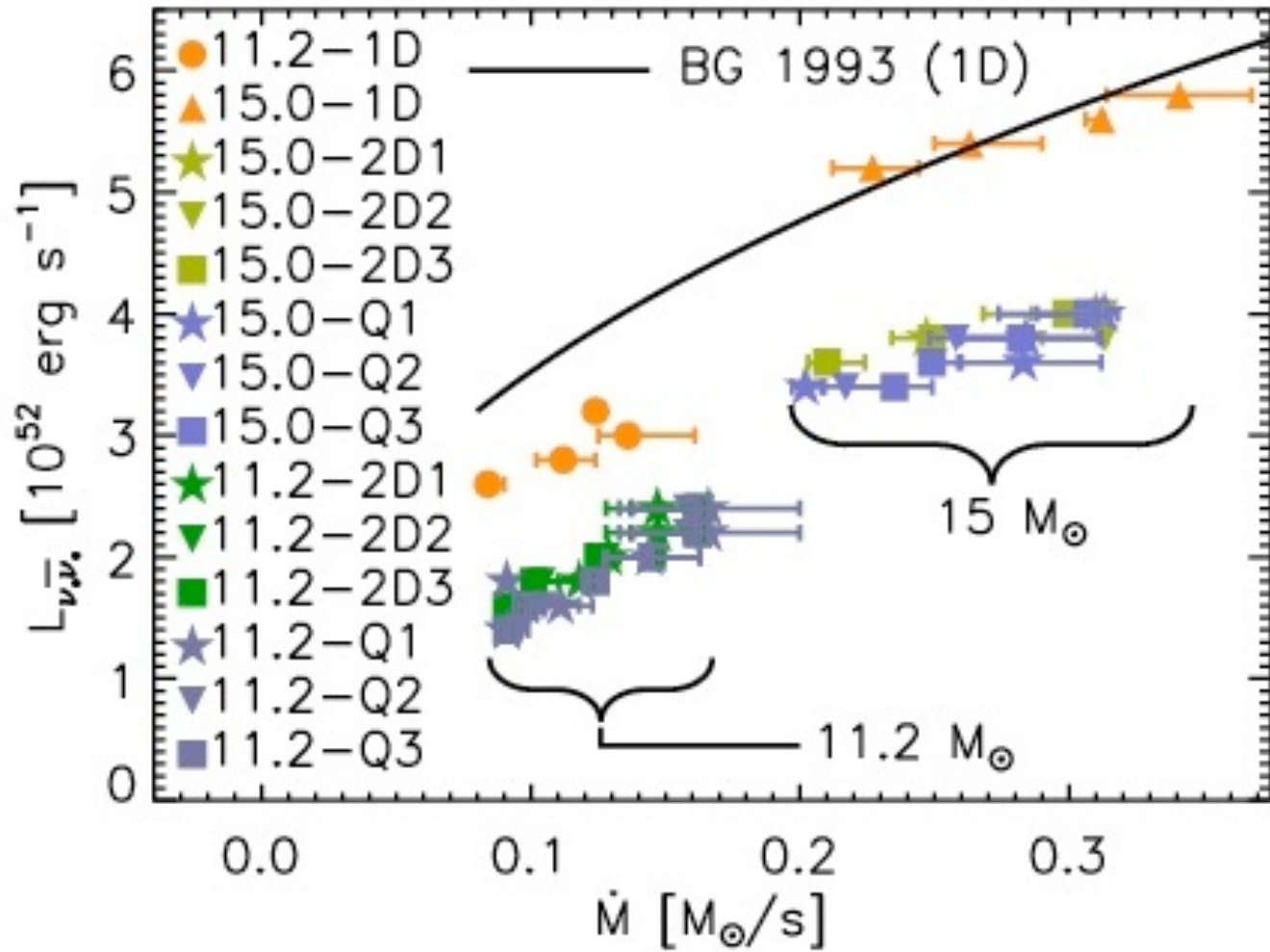
This also means that one can't easily and cleanly pick out one simple diagnostic

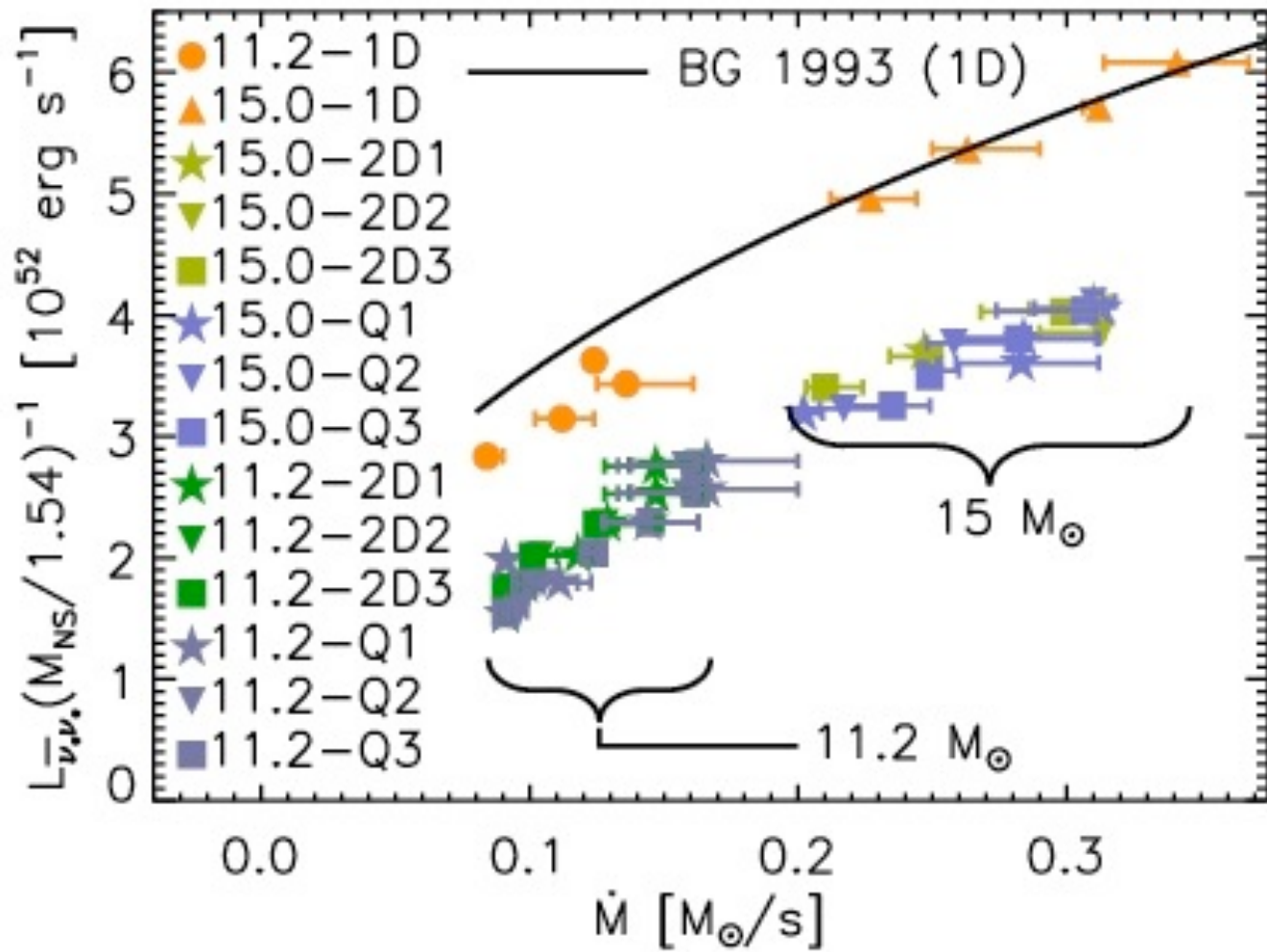
Hence... "Mazurek's Law"

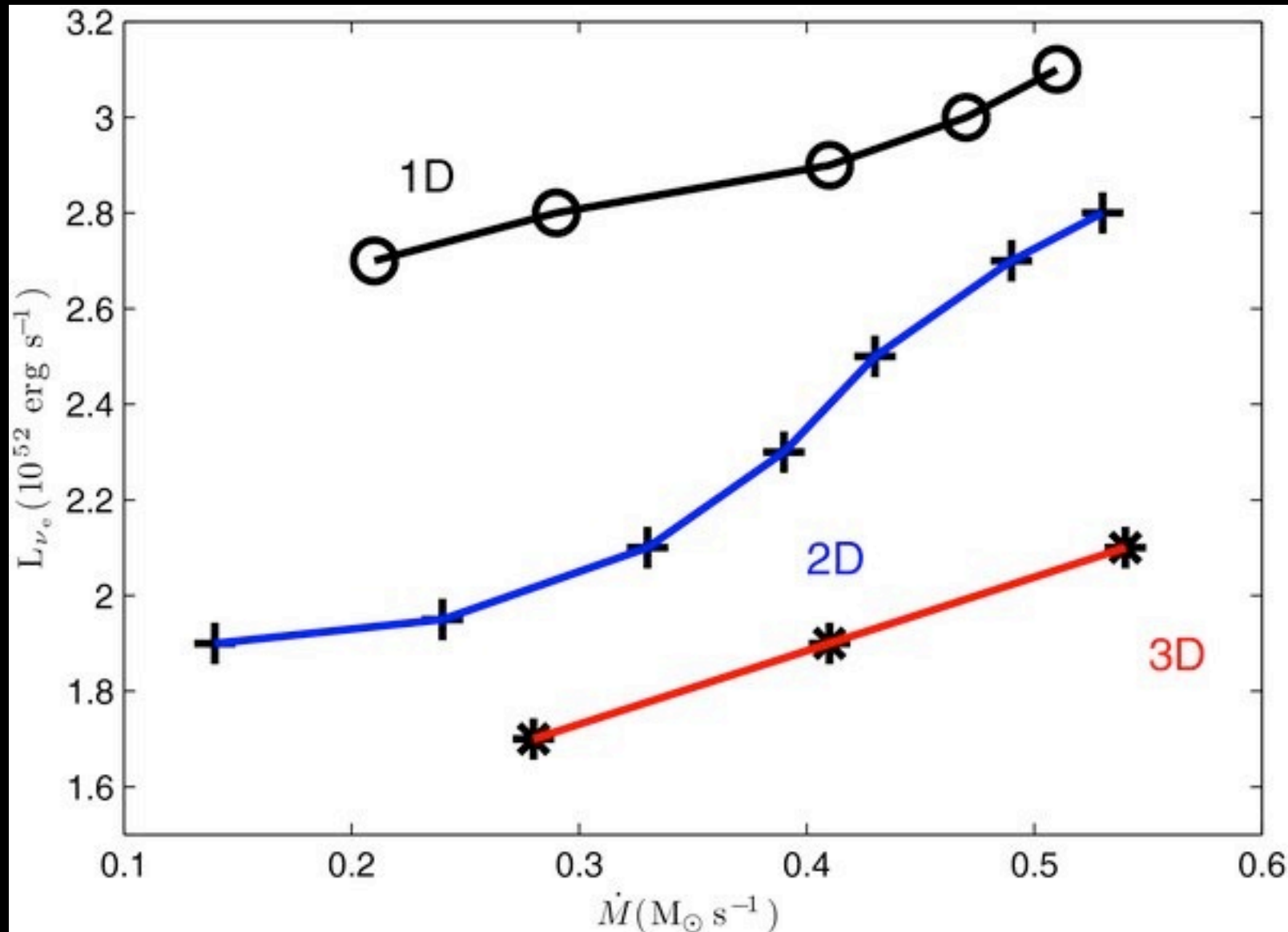
Is a critical luminosity relevant in hydrodynamic simulations?

- 1D
- 2D Convection and SASI?

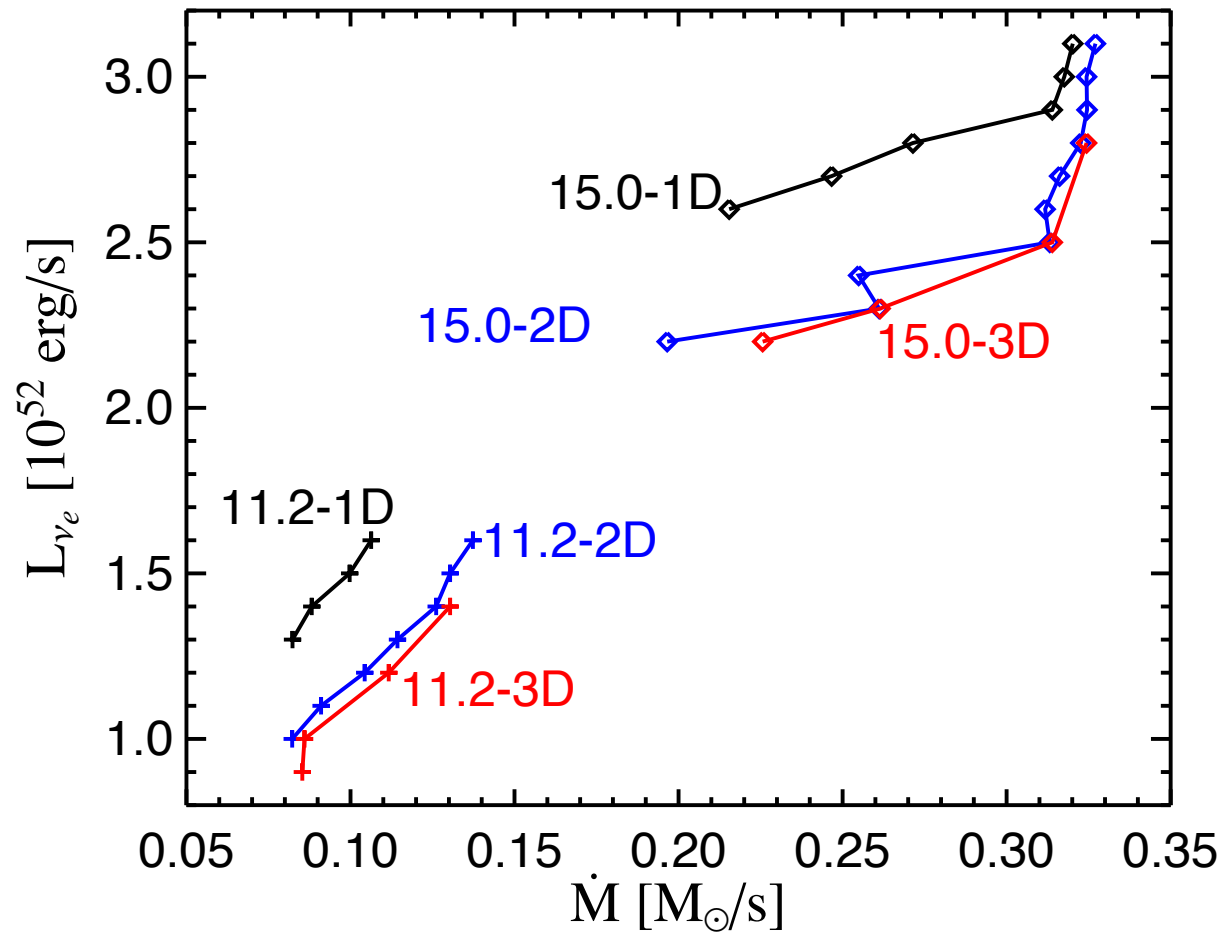
How do the critical luminosities
differ between 1D and 2D?

