

# Time-Correlated Structure in Pulsar Timing Noise

Steve Price  
Montana State University

Collaborators: B. Link, S. Shore, M. Kramer, A. Lyne

# The Goal: To Identify Evidence of Non-rigid Body Rotation

- Timing Noise: Response of the Crust to Stochastic Torque
- All modes are excited (e.g. damped rotational modes, precession, vortex lattice modes)
- Previous studies using Fourier techniques have found no evidence of non-rigid body rotation (Boynton, Deeter, 1969; Boynton, 1981; Boynton, Deeter, et. al., 1984)

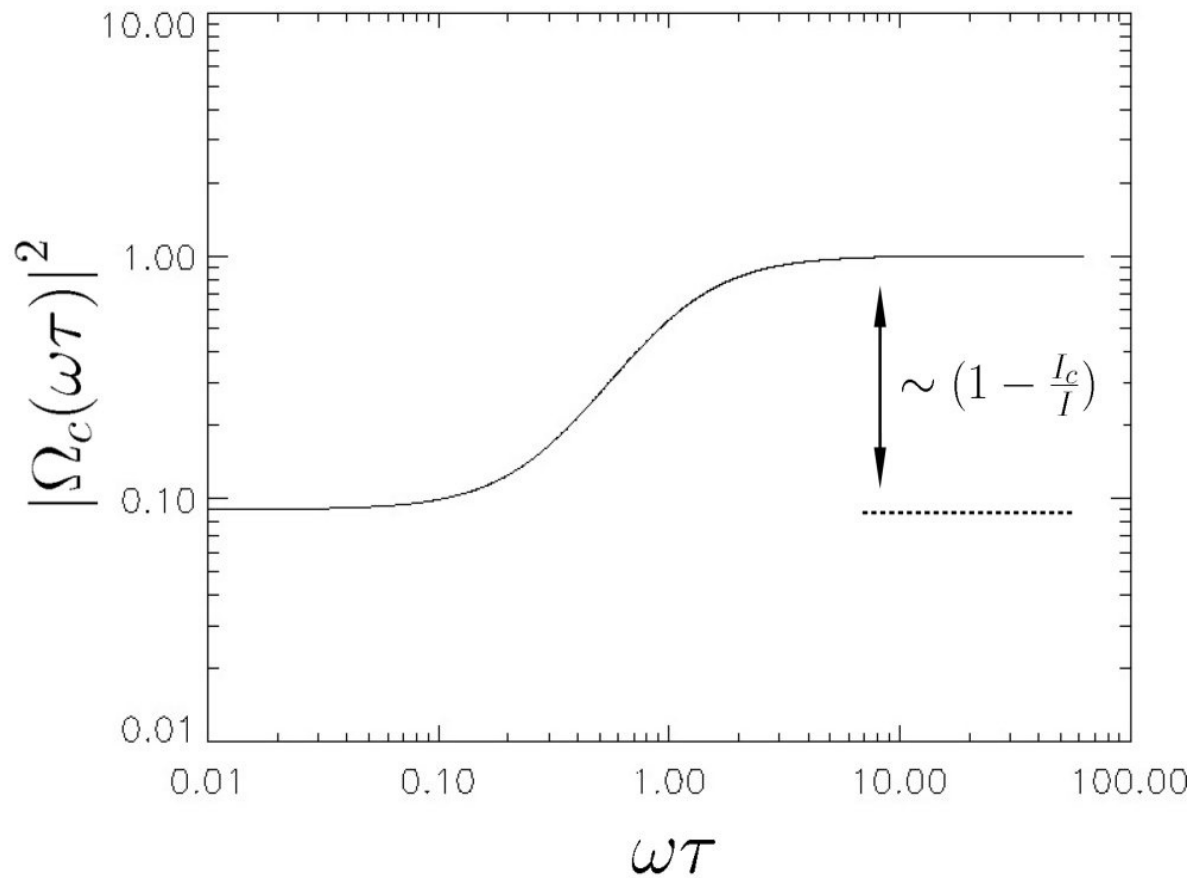
# 2-Component NS Model

$$I_c \dot{\Omega}_c = N(t) - \frac{I_r}{\tau} (\Omega_c - \Omega_s)$$

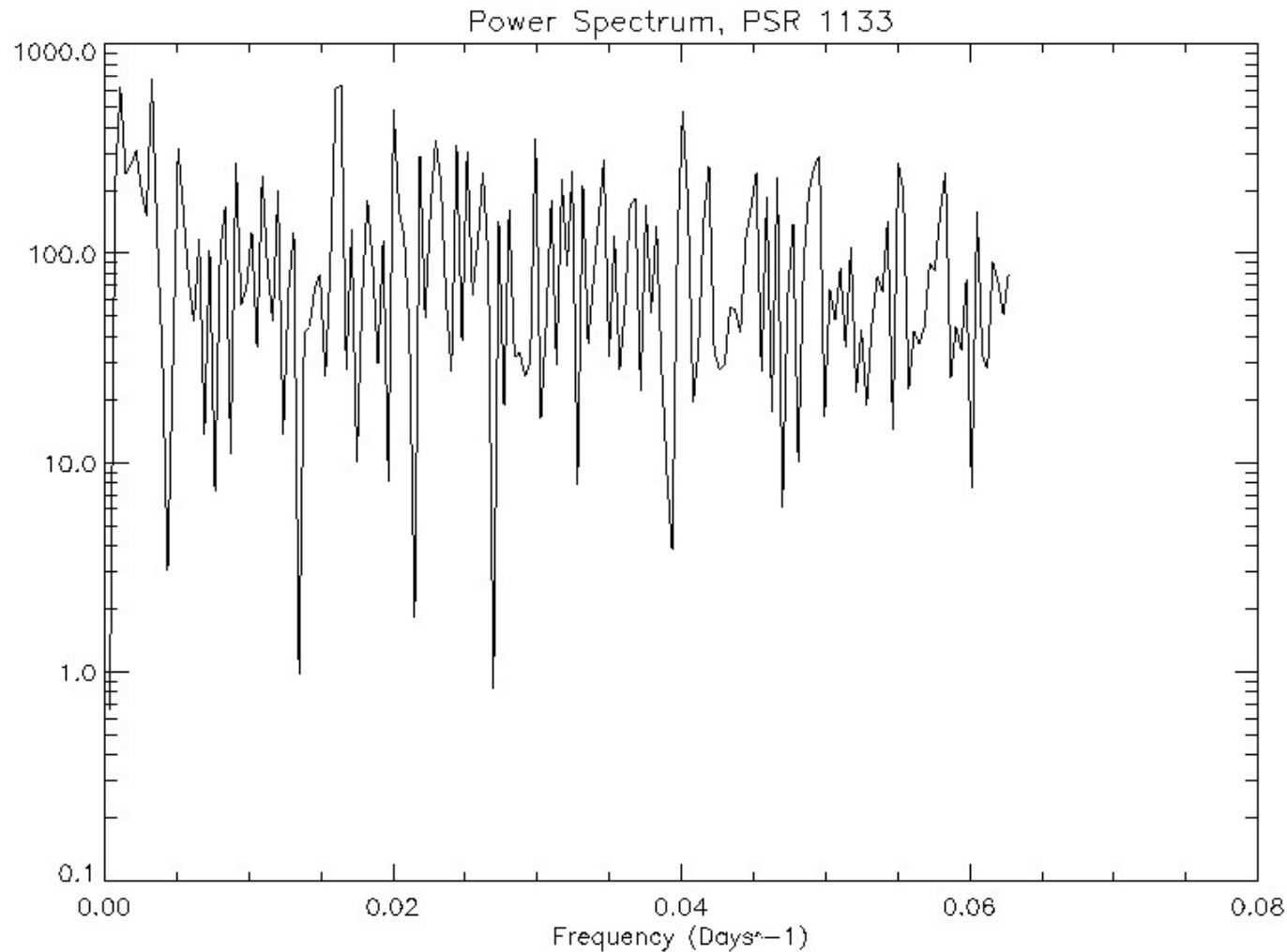
$$I_s \dot{\Omega}_s = \frac{I_r}{\tau} (\Omega_c - \Omega_s)$$

$$|\Omega_c(\omega)|^2 = \left[ \frac{(\omega\tau)^4 + \left(\frac{I_c}{I}\right)^2 (\omega\tau)^2}{(\omega\tau)^4 + (\omega\tau)^2} \right] \frac{|N(\omega)|^2}{\omega^2 I_c^2}$$

