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Thanks also to:

J. P. Vary (ISU), R. Furnstahl (OSU),

R. Roth (TU Darmstadt), S. Bogner (MSU)

Effective Field Theories and the Many-Body Problem, INT, 04/01/2009 Louisiana State University

Similarity Renormalization Group and V_{NN}

Bare interaction

$$(V_{NN}, V_{NNN}, \ldots)$$
$$H_{s=0}$$

Unitary transformations Renormalized interaction

 H_{s}

 $\lambda = \frac{1}{\sqrt{s}}$

$$H_s = e^{s\eta} H_{s=0} e^{-s\eta}$$

s ... 'flow parameter'

'flow equation' $\frac{dH_s}{ds} = [\eta, H_s] \qquad \eta = [O, H_s]$

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Body Problem, INT, 04/01/2009

Role of Symmetries in SRG Transformations of NN interactions







Symplectic Sp(3, R)) Su(3) Mars' Deímos





Intrinsic nucleon dynamics reflected in shape deformation, irrelevant of the orientation in space

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Choice of the SRG-generator: Is it vital?
Bare interaction

$$(V_{NN}, V_{NNN}, ...)$$

 $H_{s=0}$
 $H_s = e^{s\eta}H_{s=0}e^{-s\eta}$
 $Interaction$
 H_s
 $Interaction$
 H_s
 $Interaction$
 H_s
 $Interaction$
 H_s
 $Interaction$
 $Interaction Interaction Interactio$

Choice of the SRG-generator: Is it vital?
Bare interaction

$$(V_{NN}, V_{NNN}, ...)$$

 $H_{s=0}$
 $H_{s=0}$











J.P. Draayer and G. Rosensteel, Nucl. Phys. A 439 (1985) 61

Effective Field Theories and the Many-Body Problem, INT, 04/01/2009

Role of Symmetries in SRG III

Detecting the Many-body Forces: Integrity Basis $\begin{bmatrix} X_i, C_2^{su(3)} \end{bmatrix} = 0$ $H_D(s) = \alpha(s)C_{su(3)}^{(2)} + \beta(s)\{X\}^n$ $\{X\}^n : 1, X_i, X_i^2, \dots, X_i^n$		
$X_{i}X_{j},,X_{i}^{p}X_{j}^{n-p},,(X_{i}^{p}X_{j}^{q}X_{k}^{r})$ •Linearly dependent •Expressed in terms of a set of SU(3) preserving operators		
many-body integrid dimensitionsintegrid dimensition0112345162	ty basis ion (S=0) 1 1 3 5 9 13 22	 SRG-induced 2<i>N</i>+3<i>N</i>+4<i>N</i> (<i>S</i>=0): 19 SU(3) preserving operators [analytic MEs] G-induced dominating many-body forces can be tracked during the evolution

$$\frac{dH_{s}}{ds} = \left[\left[C_{2}^{su(3)}, H_{s} \right], H_{s} \right]$$

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$$\frac{d}{ds} V^{\omega_{0}S_{0}T_{0}} = \left[\left[C_{2}^{(00)00}, V^{\omega_{1}S_{1}T_{1}} \right]^{\omega_{1}S_{1}T_{1}}, V^{\omega_{2}S_{2}T_{2}} \right]^{\omega_{0}S_{0}T_{0}} \quad \omega = (\lambda \mu)$$

$$\langle n_{1}n_{2}...n_{A}(\lambda \mu)ST \| V^{\omega_{0}S_{0}T_{0}} \| n_{1}'n_{2}'...n_{A}'(\lambda' \mu')S'T' \rangle$$

$$V^{\omega_{1}S_{1}T_{1}} \times V^{\omega_{2}S_{2}T_{2}}$$

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$$\frac{dH_{s}}{ds} = \left[\left[C_{2}^{su(3)}, H_{s} \right], H_{s} \right]$$

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$$\left\langle n_{1}n_{2}...n_{A}(\lambda \mu)ST \right\| V^{\omega_{0}S_{0}T_{0}} \left\| n_{1}'n_{2}'...n_{A}'(\lambda' \mu')S'T' \right\rangle$$
What are the dimensions of such matrices?
$$V^{\omega_{1}S_{1}T_{1}} \times V^{\omega_{2}S_{2}T_{2}}$$

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Body Problem, INT, 04/01/2009

Number of SU(3)XSU_S(2) 2N, 3N, 4N Tensors



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Summary

> Symmetries are found essential in interactions/many-body systems

- We suggest use of SU(3) basis together with the second-order SU(3) invariant as the evolution operator for the SRG approach
- SRG in SU(3) basis appears to be a very effective scheme for renormalization of the NN interaction: C₂ is a good choice--physically relevant/ weak many-body forces expected
- SU(3)-coupled SRG: possible to be applied in 3-b and 4-b SU(3)coupled basis and track many-body forces (integrity basis)
- Particularly suitable for the Sp-NCSM