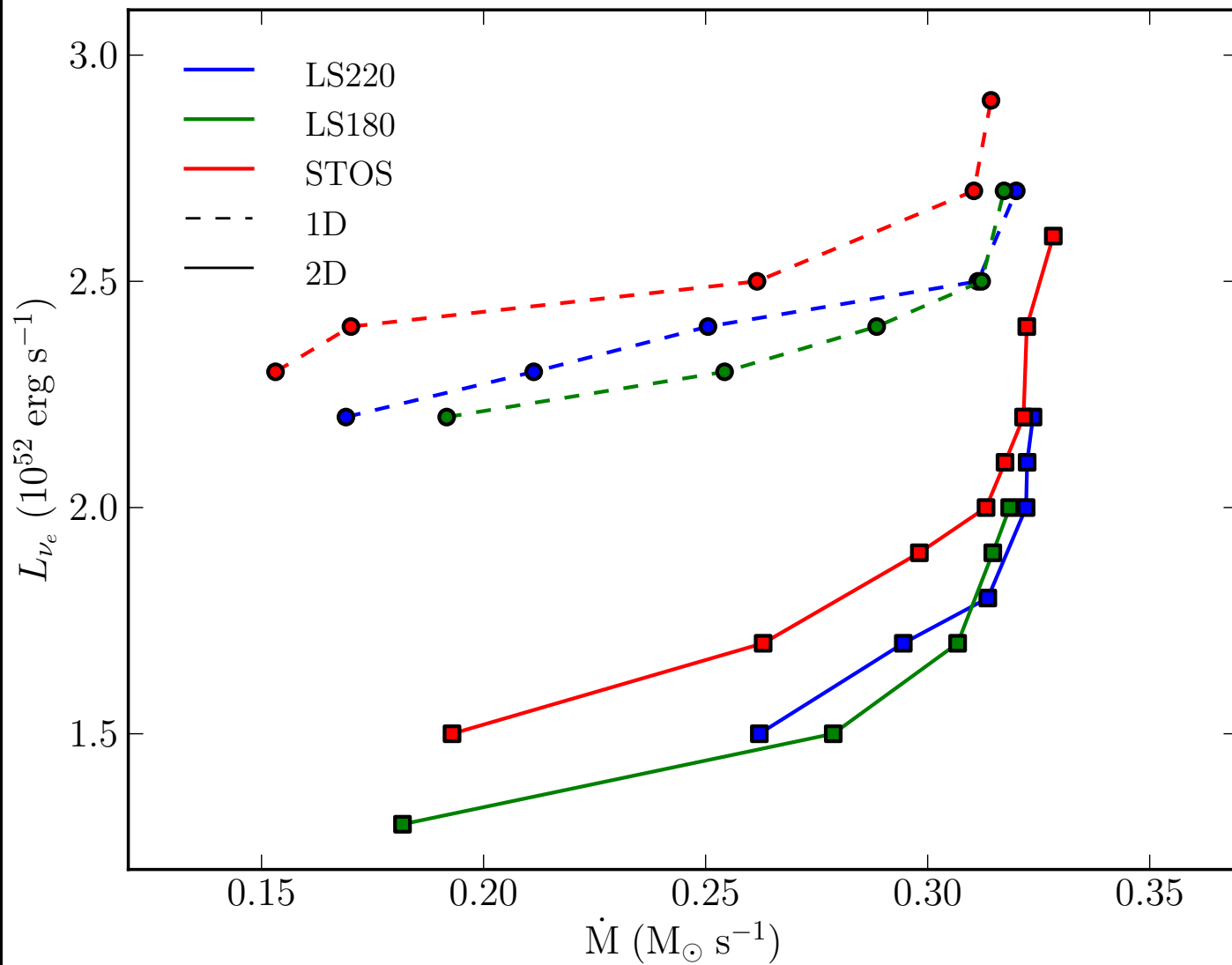






Nordhaus et al. 2010

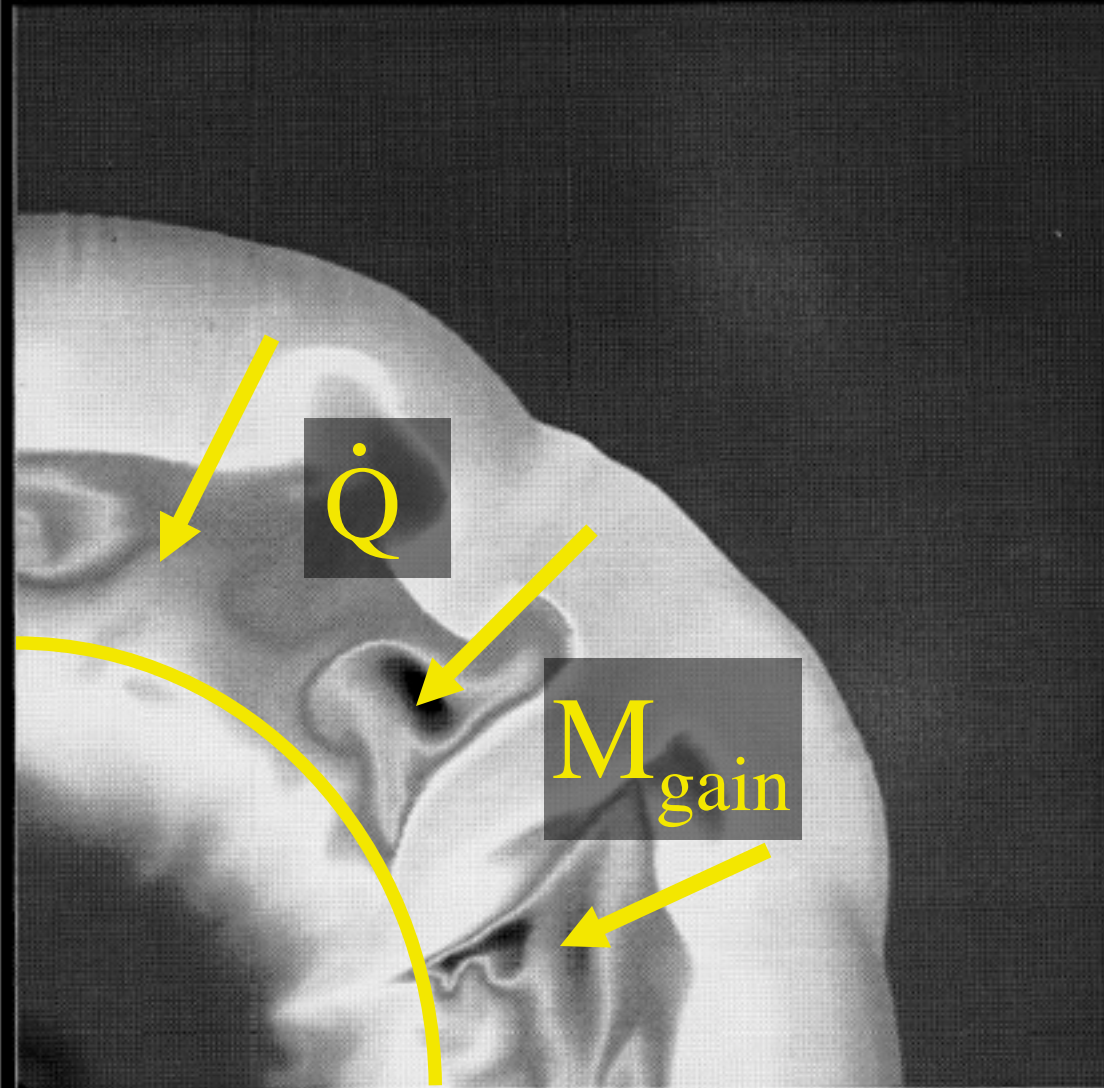




Why is critical luminosity of
multi-D simulations $\sim 70\%$ of 1D?

Comparison of Timescales

(Thompson et al. '00, Janka '01, Thompson et al. '03, Murphy et al. '08, Pejcha '11, Fernandez '12)



$$\tau_{\text{adv}} = \frac{\Delta r_{\text{gain}}}{v_r}$$

$$\tau_q = \frac{E}{\dot{Q}}$$

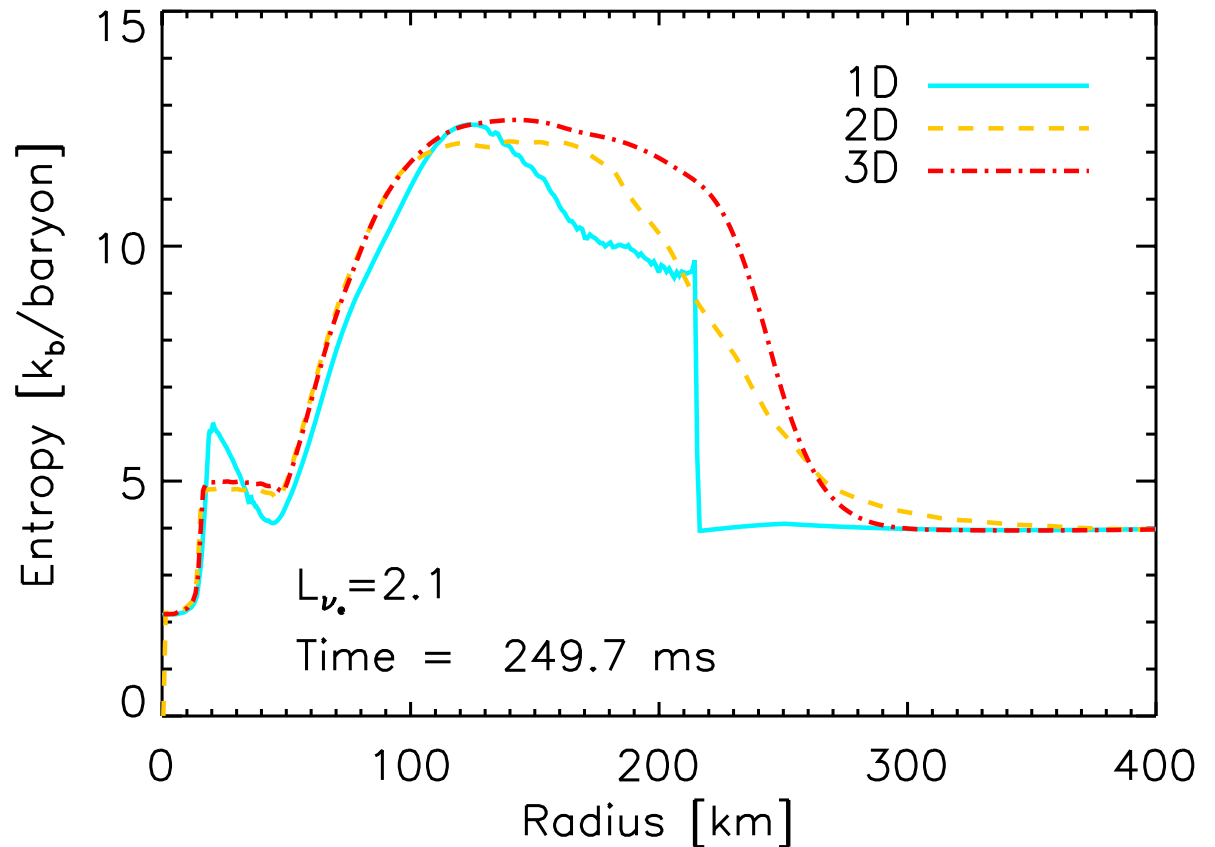
$$\frac{\tau_{\text{adv}}}{\tau_q} \gg 1$$

1D \rightarrow one time

mult-D \rightarrow distribution of times

More heating?

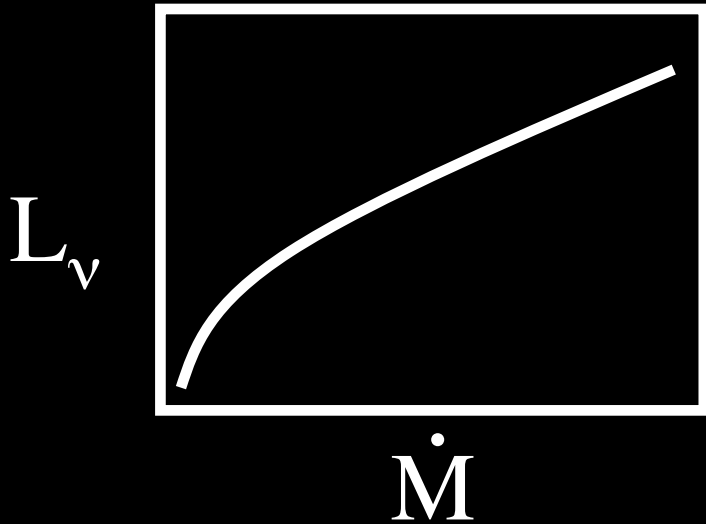
$$\Delta S \propto \frac{\dot{Q}}{T}$$



2D & 3D critical luminosity
lower than 1D

Turbulence plays an important
role!