# Frequency Response



# Observations



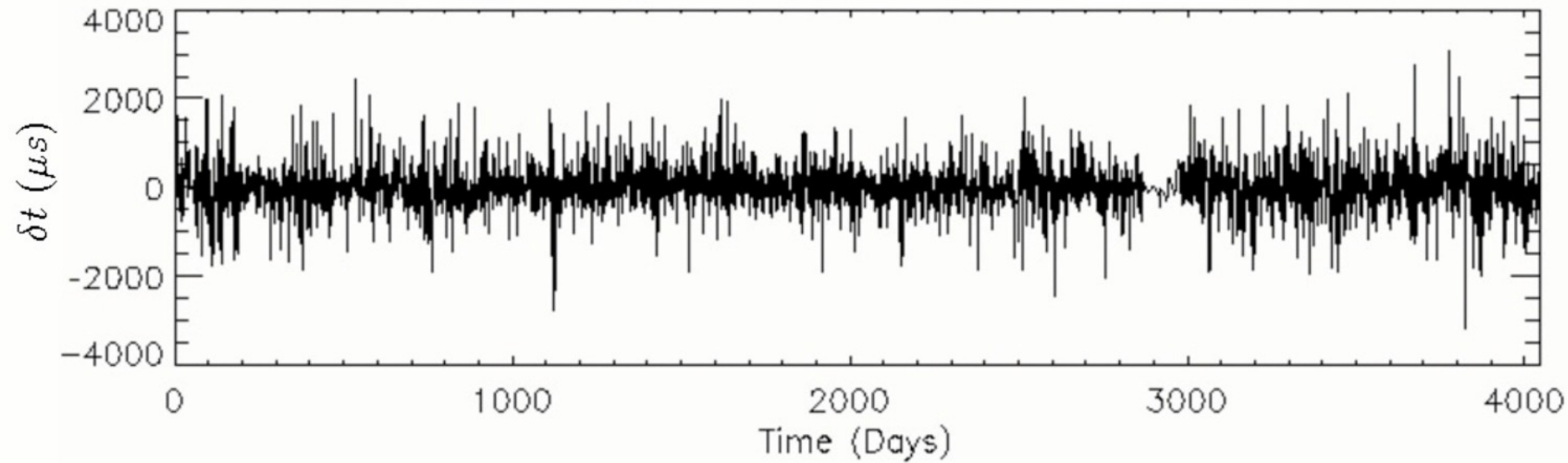
- We use methods in the time domain

# PSR B1133+16

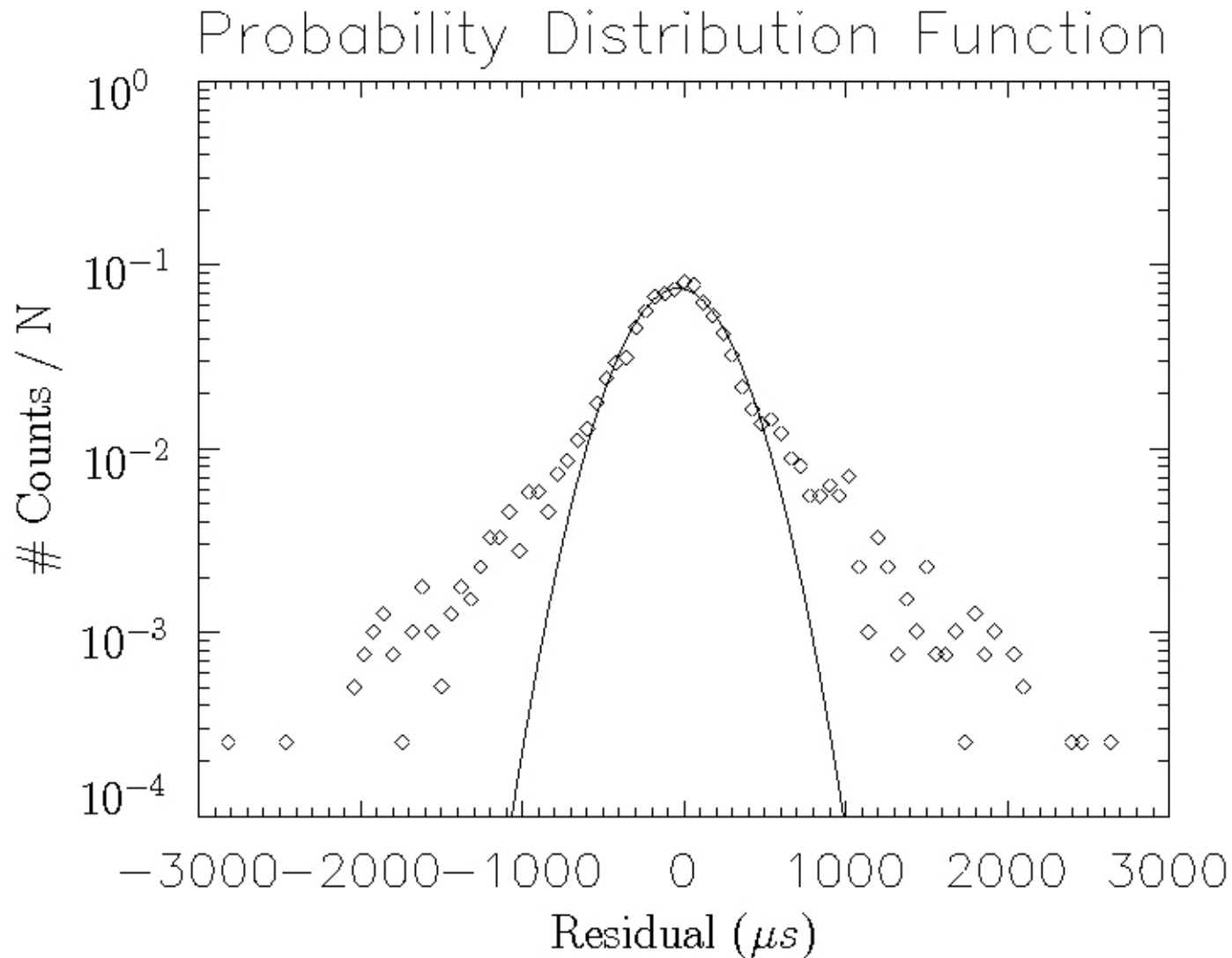
- Spin period:  $P = 1.19 \text{ s}$
- Dipole field:  $|B_d| = 5 \times 10^{12} \text{ G}$
- Spin-down age:  $\tau = 5 \times 10^6 \text{ yrs}$

# The Data

Timing Residuals, PSR 1133+16



# Distribution of Residuals





# Auto-Correlation Function

- For evenly sampled data:

$$ACF(k) = \frac{1}{(n - k) \sigma^2} \sum_{i=1}^{n-k} (y_i - \bar{y})(y_{i+k} - \bar{y})$$

- For unevenly sampled data: we use the discrete correlation function, DCF (Edelson, Krolik, 1988)

