Numerical integration of complex SDEs

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In density functional theory from an SDE viewpoint, we want

$$\langle f \rangle = \operatorname{Tr}[f\rho] = \mathbf{E}f = \frac{\int f(x)e^{-S[x]} Dx}{\int e^{-S[x]} Dx}.$$

S[x] = H/kT is usually $\beta \cdot$ energy, and the dim(x) is large: $Dx = d^n x$. Yang & Lee (1952) studied properties of

$$Z=\int e^{-S[x]} Dx$$

for complex $\beta = 1/kT$. If $\beta = it$ and $S = \int_0^t L[x(s)]ds$, we get Feynman's version of QM. Z is a lot of work and can be awkward. In principle, a simpler procedure (Nelson 1983, Parisi 1981) is

$$\mathbf{E}f = \frac{1}{T} \int_0^T f(X(t)) dt$$

for large T. X(t) is a complex process with SDE

$$dX = -\frac{1}{2}\frac{\partial S}{\partial X}dt + d\omega(t).$$

So, what is Brownian motion?



Figure: Left: 1-D Brownian motion, Right: 2-D Brownian motion

The probability density p(x, t) ($\int p \, dx = 1$) for B-motion satisfies heat equation:

$$\frac{\partial p(\omega,t)}{\partial t} = \frac{1}{2} \frac{\partial^2 p(\omega,t)}{\partial \omega^2}$$

What is $\omega(t)$? It is a sum of increments, each scaling like $(\Delta t)^{1/2}$

$$\omega(t_n)=\sum_{k\leq n}\Delta\omega_k,$$

and

$$\mathsf{E}\{\Delta\omega_i\Delta\omega_j\}=\delta_{ij}\Delta t.$$

The infinitesimal version of this is

$$\begin{aligned} \mathbf{E} d\omega(t) &= 0 \\ \mathbf{E} \{ d\omega(t) \ d\omega(s) \} &= \delta(t-s) \ dt \ ds. \end{aligned}$$

Example, systems $(m \ge 0)$ which become stationary:

$$dx = -x|x|^{m-1}dt + d\omega(t)$$

have solutions whose distribution law satisfies Kolmogorov's forward equation

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial}{\partial x} \left(\frac{1}{2} \frac{\partial}{\partial x} + x |x|^{m-1} \right) p(x,t) \to 0$$

when $t \to \infty$. Density $p(x, t \to \infty)$, properly normalized, is

$$p(x,\infty) = N_m e^{-\frac{2}{m+1}|x|^{m+1}}.$$

Two examples:

$$p(x,\infty) = e^{-2|x|}$$
 for $m = 0$,
 $p(x,\infty) = \frac{1}{\sqrt{\pi}}e^{-|x|^2}$ for $m = 1$.

In quantum systems, where we are interested in complex processes, R.J. Glauber (1963) suggested the following *coherent states* representation:

$$\rho = \int P_t(\alpha) \Lambda_\alpha d^2 \alpha$$

using the basis

$$\Lambda_{\alpha} = |\alpha\rangle\langle\alpha|$$

of coherent states

$$|\alpha\rangle = e^{-|\alpha|^2/2}e^{\alpha a^{\dagger}}|0\rangle.$$

These states are **over complete** - only the diagonal elements needed. The dynamics are from the canonical von Neumann relation ($\hbar = 1$)

$$\dot{\rho} = i[\rho, H].$$

For a single mode BEC situation, the Hamiltonian is

$$H=\frac{1}{2}(a^{\dagger}a)^{2}.$$

The idea: take Glauber & Sudarshan's representation (1968), form the dynamical equations, and get a PDE for $P_t(\alpha)$. Using the canonical commutation relation $[a, a^{\dagger}] = 1$,

$$a^{\dagger}a\|lpha
angle = lpha rac{\partial}{\partial lpha}\|lpha
angle$$

where

$$|\alpha\rangle = e^{-|\alpha|^2/2} \|\alpha\rangle$$

in terms of the un-normalized Bargmann states

$$\|\alpha\rangle = e^{\alpha a^{\dagger}}|0\rangle$$

Integrating by parts, and the notation

$$Q = e^{-|\alpha|^2} P$$

we almost get a Fokker-Planck equation

$$\frac{\partial}{\partial t}Q = \frac{i}{2}\left[(\partial_{\bar{\alpha}}\bar{\alpha})^2 Q - (\partial_{\alpha}\alpha)^2 Q\right]$$