A Theoretical Framework for Successful Explosions

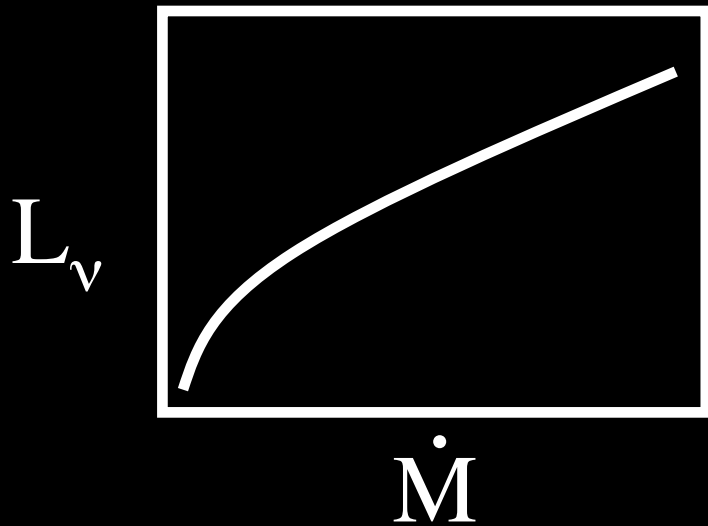


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Turbulence
Model

Murphy & Meakin 2011

A Theoretical Framework for Successful Explosions



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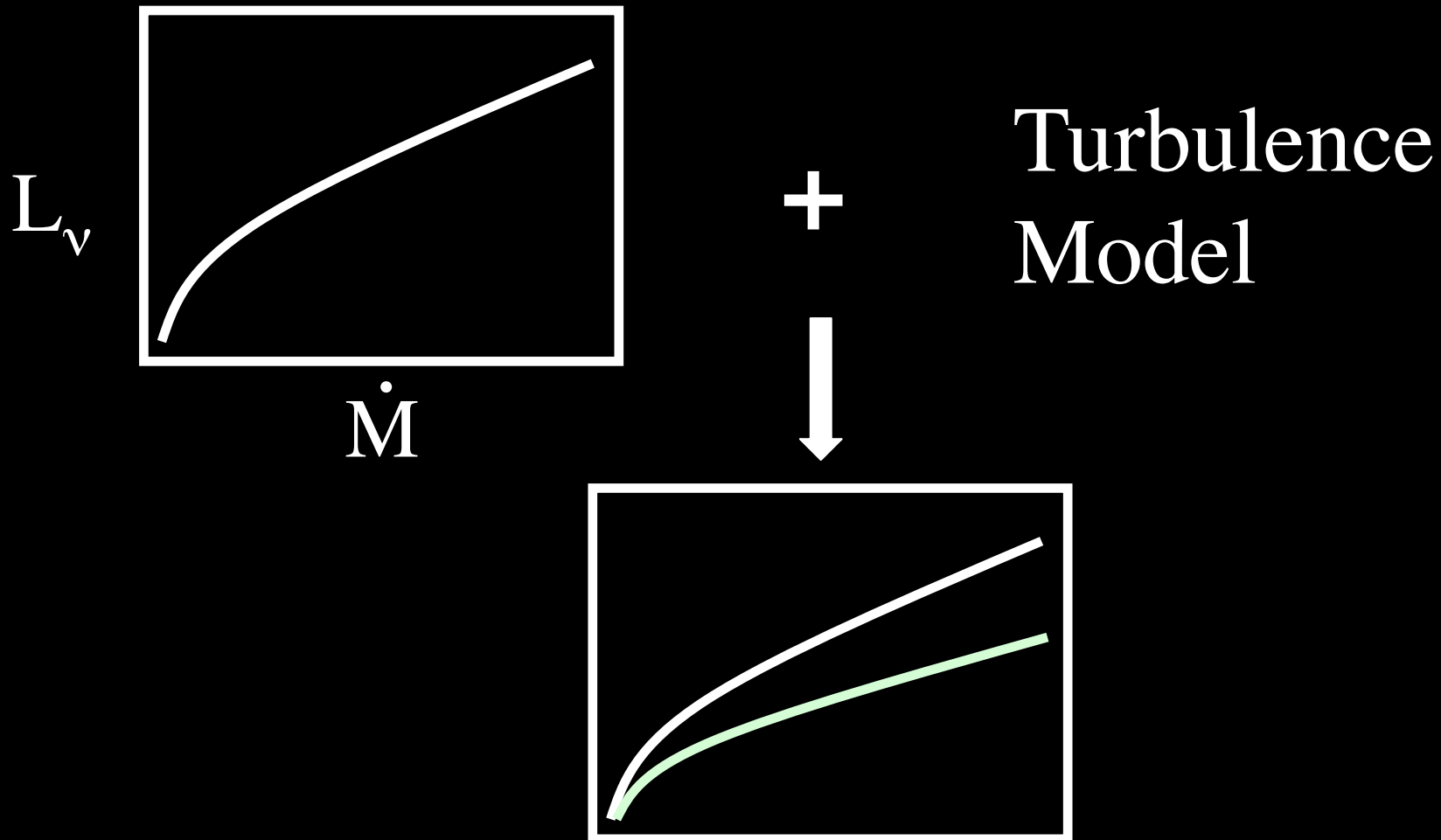
Turbulence
Model



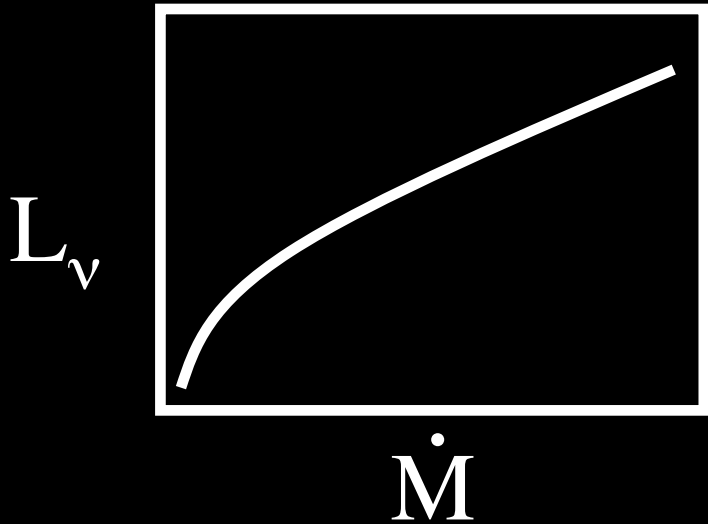
Calibrate with 3D
Simulations

Murphy et al. 2012, in prep

A Theoretical Framework for Successful Explosions



A Theoretical Framework for Successful Explosions



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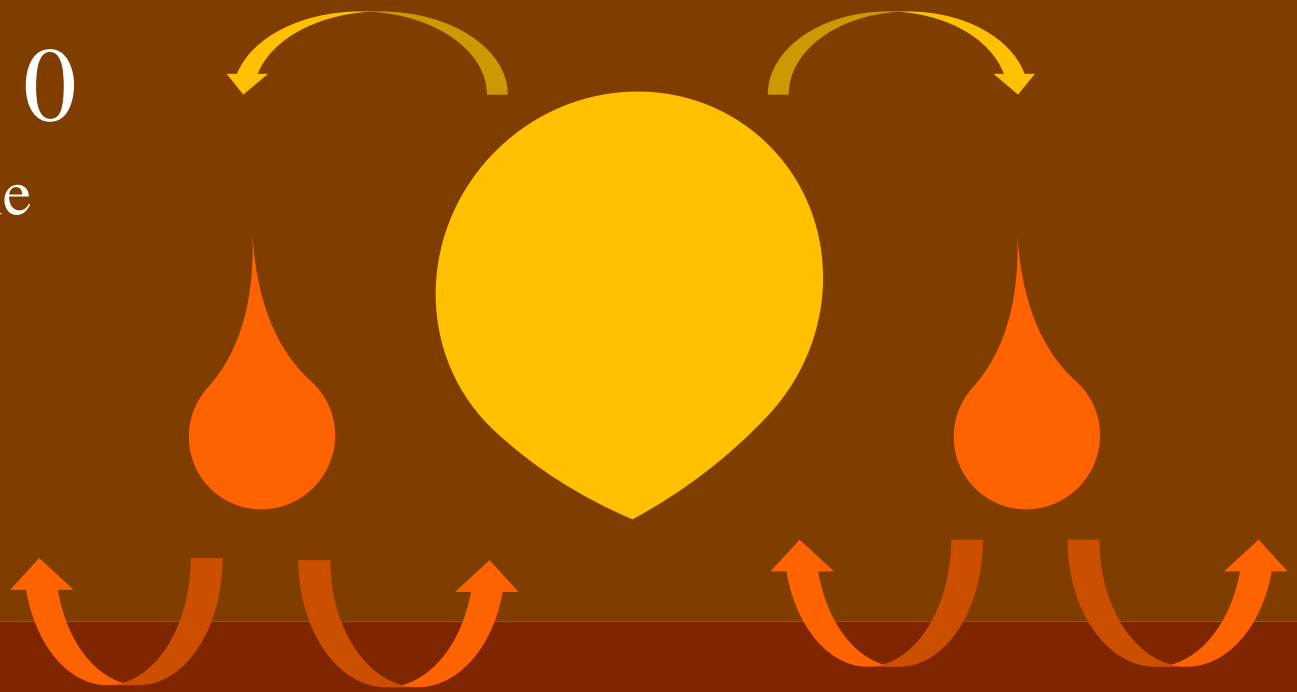
Turbulence
Model



1D Rad-hydro simulations
Realistic and quantitative explosions
Systematic exploration

$N^2 < 0, \nabla s < 0$

Convectively unstable

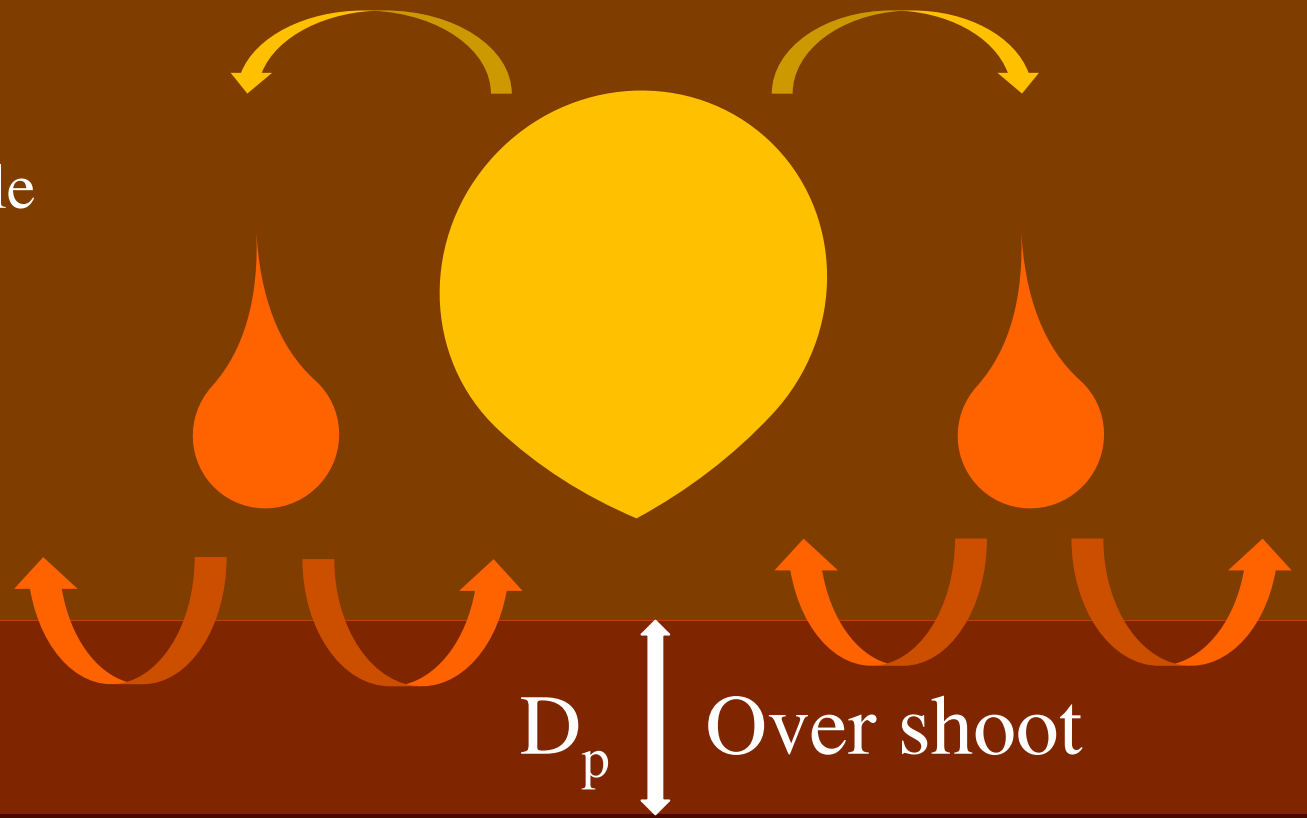


$N^2 > 0$

$N^2 > 0$
Stably stratified
(gravity waves)

$$N^2 < 0$$

Convectively unstable



$$N^2 > 0$$

$$N^2 > 0$$

Stably stratified
(gravity waves)