# Discrete Correlation Function

$$UDCF_{ij} = \frac{(y_i - \bar{y})(y_j - \bar{y})}{\sigma_y^2}$$

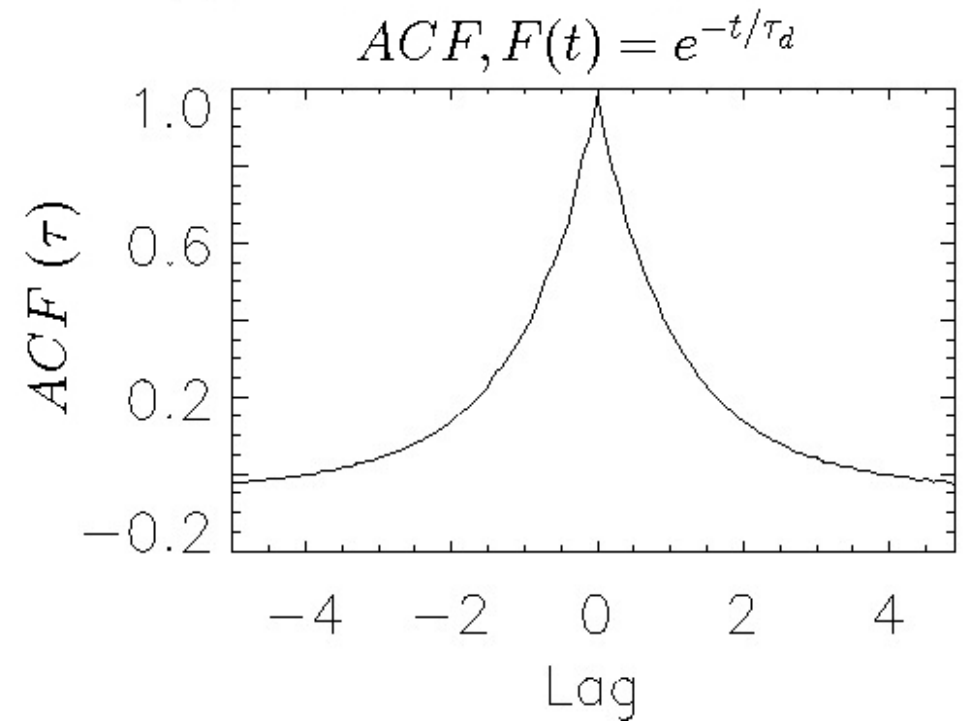
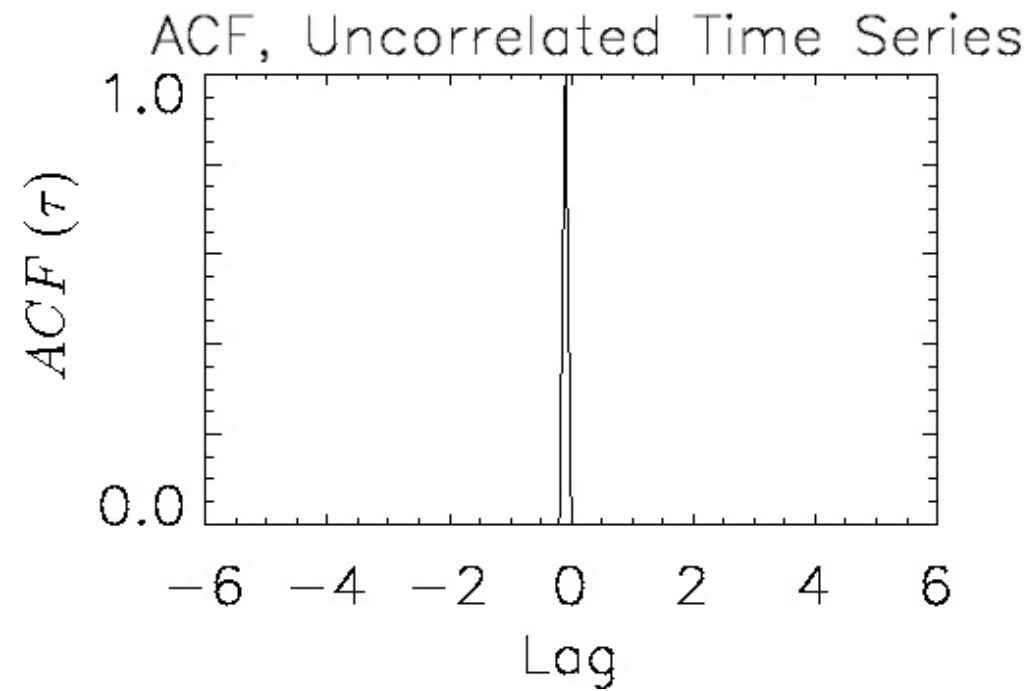
$$DCF(\tau) = \frac{1}{M} \sum_{i=1}^M UDCF$$