After some manipulation, and writing α in terms of its real/imaginary parts,

$$\alpha = x_1 + i x_2,$$

we get our Fokker-Planck equation:

$$\frac{\partial}{\partial t}P = (\partial_2 x_1 - \partial_1 x_2)|\alpha|^2 P + \frac{1}{2}(\partial_1 x_2 - \partial_2 x_1)P + \frac{1}{2}\sum_{j,k=1}^2 \partial_j \partial_k [a_{jk}P].$$

Notation: $\partial_i = \frac{\partial}{\partial x_i}$, for i = 1, 2. The *diffusion* matrix $A = [a_{ij}]$ is

$$\begin{bmatrix} x_1 x_2 & \frac{1}{2} (x_2^2 - x_1^2) \\ \frac{1}{2} (x_2^2 - x_1^2) & -x_1 x_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} Im[\alpha^2] & -\frac{1}{2} Re[\alpha^2] \\ -\frac{1}{2} Re[\alpha^2] & -\frac{1}{2} Im[\alpha^2] \end{bmatrix}.$$

Fundamental problem: matrix A is **not** positive definite: eigenvalues of A are $\pm \frac{1}{2} |\alpha|^2$. Let's go on, pretending we had good sense. First idea: project the flow onto stable directions in the positive eigenspace.

$$\begin{array}{rcl} \mathcal{A} & = & \mathcal{U}\left(\begin{array}{cc} \frac{1}{2}|\alpha|^2 & 0\\ 0 & -\frac{1}{2}|\alpha|^2 \end{array}\right) \mathcal{U}^{\mathsf{T}} \xrightarrow{\mathcal{P}} \frac{1}{2}|\alpha|^2 \mathcal{U}\left(\begin{array}{cc} 1 & 0\\ 0 & 0 \end{array}\right) \mathcal{U}^{\mathsf{T}} \\ & = & \mathcal{A}'. \end{array}$$

To get the term $\sigma d\omega$ in the SDE, with $d\omega = (d\omega_1, d\omega_2)^T$, set $A' = \sigma \sigma^T$ and $\theta = \phi - \pi/4$, $\phi = \arg(\alpha)$,

$$\sigma = \frac{|\alpha|}{\sqrt{2}} \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}.$$

This projection is not unique. Any variant of $\sqrt{A'}$ will do.



Figure: Stable and unstable fluctuations in the Brownian increment

Image: A matrix and a matrix

Where $\phi = \arg(\alpha)$ is the phase of α , choice $\theta = \phi - \pi/4$ keeps $U \in O(2)$ in the subspace of A'. The positive eigenvalue equation is

$$\left(\begin{array}{cc} \sin(2\phi) & -\cos(2\phi) \\ -\cos(2\phi) & -\sin(2\phi) \end{array}\right) \left(\begin{array}{c} \cos(\theta) \\ \sin(\theta) \end{array}\right) = \left(\begin{array}{c} \cos(\theta) \\ \sin(\theta) \end{array}\right).$$

That is,

$$\sin(2\phi - \theta) = \cos(\theta)$$
 and $\cos(2\phi - \theta) = -\sin(\theta)$,
or $-ie^{2i\phi} = e^{2i\theta}$, with solution $\theta = \phi - \pi/4$. the resulting SDE is
 $d\alpha = -i(|\alpha|^2 + 1/2)\alpha dt + \nu \sqrt{-i/2} \alpha d\omega_1$,
where $\nu = \cos(\psi)$ of arbitrary phase ψ . Notice the two singular

where $\nu = \cos(\psi)$ of arbitrary phase ψ . Notice the two singular points: $\alpha = 0$ and $\alpha = \infty$.