$$b(r) = \int N^2 dr = \text{buoyant accel.}$$

$$N^2 < 0$$

Convectively unstable

$$F = F_{\text{rad}} + F_{\text{conv}}$$

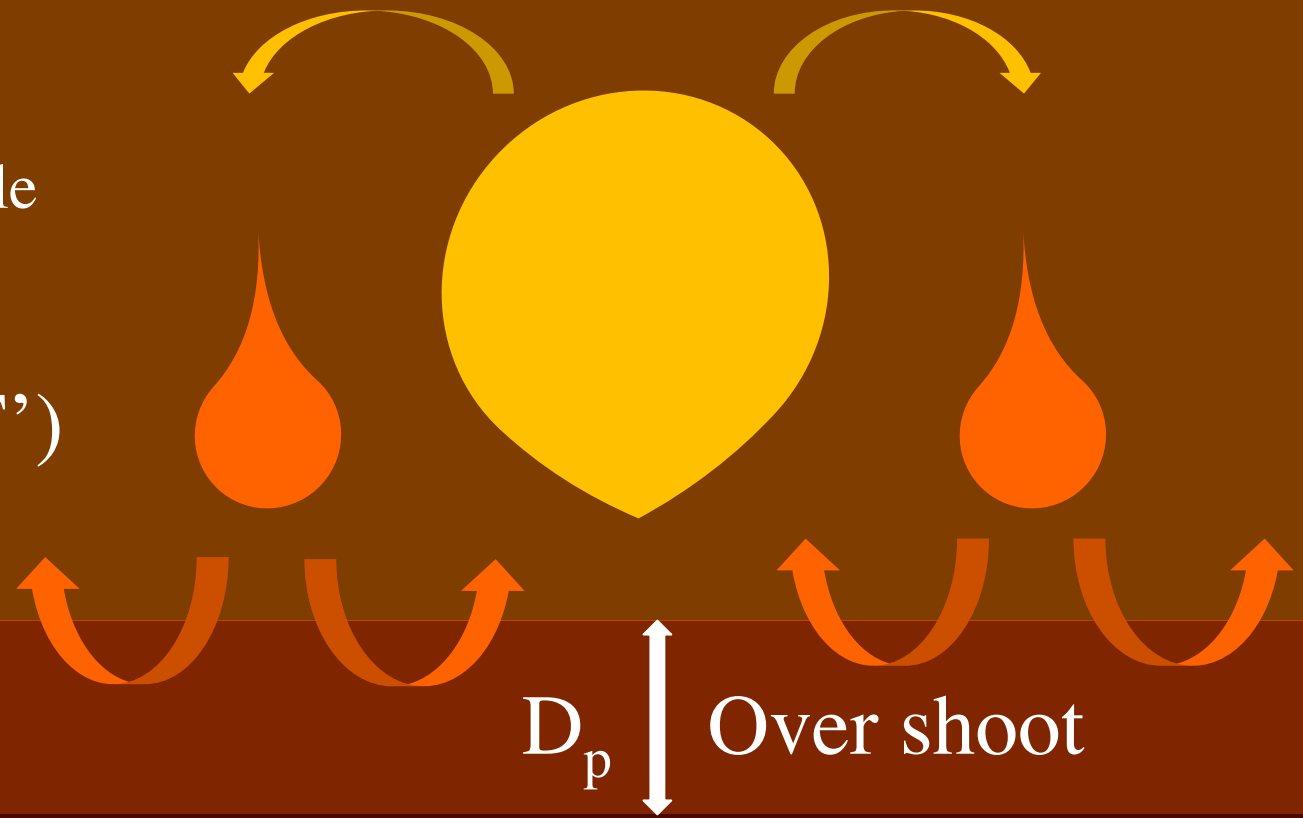
$$F_{\text{conv}} = C_p \rho (v' T')$$

$$N^2 > 0$$

$$N^2 > 0$$

Stably stratified
(gravity waves)

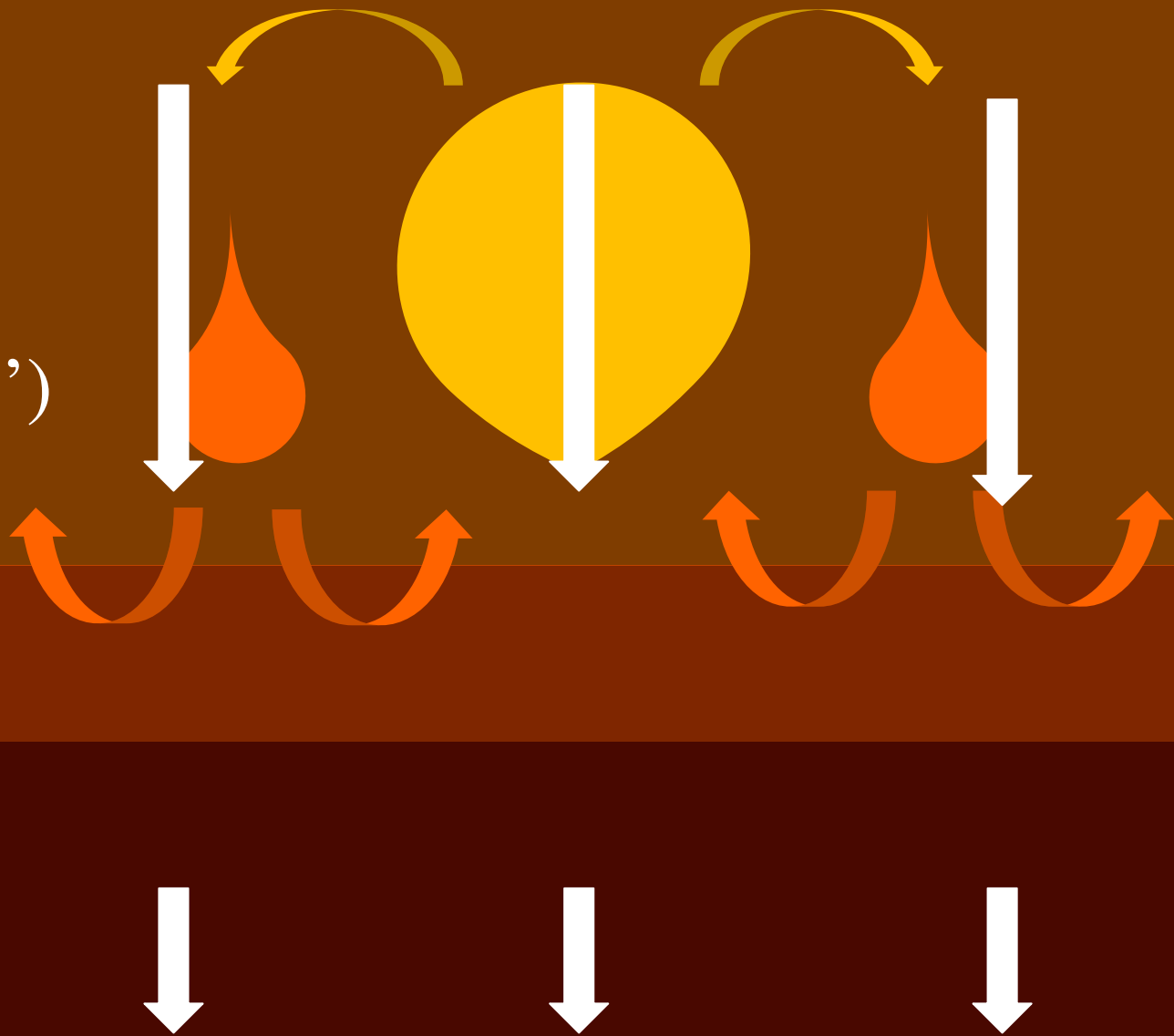
$$F = F_{\text{rad}}$$



$$b(r) = \int N^2 dr = \text{buoyant accel.}$$

$$F = \cancel{F_{\text{rad}}} + F_{\text{conv}}$$

$$F_{\text{conv}} = C_p \rho (v' T')$$



Need a More General Turbulence Model (Reynolds Decomposition)

Back to the Beginning

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = -\nabla P + \rho \mathbf{g} + \nabla \cdot \sigma$$

$$\partial_t(\rho s) + \nabla \cdot (\rho \mathbf{v} s) = \frac{\dot{Q} + \varepsilon}{T}$$

$$P = P(\rho, s, X_i)$$

Reynolds Decomposition

$$\phi = \phi_0 + \phi' \quad \phi_0 = \langle \phi \rangle$$



Hydro Equations



Mean-Field Equations



New steady-state solutions & Critical Curve

Reynolds-Averaged Equations

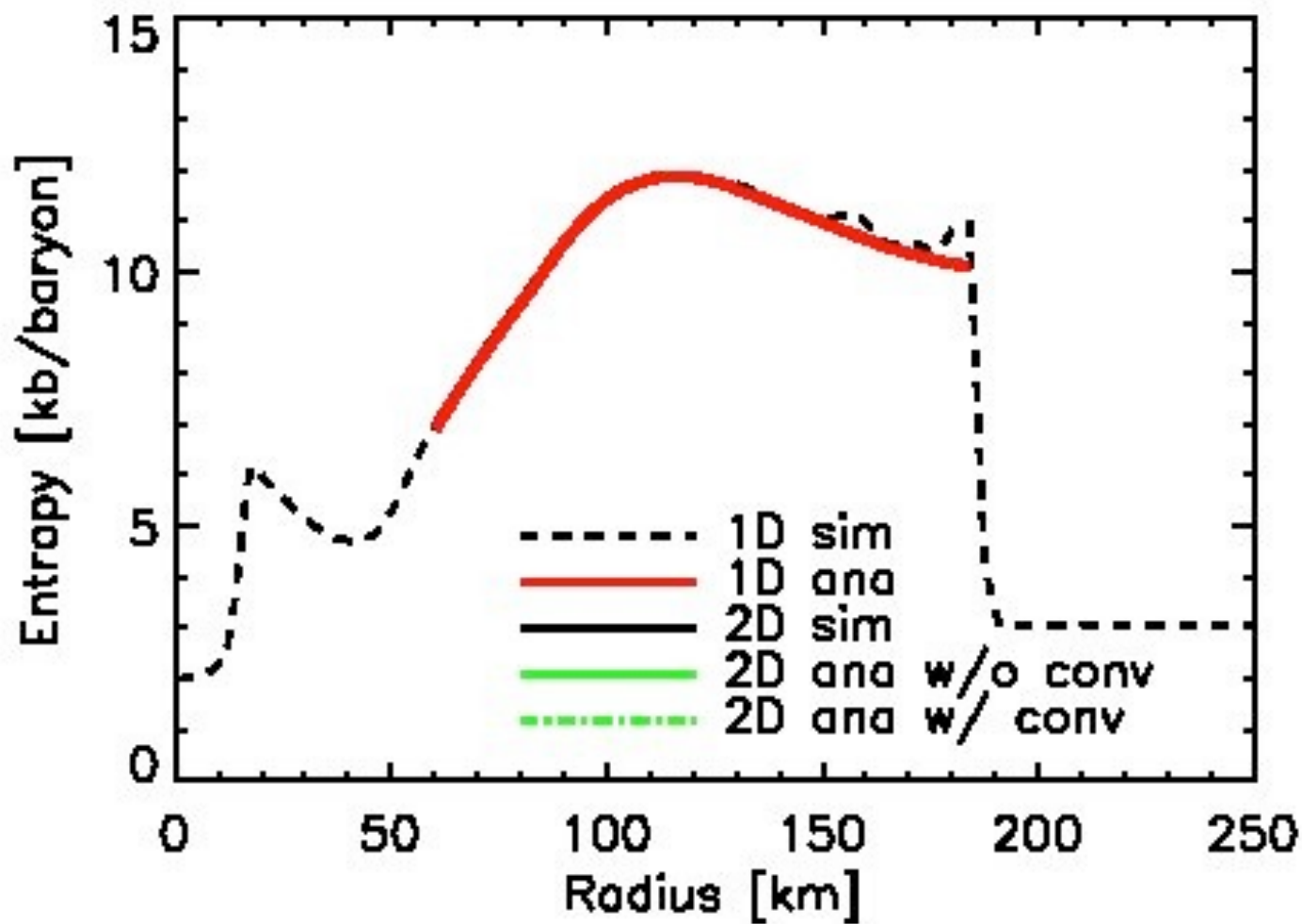
$$\dot{M} = 4\pi r^2 (\rho_0 v_0 + \langle \rho' v' \rangle)$$

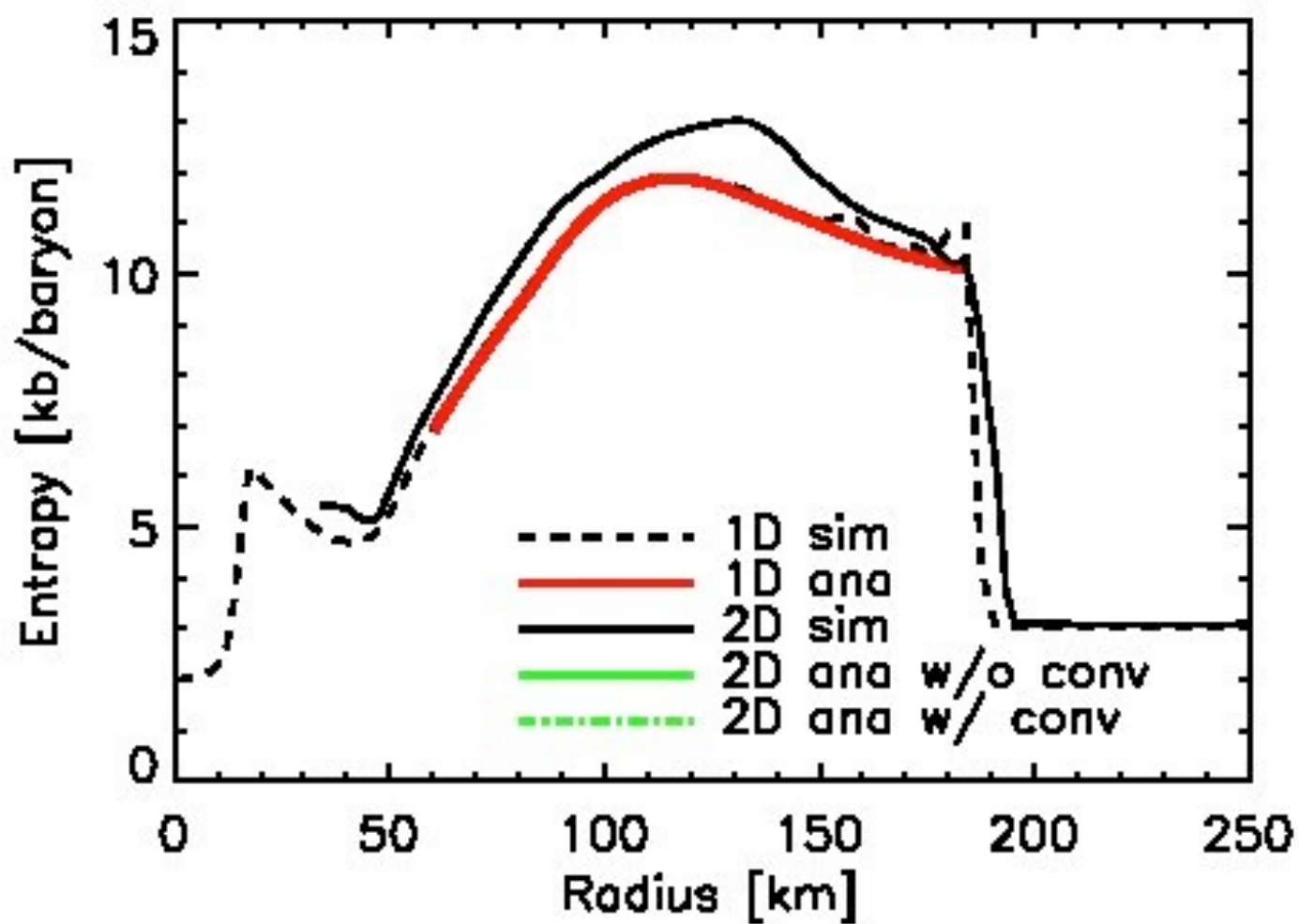
$$\langle \rho \mathbf{v} \rangle \cdot \nabla \mathbf{v}_0 = -\nabla P_0 + \rho_0 g - \nabla \cdot \langle R \rangle$$

$$\langle \rho \mathbf{v} \rangle \cdot \nabla s_0 = \frac{\dot{Q} + \varepsilon}{T} - \nabla \cdot \langle \mathbf{F}_s \rangle$$