$$\tau - \frac{\Delta\tau}{2} \leq t_j - t_i \leq \tau + \frac{\Delta\tau}{2}$$

- Benefits

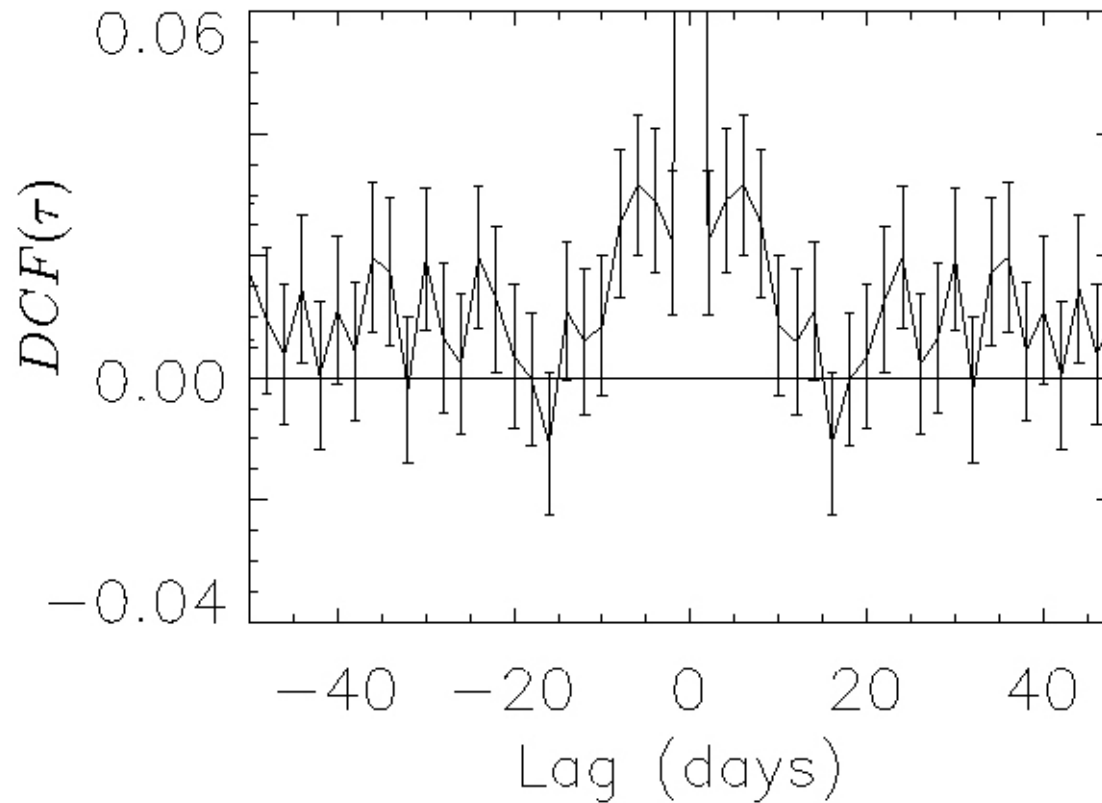
- No binning required
- Uses all data points
- No penalty for gaps in the data

# Auto-Correlation Function



# Discrete Correlation Function

PSR B1133+16



$$S_{corr} = DCF[1] \cdot DCF[2] \cdot DCF[3] \cdot DCF[4]$$

$$S_{corr} \simeq 26 \sigma$$

# Significance

- From Monte Carlo simulations, the probability of the null hypothesis is less than  $10^{-4}$
- Further confirmation: Lagged Dispersion Statistic