Unfortunately, the Brownian increment is not isotropic - it depends on $\phi = \arg \alpha$. All variants of $d\omega' = (d\omega'_1, d\omega'_2)^T$ of the form

$$d\omega' = \left(egin{array}{cc} \cos(\psi) & -\sin(\psi) \ \sin(\psi) & \cos(\psi) \end{array}
ight) \left(egin{array}{c} d\omega_1 \ d\omega_2 \end{array}
ight),$$

are equally valid. Thus, we can make any choice $\nu = \cos(\psi)$, $\psi \sim U(0, 2\pi)$ uniformly. Even simpler, $\bar{\nu} = (\langle \cos^2(\psi) \rangle)^{1/2}$, which yields the complex SDE

$$d\alpha = -i(|\alpha|^2 + 1/2)\alpha dt + \frac{1}{2}\sqrt{-i}\alpha d\omega_1,$$

where $d\omega_1$ is the real component of a complex Brownian increment.

Now we need an integration algorithm, quite generally for the problem

$$dx(t) = b(x(t))dt + \sigma(x(t))d\omega(t),$$

here is a weak 2^{nd} order procedure which is trapezoidal rule stable. It uses 3 stages beginning at x_0 :

$$\begin{aligned} x_{1/2} &= x_0 + \frac{h}{4} (b(x_{1/2}) + b(x_0)), \text{ solve for } x_{1/2}, \end{aligned} \tag{1a} \\ x_1 &= x_{1/2} + \int_0^h \sigma(x(s)) d\omega(s), \text{ starting at } x_{1/2}, \end{aligned} \tag{1b} \\ x_h &= x_1 + \frac{h}{4} (b(x_h) + b(x_1)), \text{ solve for } x_h. \end{aligned}$$

Another variant is from 1998 (wpp). Martingale step (1b) is described below. Also: see Denis Talay (1986).

$$x_{1} = x_{1/2} + \frac{1}{2} \{ \sigma(x_{1/2} + \sqrt{\frac{1}{2}}\sigma(x_{1/2})\xi_{0}) + \sigma(x_{1/2} - \sqrt{\frac{1}{2}}\sigma(x_{1/2})\xi_{0}) \} \xi_{1} + (\frac{\partial\sigma}{\partial x})(x_{1/2})\sigma(x_{1/2}) \Xi.$$

where $\xi_k = \sqrt{h}z_k$ are iid Gaussian RVs with mean zero and variance *h*. A needed stochastic integral is approximated by

$$\begin{split} I^{\epsilon\gamma} &= \int_{t}^{t+h} \omega^{\epsilon}(s) \, d\omega^{\gamma}(s) \quad \approx \quad \Xi^{\epsilon\gamma} \\ &= \quad \frac{h}{2} \left(z_{1}^{\epsilon} z_{1}^{\gamma} - \tilde{z}^{\epsilon\gamma} \right) \quad \text{if } \epsilon > \gamma, \\ &= \quad \frac{h}{2} \left(z_{1}^{\epsilon} z_{1}^{\gamma} + \tilde{z}^{\gamma\epsilon} \right) \quad \text{if } \epsilon < \gamma, \\ &= \quad \frac{h}{2} \left((z_{1}^{\epsilon})^{2} - 1 \right) \quad \text{ when } \epsilon = \gamma. \end{split}$$

э

Regardless of method, we need metrics to test it. We compared moments. Start with the harmonic oscillator basis

$$|k
angle = rac{1}{\sqrt{k!}}(a^{\dagger})^k|0
angle.$$

Completing the square and some algebra

$$\langle \alpha | e^{iHt} a^m e^{-iHt} | \alpha \rangle = \alpha^m \exp\left(|\alpha|^2 (e^{-imt} - 1) - i \frac{m^2 t}{2} \right).$$

These moments are not physical observables.