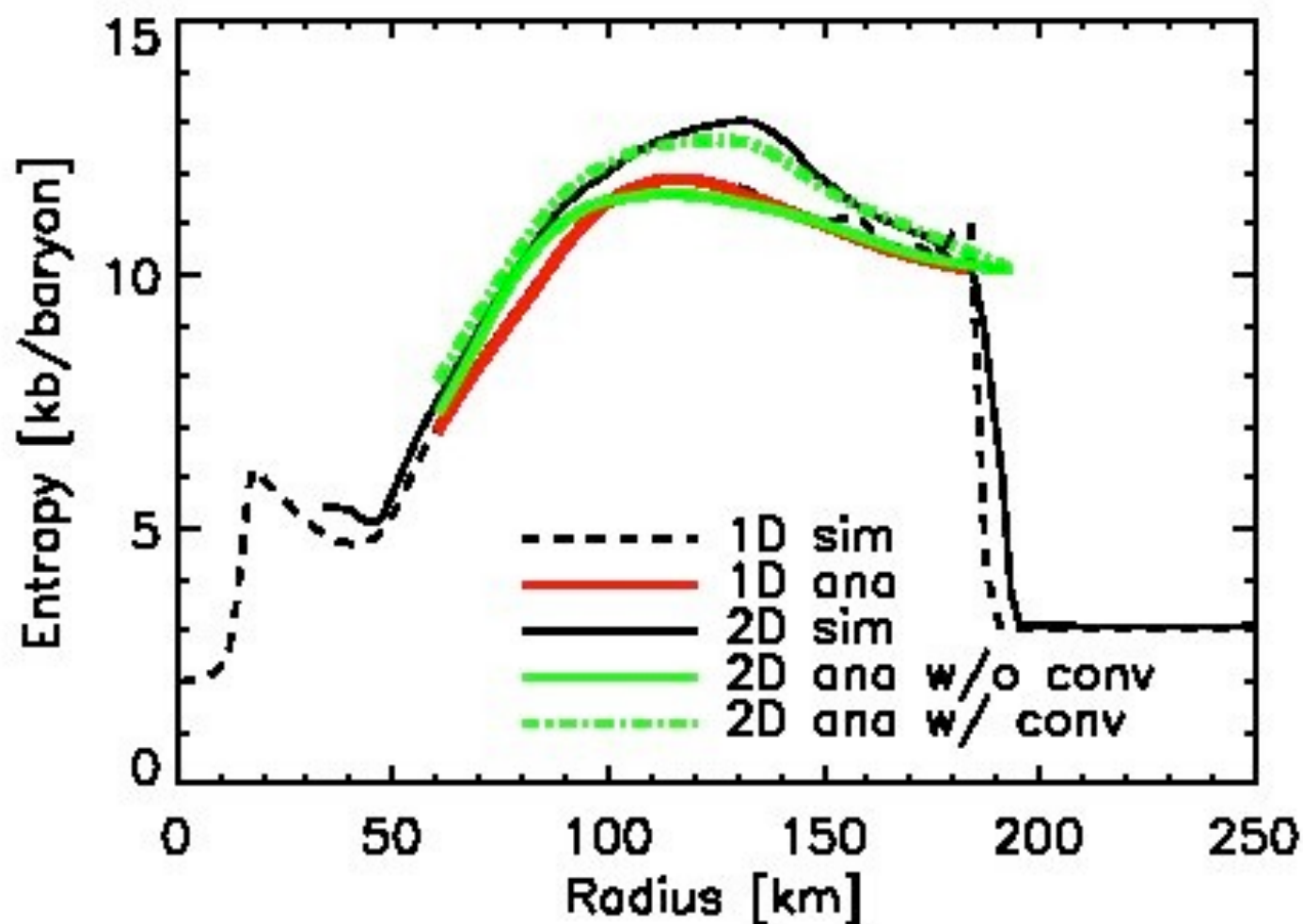
Murphy & Meakin 2011

$$\rho \mathbf{v} \cdot \nabla s = \frac{\dot{Q}}{T}$$





$$\langle \rho \mathbf{v} \rangle \cdot \nabla s_0 = \frac{\dot{Q} + \varepsilon}{T} - \nabla \cdot \langle \mathbf{F}_s \rangle$$



Reynolds-Averaged Equations

$$\dot{M} = 4\pi r^2 (\rho_0 v_0 + \langle \rho' v' \rangle)$$

$$\langle \rho \mathbf{v} \rangle \cdot \nabla \mathbf{v}_0 = -\nabla P_0 + \rho_0 g - \nabla \cdot \langle R \rangle$$

$$\langle \rho \mathbf{v} \rangle \cdot \nabla s_0 = \frac{\dot{Q} + \varepsilon}{T} - \nabla \cdot \langle \mathbf{F}_s \rangle$$

Murphy & Meakin 2011

Turbulent Moment Equations

Equations for 2nd order moments

$$\begin{aligned} \partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle \end{aligned}$$

and more ...

Turbulent Moment Equations

Equations for 2nd order moments

$$\partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle$$

$$\sim \frac{v'^3}{L}$$

$$F_K = \rho K v'$$

Depends upon higher order moments

Turbulent Moment Equations

Equations for 2nd order moments

$$\begin{aligned} \partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle \end{aligned}$$

A Closure Problem!

Closure Strategies

Local Algebraic

Local Single-Point

Global

Closure Strategies

Local Algebraic

Local Single-Point

Global

$$\begin{aligned} \partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle \end{aligned}$$

Closure Strategies

Local Algebraic

Local Single-Point

Global

$$\begin{aligned} \cancel{\partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle)} \\ \approx \langle \rho' v' \rangle g - \varepsilon - \cancel{\nabla \cdot \langle F_K \rangle} \\ \langle \rho' v' \rangle g \approx \varepsilon \sim \frac{\rho v'^3}{L} \end{aligned}$$

MLT is a classic example

Closure Strategies

Local Algebraic

Local Single-Point

Global

$$\begin{aligned} \partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle \end{aligned}$$

Local models for these



Closure Strategies

Local Algebraic

Local Single-Point

Global

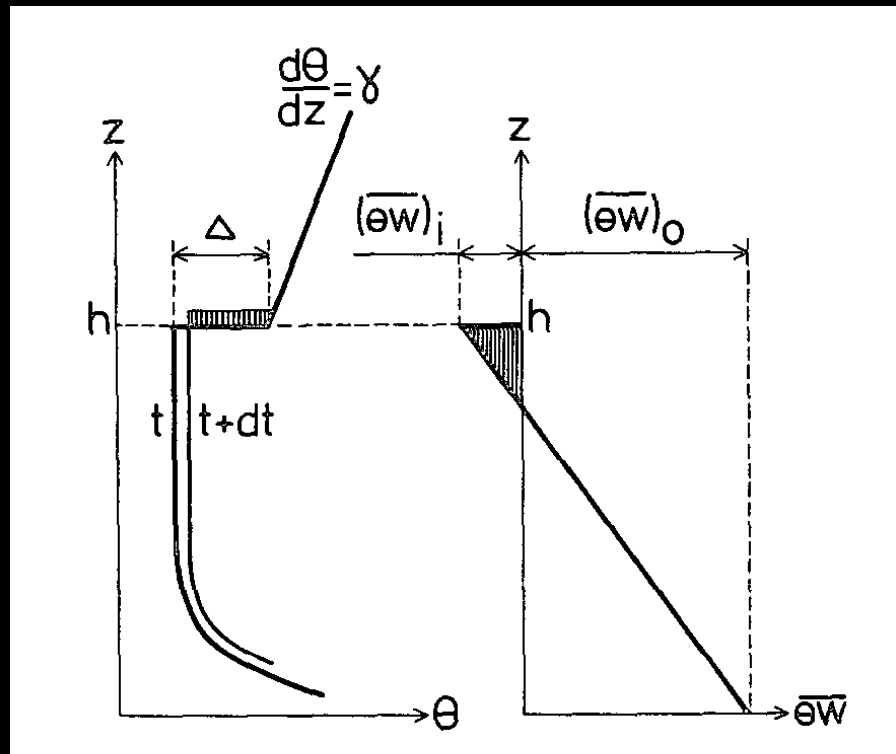
$$\begin{aligned} \partial_t \langle \rho K \rangle + \nabla \cdot (v_0 \langle \rho K \rangle) \\ \approx \langle \rho' v' \rangle g - \varepsilon - \nabla \cdot \langle F_K \rangle \end{aligned}$$

$$\int \langle \rho' v' \rangle g dV = \int \varepsilon dV$$

Global Closure Examples

Earth's Atmospheric Convective Layer

$$\nabla s_0 = 0 \quad \Rightarrow \quad \rho_0 \langle \dot{s} \rangle = -\partial_z \langle F_s \rangle$$

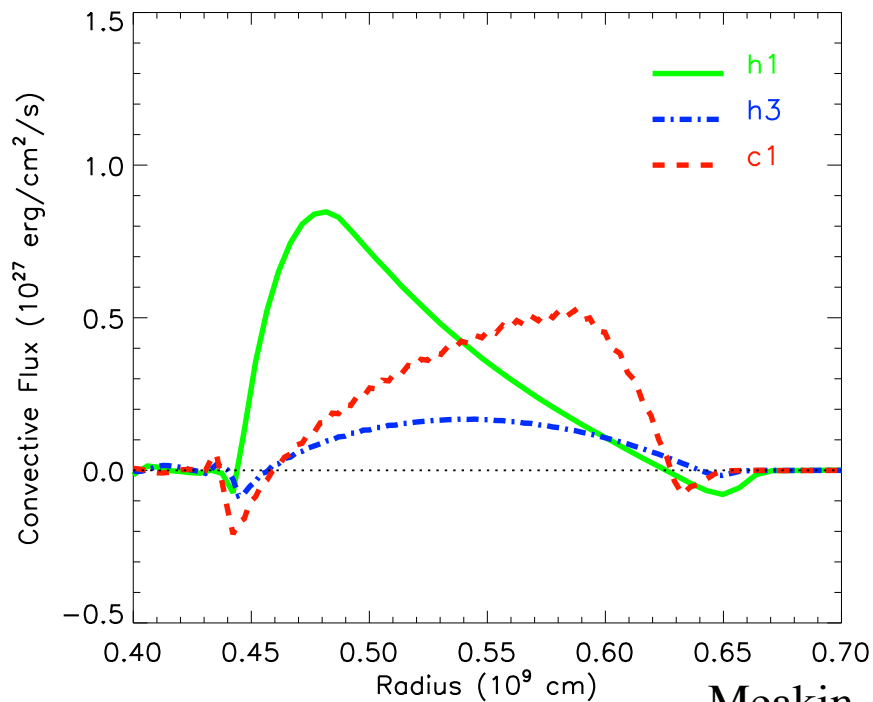


Tennekes 1973

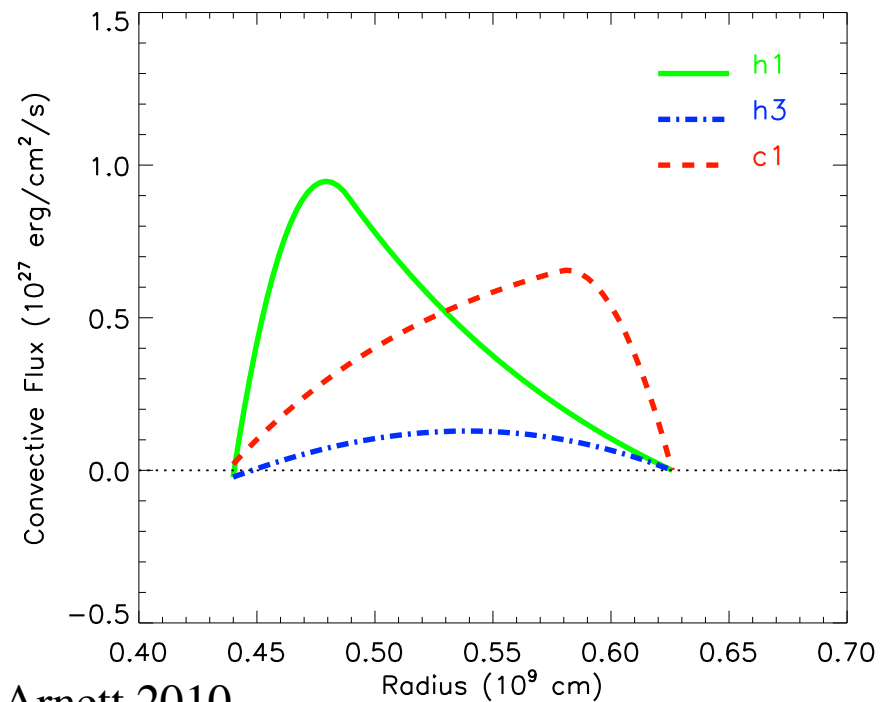
Global Closure Examples

Stellar Convection

$$\nabla s_0 = 0 \Rightarrow \rho_0 \langle \dot{s} \rangle = -\nabla \cdot \langle F_s \rangle + \frac{\dot{Q} + \varepsilon}{T}$$



Meakin & Arnett 2010



Global Closure For CCSNe

$$\langle \rho \mathbf{v} \rangle \cdot \nabla s_0 = \frac{\dot{Q} + \varepsilon}{T} - \nabla \cdot \langle \mathbf{F}_s \rangle$$

Use

$$\int \langle \rho' v' \rangle g dV = \int \varepsilon dV$$

And simulations to inform assumptions
about profiles

Comparison of Timescales

$$\frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \gtrsim 1$$

Heuristic & Empirical

See...