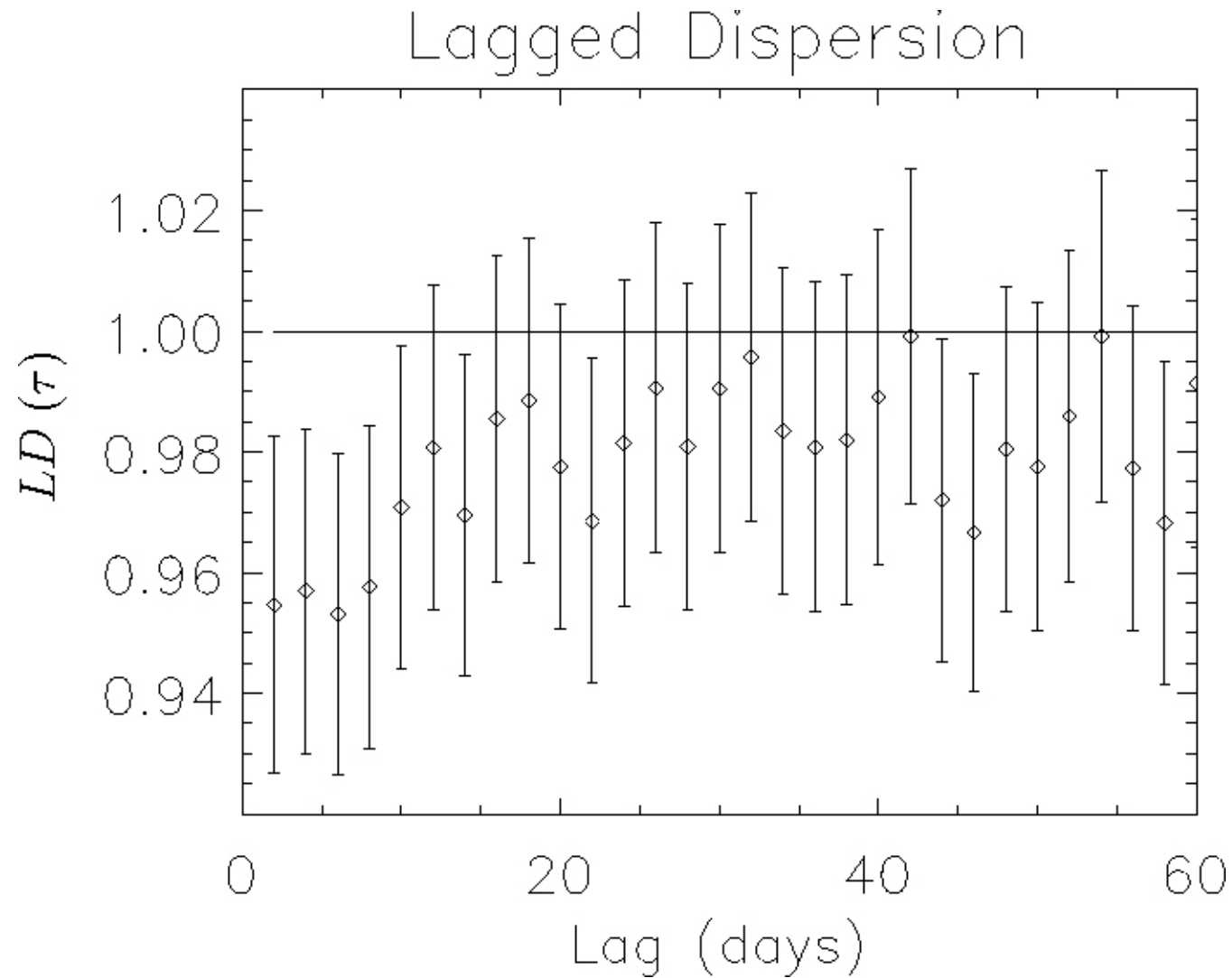
# Lagged Dispersion Statistic

$$\Delta y_{ij} = y_j - y_i$$

$$\tau - \frac{\Delta\tau}{2} \leq t_j - t_i \leq \tau + \frac{\Delta\tau}{2}$$