Here is where we started:



Figure: $Im E[\alpha]$, Deuar and Drummond, Comp. Phys. Comm., 2001

So, what do these moments actually look like?



Figure: Left: $\mathbf{E}[\alpha]$, Right: $\mathbf{E}[\alpha^2]$



Figure: $\mathbf{E}[\alpha]$ using Glauber-Sudarshan rep. and projection



Figure: $\mathbf{E}[\alpha^2]$ using Glauber-Sudarshan rep. and projection

Glauber-Sudarshan results better, but unsatisfactory. Next idea: Deuar and Drummond. Treat α and $\beta = \overline{\alpha}$ separately. SDEs are

$$d\alpha = -i(\bar{\beta}\alpha + 1/2)\alpha dt + \sqrt{-i\alpha}d\omega_1$$
 (2a)

$$d\beta = -i(\bar{\alpha}\beta + 1/2)\beta dt + \sqrt{-i}\beta d\omega_2.$$
 (2b)

Related singular pts. $\alpha = 0$, $\beta = \infty$, and $\beta = 0$, $\alpha = \infty$.

$$d\alpha = -i(\bar{\beta}\alpha + 1/2)\alpha dt$$

$$d\beta = -i(\bar{\alpha}\beta + 1/2)\beta dt.$$

Real $\alpha_0, \beta_0, \ d\alpha/\alpha = -d\bar{\beta}/\bar{\beta}$, thus $\bar{\beta}\alpha = n_0$. Solutions

$$lpha(t) = lpha_0 e^{-i(n_0+1/2)t}$$
 and $eta(t) = eta_0 e^{-i(ar n_0+1/2)t}.$

Now perturb $n_0 \rightarrow n_0 + i\delta$.

$$\alpha(t)
ightarrow lpha(t) e^{\delta t}$$
 and $eta(t)
ightarrow eta(t) e^{-\delta t}$.

So, α grows, and $\beta \rightarrow {\rm 0.}$



Figure: Annulus regularization: $r_{<}(\lambda), r_{>}(\lambda)$.

To control α, β , we need $r_{<} \leq |\alpha|, |\beta| \leq r_{>}$ parameterized by λ . A renormalization scheme (also Sidi's GREP)

$$\mathbf{E}[\alpha^m] = \frac{c_{-1}}{\lambda} + c_0 + \sum_{k \ge 1} c_k \lambda^k$$

wasn't very successful, so we settled for optimization: best fit to known $\mathbf{E}[\alpha]$ and compared $\mathbf{E}[\alpha^m]$ for m > 1.

$$r_{<} = \lambda \cdot |\alpha_0| \qquad r_{>} = \frac{|\alpha_0|}{\lambda^2}.$$

At time step t_k , if α_k is outside annulus:

	toroid	annulus
$ \alpha > r_>$	$\alpha \to \frac{r_{<}}{r_{>}} \alpha$	$\alpha ightarrow (2rac{r_{>}}{ \alpha } - 1) lpha$
$ \alpha < r_{<}$	$\alpha \rightarrow \frac{r_{>}}{r_{<}} \alpha$	$\alpha ightarrow (2\frac{r_{<}}{ \alpha } - 1) \alpha$

Figure: Artificial boundary conditions for $\alpha - \beta$ equations.



Figure: **E**[α] using annulus regularization: $\lambda = 0.64$



Figure: **E**[α^2] using annulus regularization: $\lambda = 0.64$



Figure: $\mathbf{E}[\alpha^3]$ using annulus regularization: $\lambda = 0.64$

Conclusions:

- For complex SDEs, instability is not just a problem: it's in the nature of the beasts.
- A good integrator should show growing processes when they are supposed to.
- Regularization is necessary: projections, artificial boundary conditions, filtrations.
- Long time functionals are possible if additional Fourier/Laplace information is known.
- Numerical inversion of Laplace transform also needs regularization (Perret, 2010). Likewise, discrete Fourier analysis.
- ► Wick rotations using formal scaling ω(ξt) = √ξῶ(t) did not work (Perret, 2010).

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