Thompson et al. '00

Janka '01

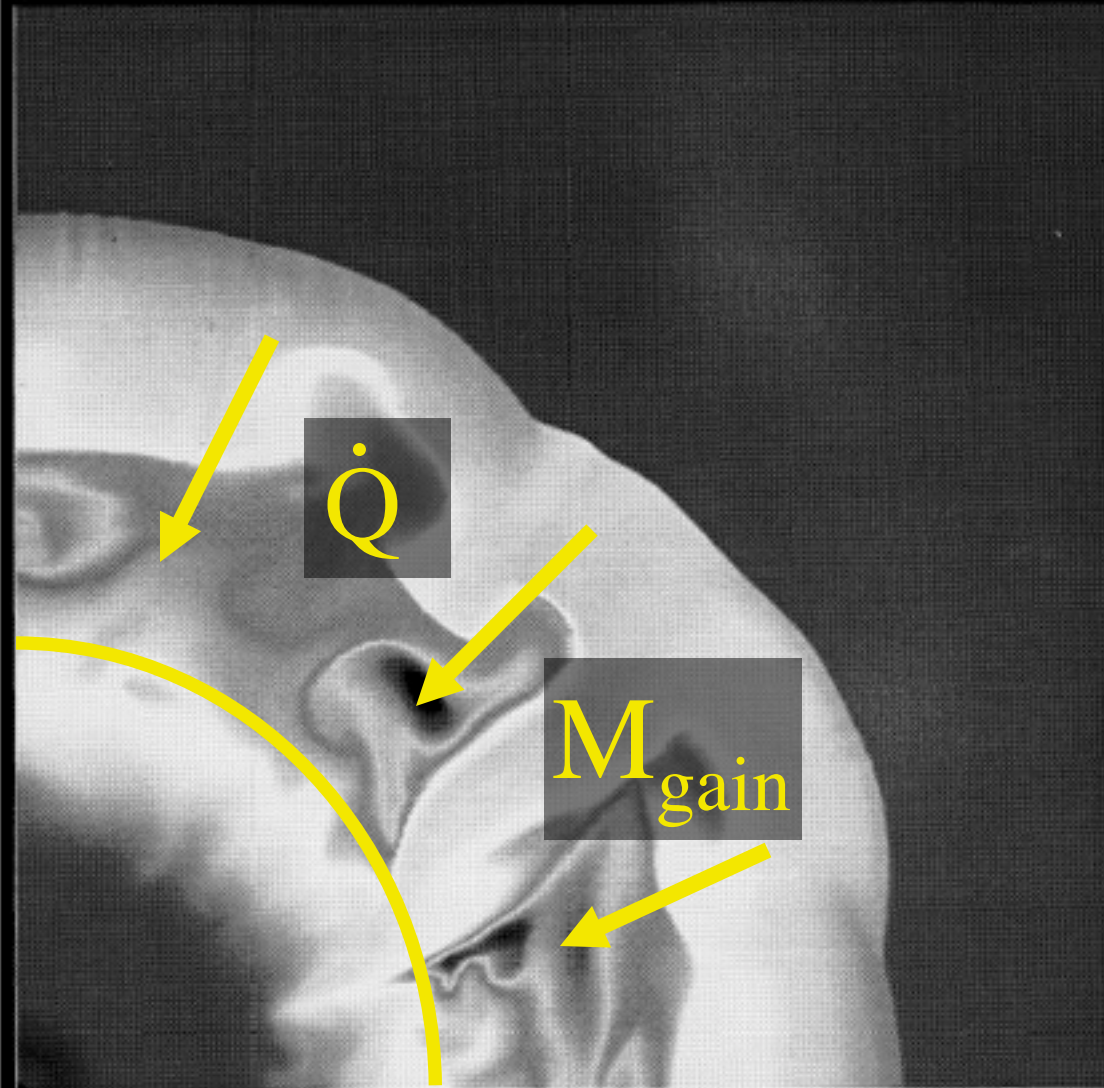
Thompson et al. '03

Murphy et al. '08

Buras '06

Pejcha '11

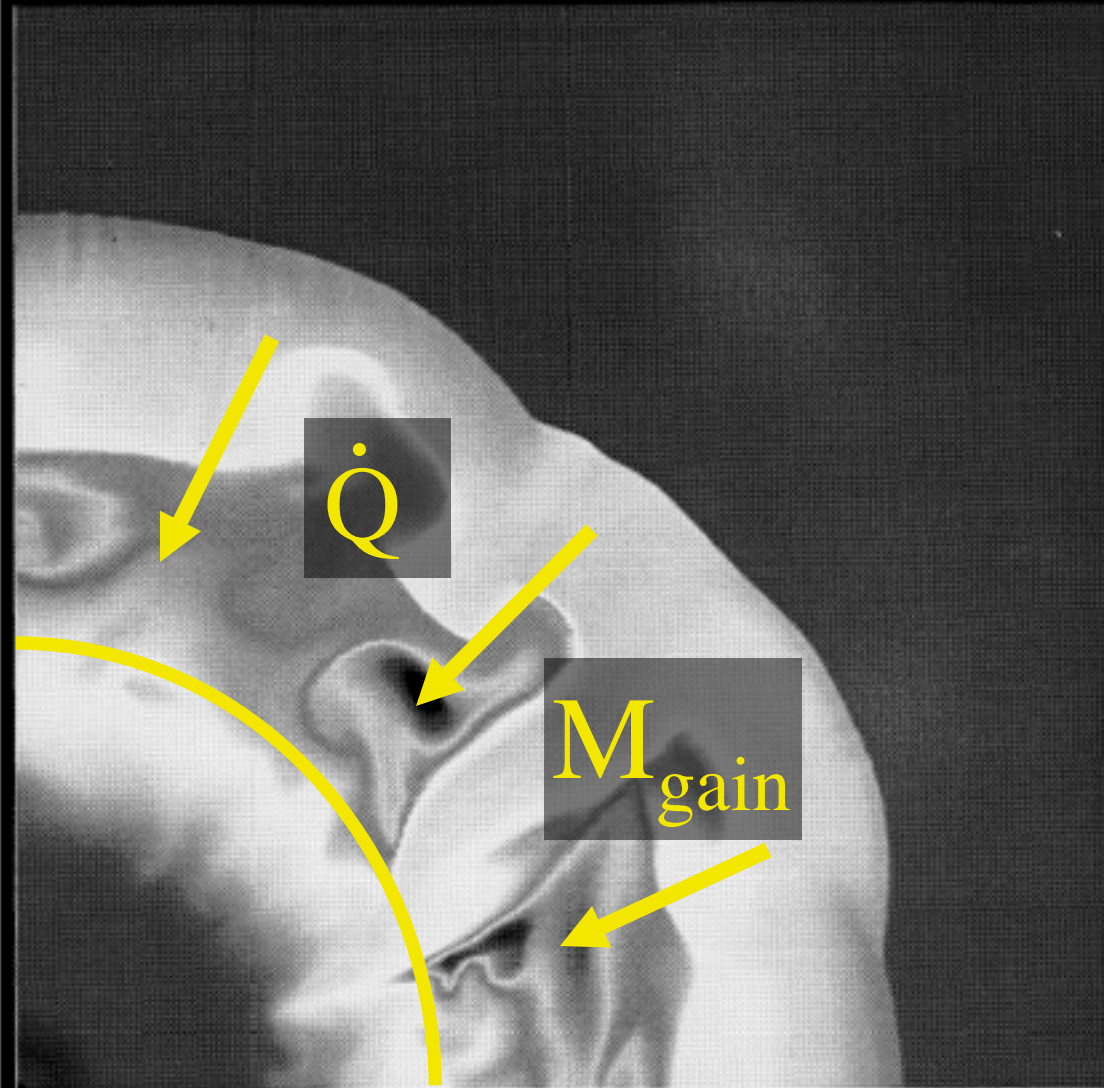
Fernandez '12



Comparison of Timescales

$$\frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \gtrsim 1$$

$$\rho \mathbf{v} \cdot \nabla s = \frac{\dot{Q}}{T}$$



Comparison of Timescales

$$\frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \sim \frac{1}{\Delta s} \int \frac{\dot{Q}}{T} \frac{dr}{\rho v} \quad \frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \gtrsim 1$$

$$\rho \mathbf{v} \cdot \nabla s = \frac{\dot{Q}}{T}$$

Comparison of Timescales

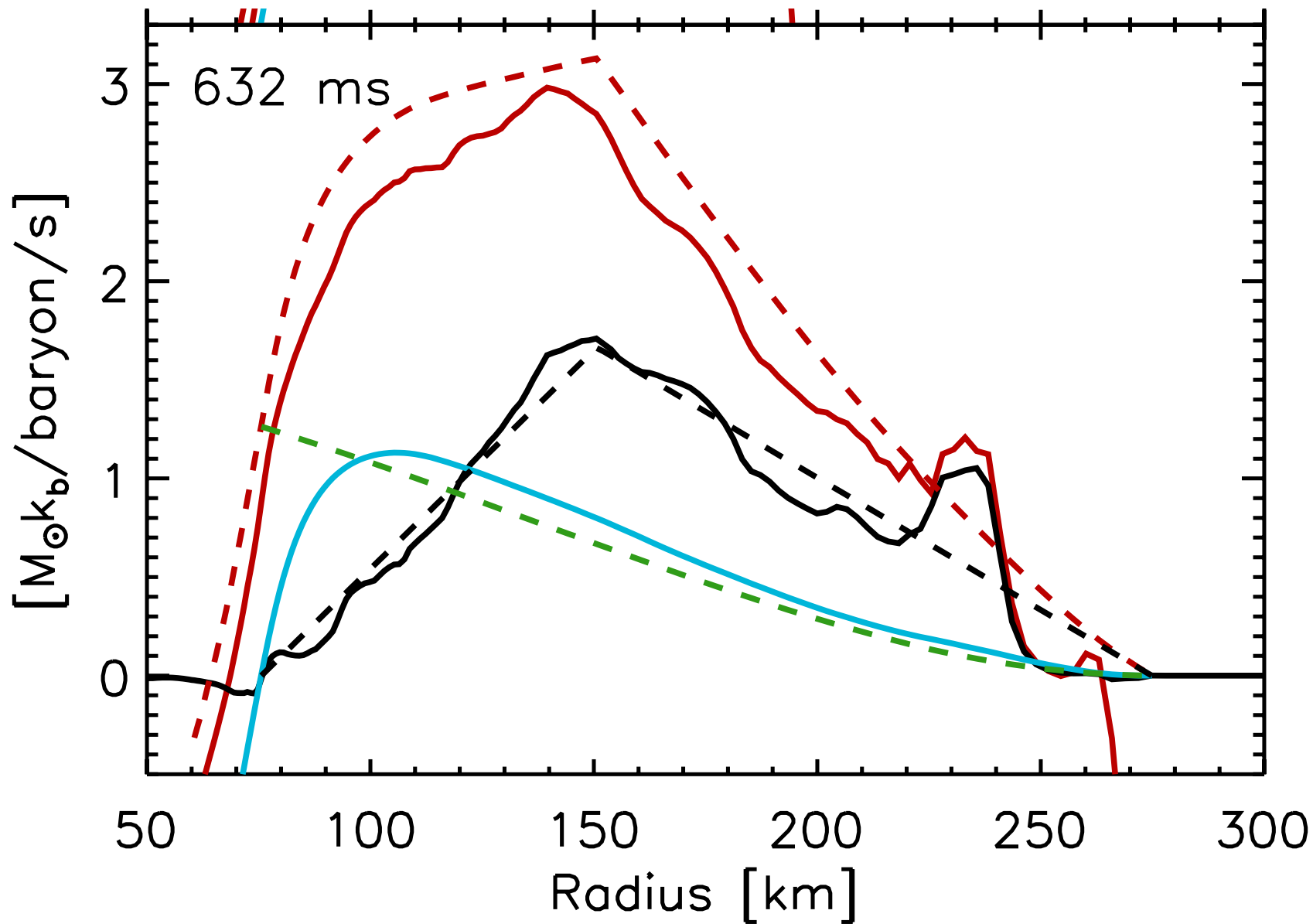
$$\frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \sim \frac{1}{\Delta s} \int \frac{\dot{Q}}{T} \frac{dr}{\rho v} \quad \frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \gtrsim 1$$

$$\Delta s \gtrsim \Delta s_{\text{crit}} \quad \rho \mathbf{v} \cdot \nabla s = \frac{\dot{Q}}{T}$$

Comparison of Timescales

$$\Delta s \gtrsim \Delta s_{\text{crit}} \qquad \frac{\tau_{\text{adv}}}{\tau_{\text{heat}}} \gtrsim 1$$

$$\dot{M}\Delta s = \int \frac{\dot{Q}}{T} dV + \int \frac{\varepsilon}{T} dV + L_s$$



“What about the SASI?”

What dominates the post shock flow?
Convection, SASI... both?

Compare nonlinear theories for convection
and SASI with post shock flow

SASI nonlinear theory

?