$$LD(\tau) = \frac{1}{M} \sum (\Delta y_{ij} - \bar{\Delta y})^2$$

# Lagged Dispersion

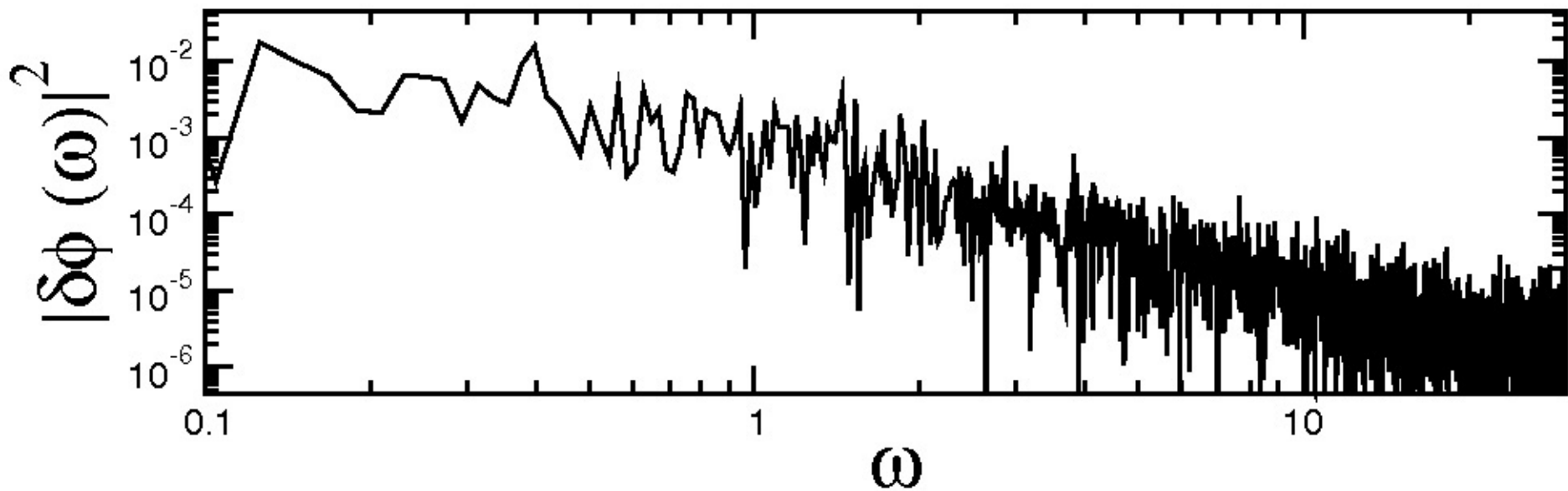
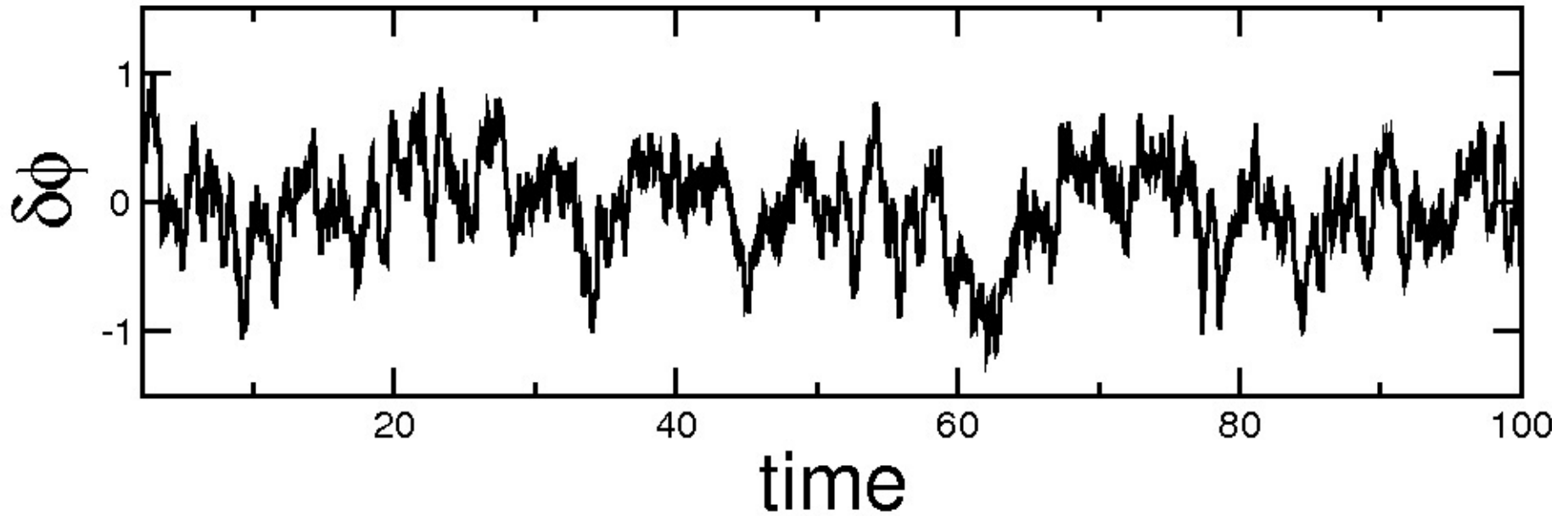