Compare nonlinear theories for convection and SASI with post shock flow

Convection nonlinear theory

100+ years

In CCSN...Murphy & Meakin 2012

Compare nonlinear theories for convection and SASI with post shock flow

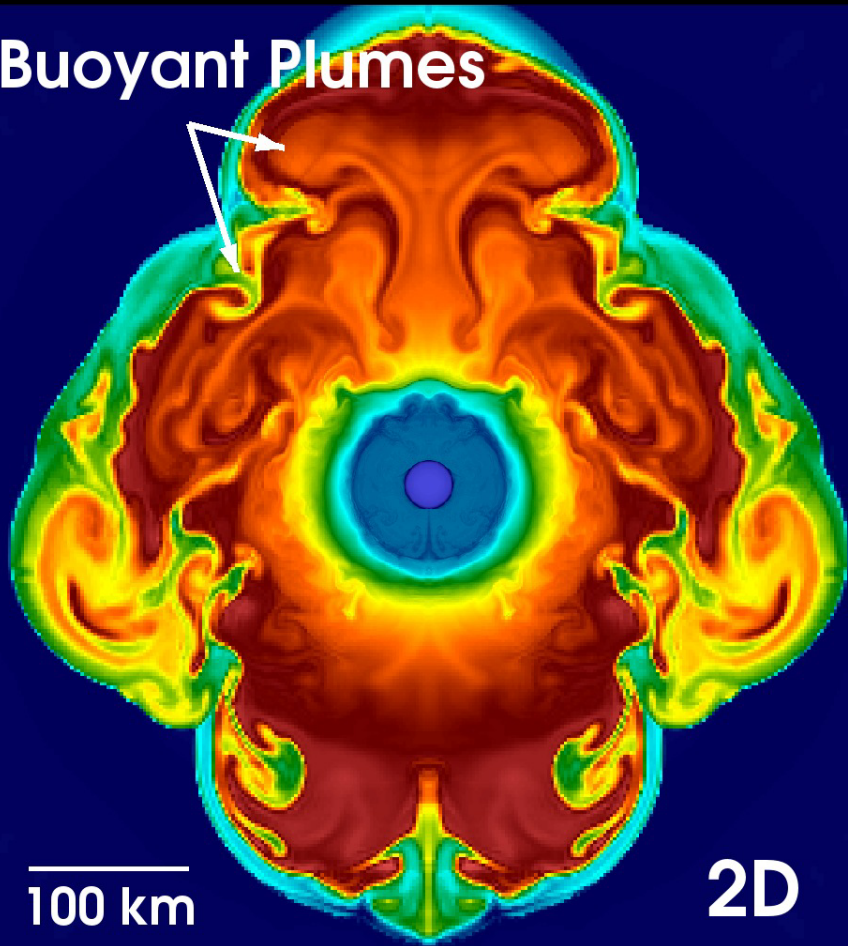
Convection nonlinear theory

100+ years

In CCSN...Murphy & Meakin 2012

We can test this theory with 3D simulations

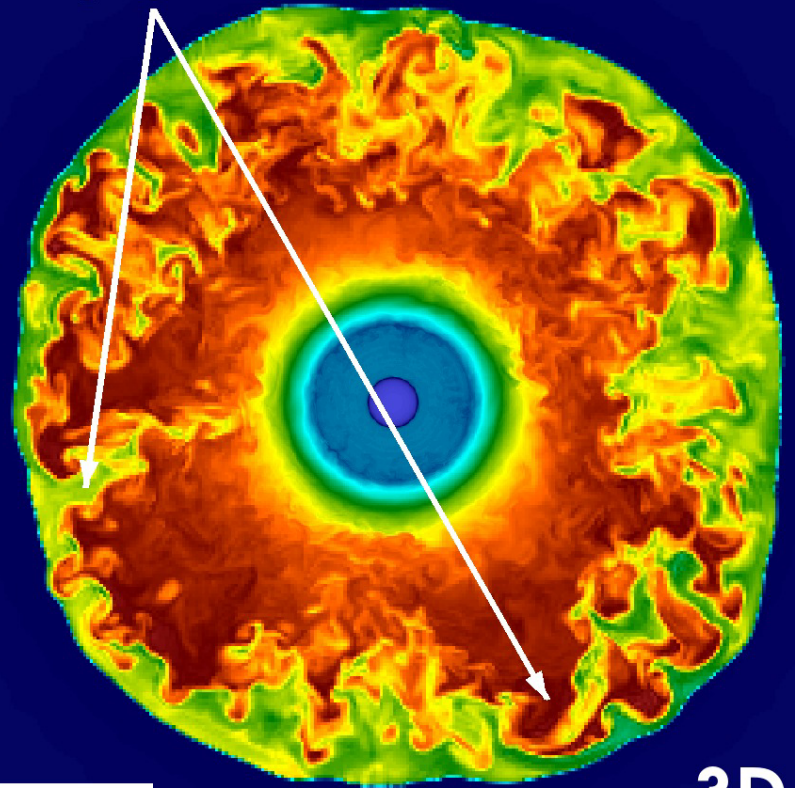
Buoyant Plumes



100 km

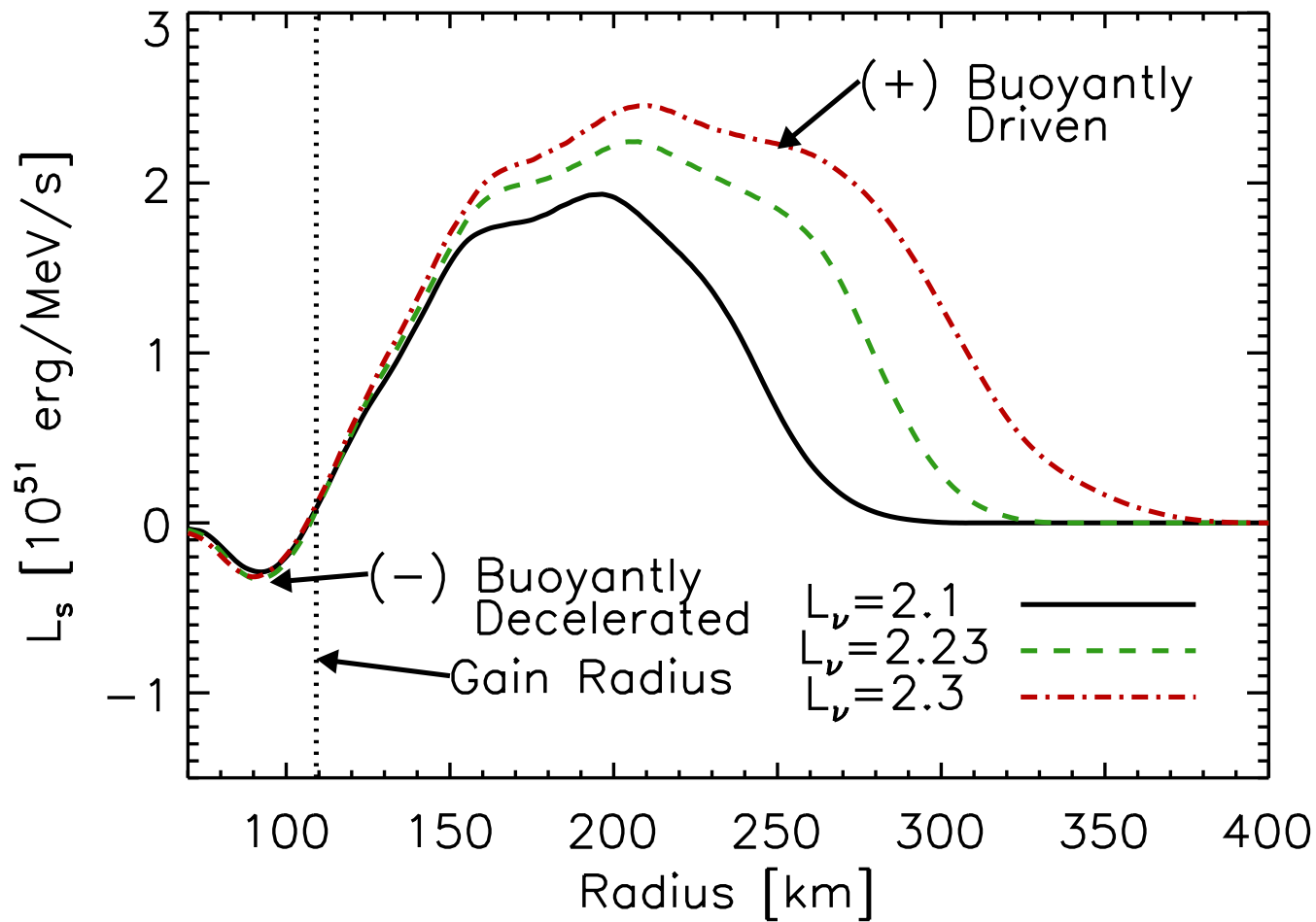
2D

Buoyant Plumes



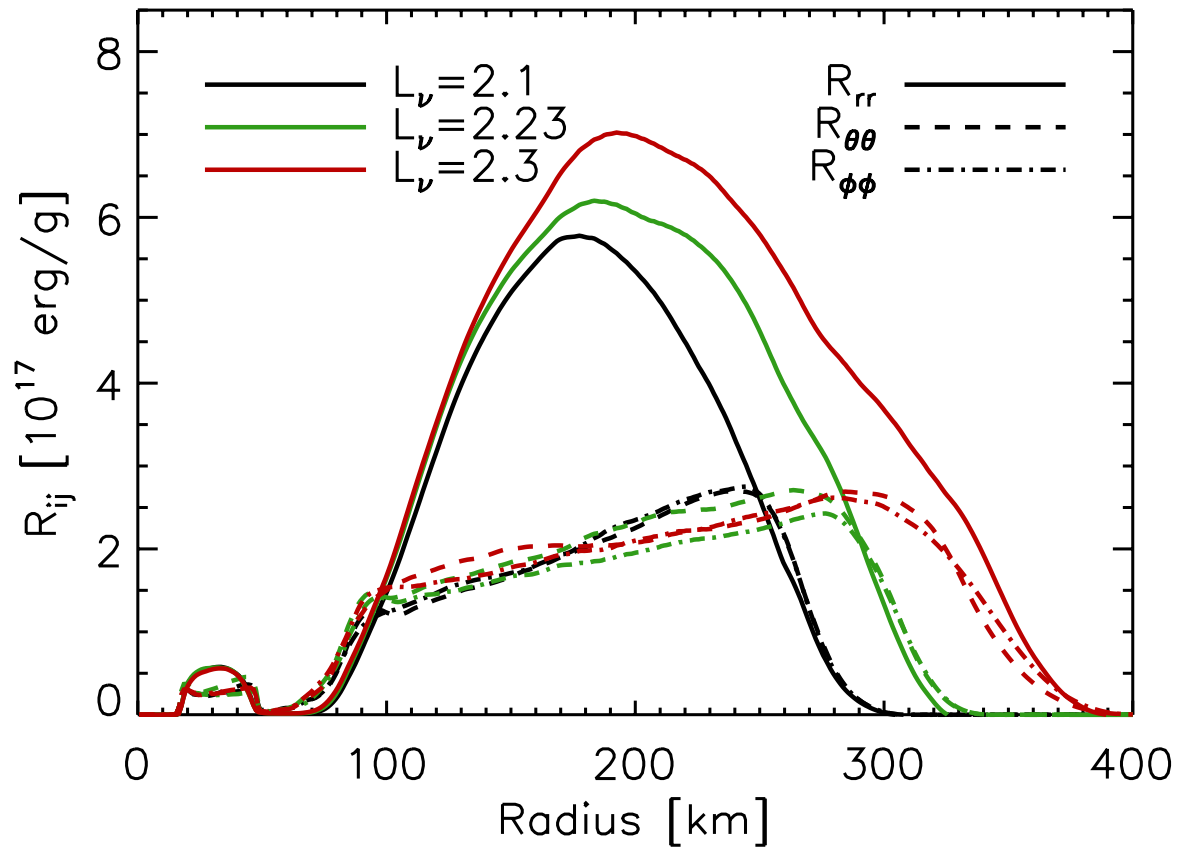
100 km

3D



$$L_s = \langle \rho v' s' \rangle 4\pi r^2$$

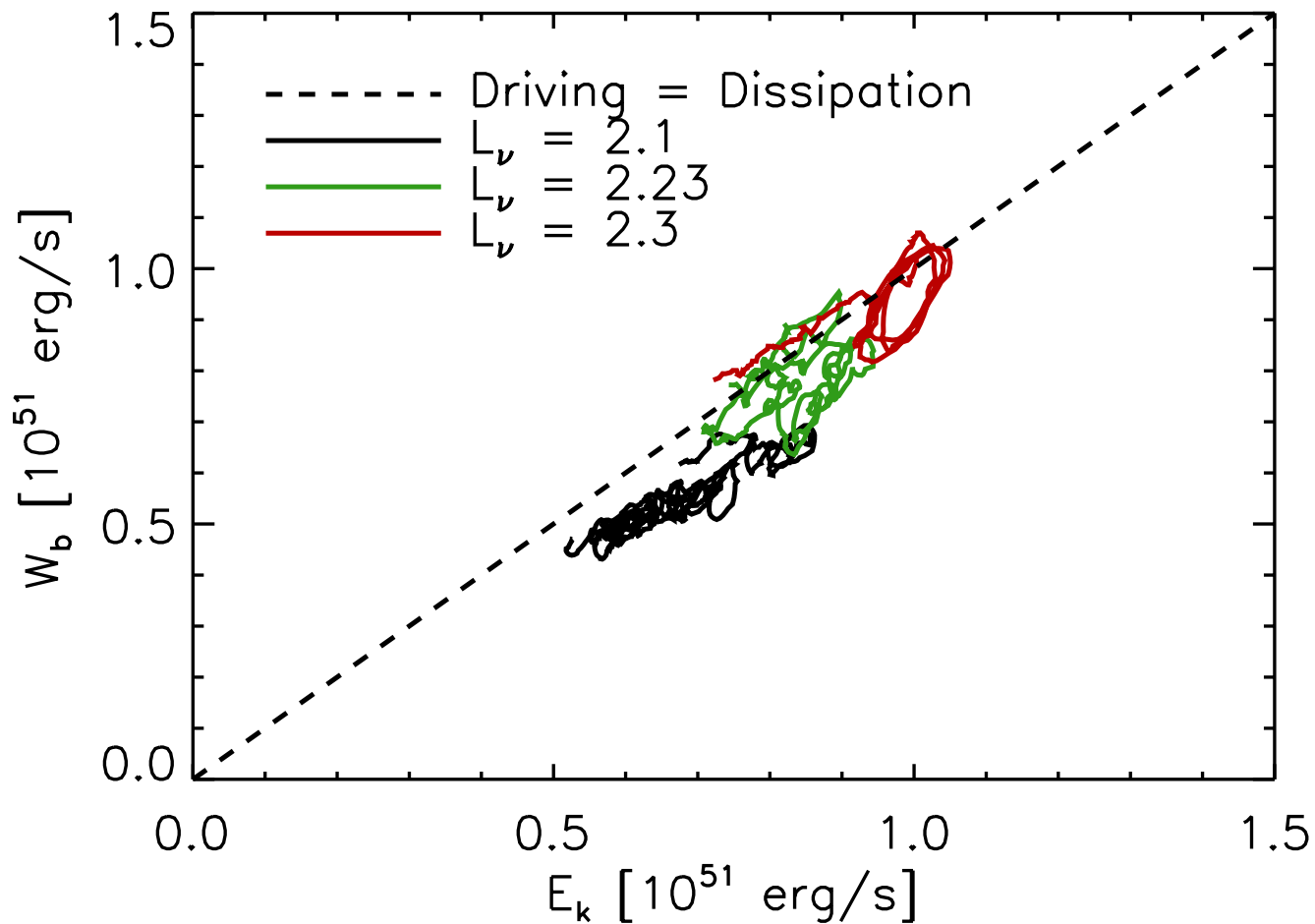
$$R_{ij} = \langle v'_i v'_j \rangle$$

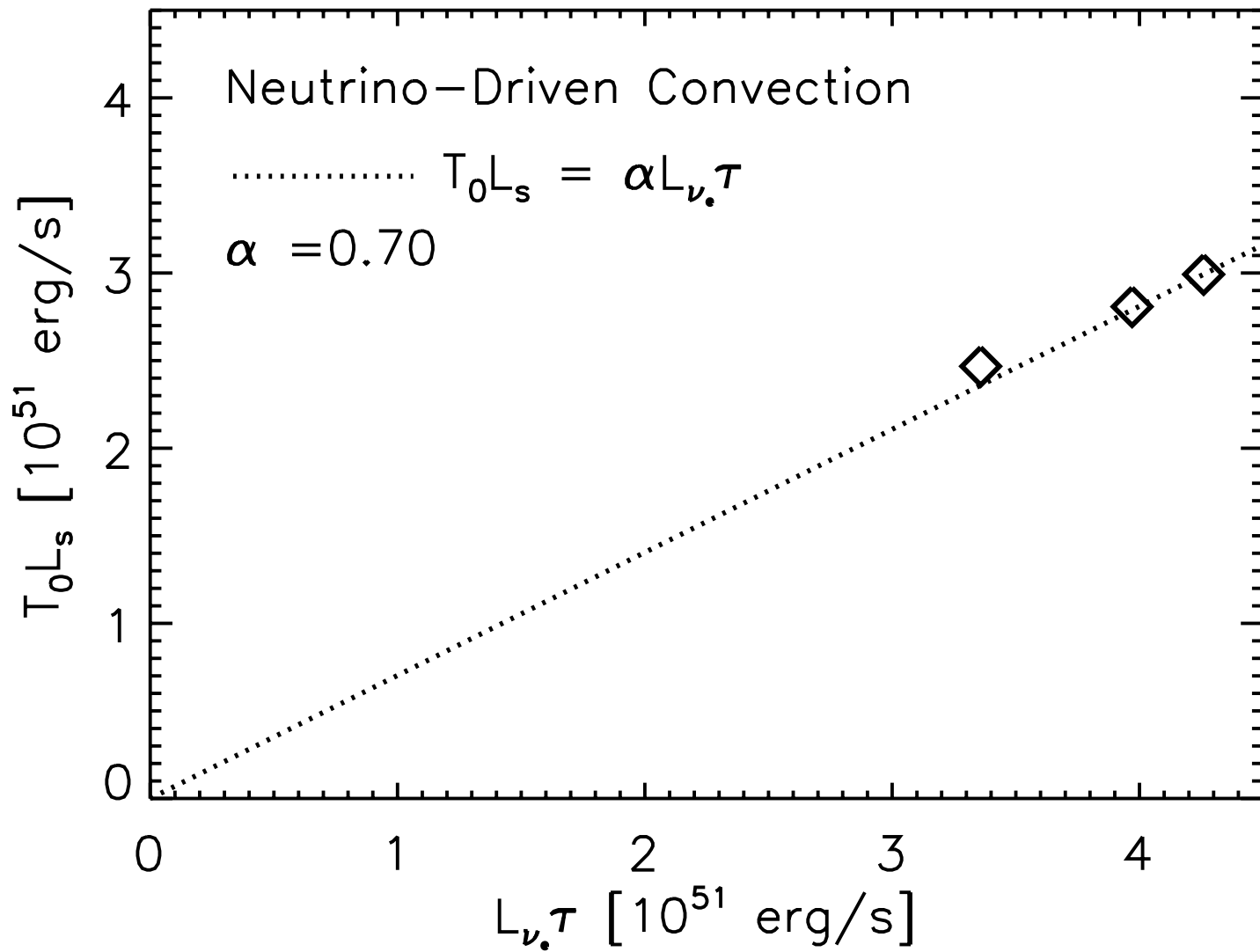