# Conclusions

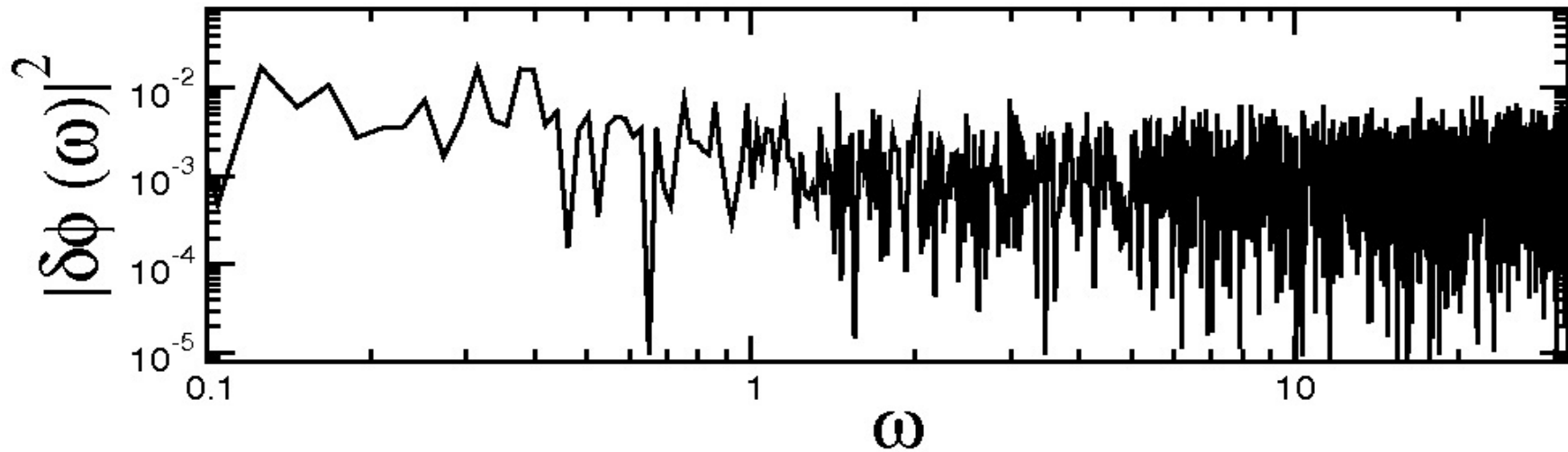
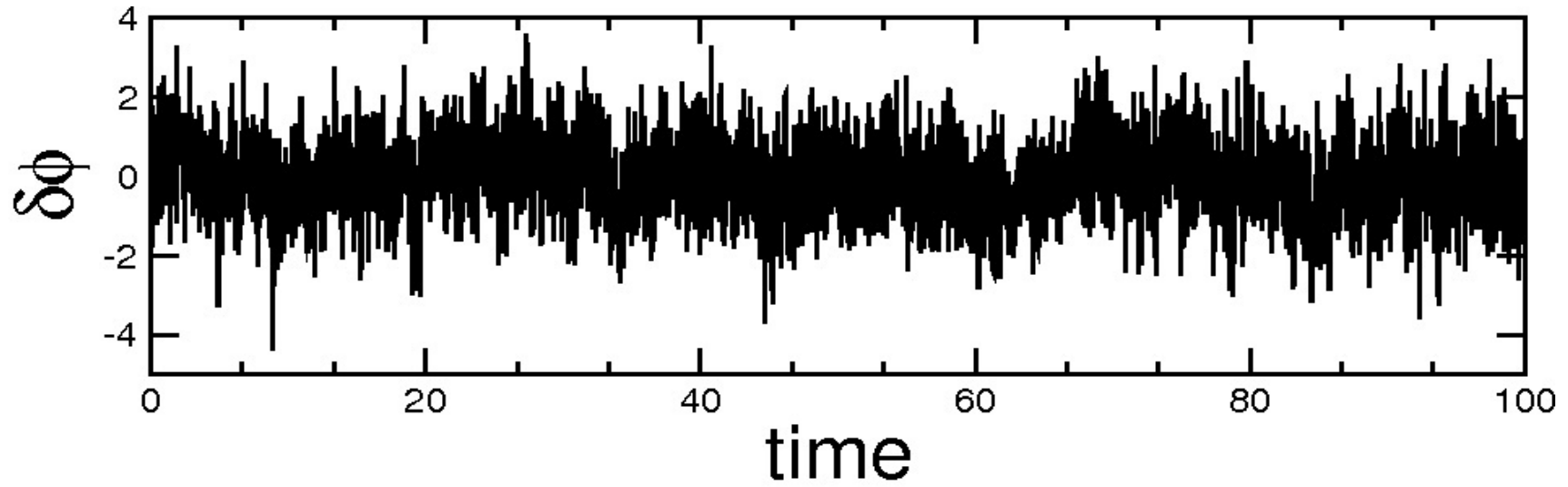
- We find correlation timescale of 10 days in PSR B1133+16
- Interpretation: Deviations from rigid body rotation
- DCF and LD (Time Domain) are better suited for analyzing noisy data than Fourier techniques