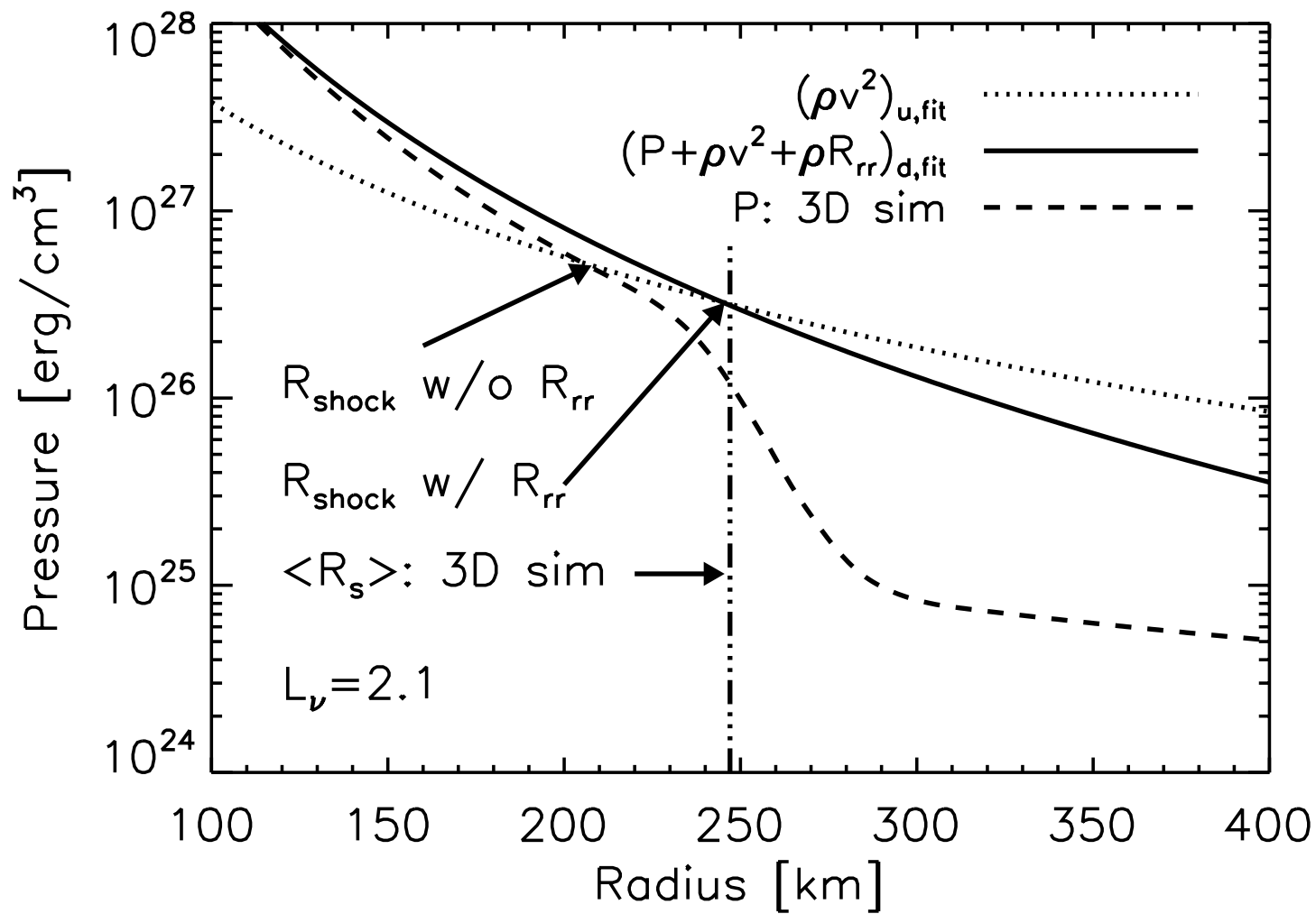
$$R_{rr} \approx R_{\theta\theta} + R_{\phi\phi}$$

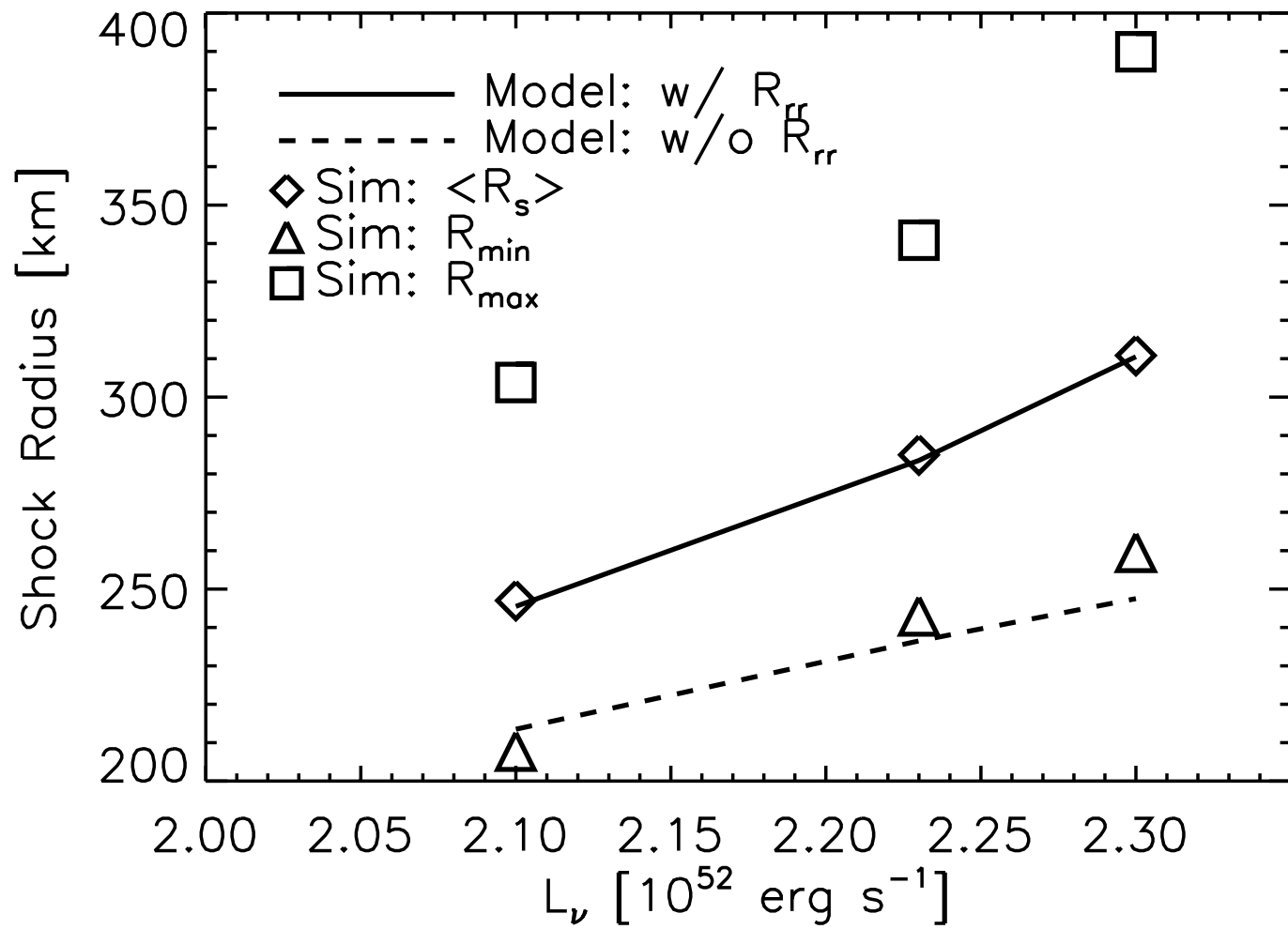
$$R_{\theta\theta} \approx R_{\phi\phi}$$

$$\int \langle \rho' v' \rangle g dV = \int \frac{\rho (v'_r)^3}{L} dV$$









Nonlinear Convection is Consistent with Post Shock Flow

1. Consistent buoyancy flux profile
2. Consistent Reynolds stresses
3. Buoyant driving balances dissipation
4. Analytic scaling between buoyant flux and neutrino driving
5. Expansion of shock due to turbulent ram pressure

*Nonlinear Convection is Consistent
with Post Shock Flow*

But what about the SASI?



*A theory for neutrino-driven
explosions*

A turbulence model for CCSNe

*Post shock flow is consistent with
nonlinear convection theory*