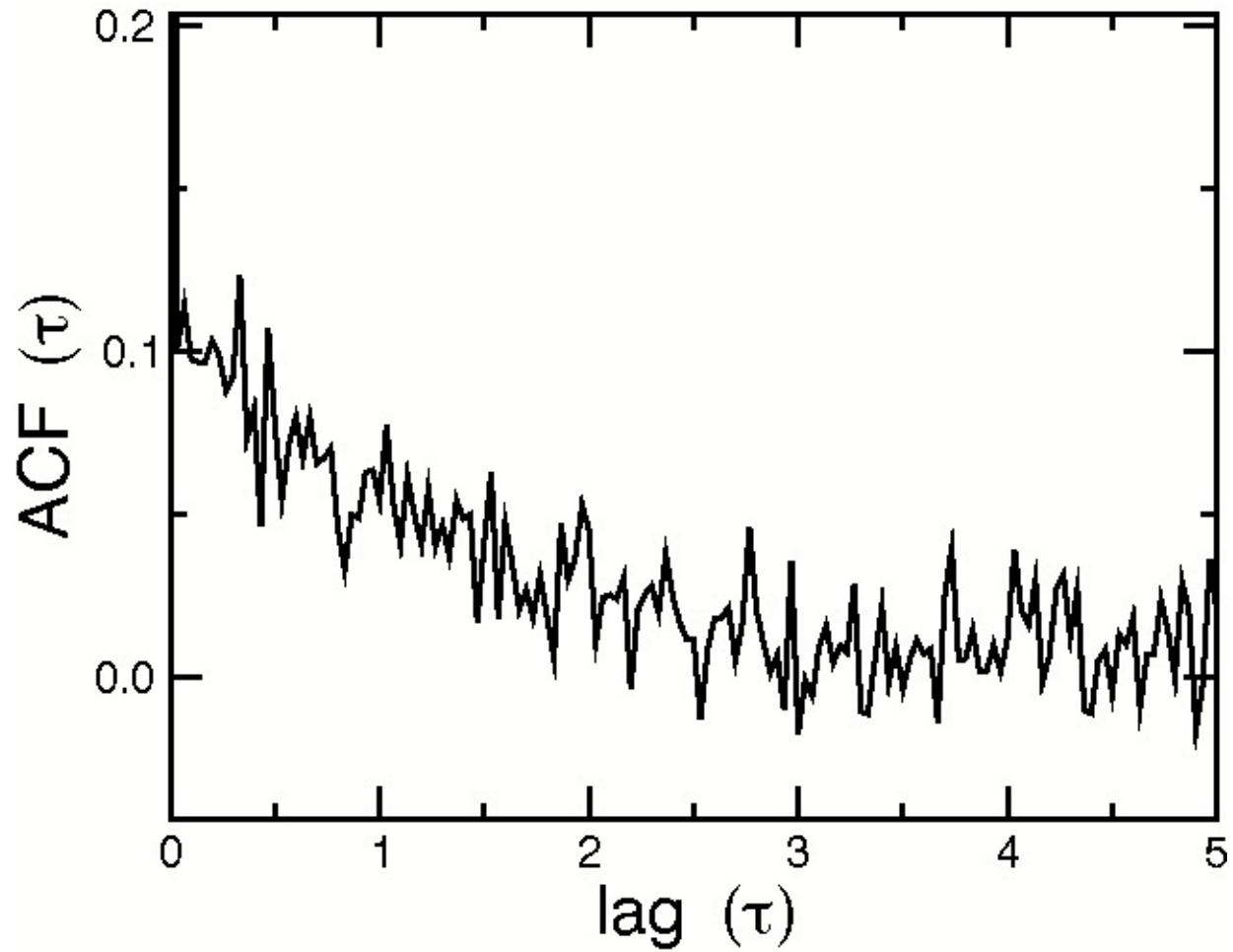
# Error Sensitivity Simulation



# Error Sensitivity Simulation



# Error Sensitivity Simulation



# Future Work

$$I_c \dot{\Omega}_c = N(t) - \frac{I_r}{\tau} (\Omega_c - \Omega_s)$$

$$I_s \dot{\Omega}_s = \frac{I_r}{\tau} (\Omega_c - \Omega_s)$$

- Constrain values of moment of inertia ratio using our results