Magnetic Mapping for the ⁶He Experiment REU Final Presentation

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Motivation

- Search for Beyond the Standard Model (BSM) physics through precision experiment
- predicted by other theories: supersymmetry, Grand Unified Theories



Background - Weak Interaction

- Weak interaction fundamental force
- responsible for β decay

$$^{6}\text{He} \rightarrow {}^{6}\text{Li} + e^{-} + \bar{\nu_{e}}$$

- mediated by W^- boson
- new physics: interactions



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Background - Parity Violation

Parity is the inversion of spatial coordinates

$$(ct, x, y, z)
ightarrow (ct, -x, -y, -z)$$

 $\hat{P}\vec{r} = -\vec{r}$
 $\hat{P}\vec{L} = (-\vec{r}) imes (-\vec{p}) = \vec{r} imes \vec{p}$

- Parity shows symmetry under the inversion of spatial coordinates
- with parity: expected both rightand left-handed particles
- Chien Sheng-Wu 1957 left-handed particles only



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Helicity and Chirality

Helicity:



Helicity *not* Lorentz invariant \rightarrow solution: define *Chirality*

 $e^{L} = \sqrt{\frac{1+\frac{p}{E}}{2}}e^{H=-1} + \sqrt{\frac{1-\frac{p}{E}}{2}}e^{H=+1}$ $e^{R} = \sqrt{\frac{1-\frac{p}{E}}{2}}e^{H=-1} + \sqrt{\frac{1+\frac{p}{E}}{2}}e^{H=+1}$

$$e^R e^L = \sqrt{1 - (rac{p}{E})^2} = rac{m}{E}$$

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Interaction Hamiltonian for ⁶He beta decay:

$$H_{int} = \frac{\bar{\psi}_{f} \gamma^{\mu} \gamma_{5} \psi_{i} (2C_{A}e^{-L}\gamma_{\mu}\gamma_{5}\nu_{e}^{L}) +}{\bar{\psi}_{f} \sigma^{\mu\nu} \psi_{i} [(C_{T} - C_{T}')e^{-L}\sigma_{\mu\nu}\nu_{e}^{R} + (C_{T} + C_{T}')e^{-R}\sigma_{\mu\nu}\nu_{e}^{L}]}$$

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Search for tensor currents $(\sigma_{\mu\nu})$

Chirality-flipping - Fierz Interference

- terms that include RH & LH are chirality flipping
- show small distortions to spectrum

$$dW = dW_0(1 + arac{ar{
ho_e}\cdotar{
ho_\nu}}{E_eE_
u} + brac{\Gamma_m_e}{E_e}) \ b pprox rac{(C_T+C_T')}{C_A}$$



Measuring the β spectrum - CRES technique

- need precision measurements of the entire spectrum
- 6 GHz bandwidth, tune magnet
- Cyclotron Radiation Emission Spectroscopy (Project 8)



My Contribution

Magnetic Modeling

- 1. adapt NMR probe
- 2. multipole expansion
 - 3. position mapping

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Place the probe in the magnet at a particular location $(\hat{r}, \hat{\theta}, \hat{z})$



Nuclear Magnetic Resonance (NMR) Principles

- start with a sample in a magnetic field, B_0
- perturb with a small oscillating field, B_1
- at resonance, induces an energy transition by flipping magnetization
- produces a strong signal at this frequency
 characteristic of magnetic field seen by nucleus
- use this magnitude measurement & fit to multipole expansion





Laplace's Equation:

$$\nabla^2 \phi_m = 0$$

Solutions: Taylor Expansion with spherical harmonics:

$$\phi_m = \sum_{l=0}^{\infty} \sum_{m=-l}^{l} (a_l^m r^l + b_l^m r^{-(l+1)}) Y_l^m$$



Theodolite Mapping



- accurate position measurements for probe
- position accuracy impacts accuracy of Linear Least Squares fit in code

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Position mapping: z=-20 cm



- Mean (x,y) values for set r
- colors show r-value
- Additional measurements: z=0 and z=+20 cm (not yet finished)

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Future Investigation

- Finish position mapping of magnet
- Automate gadget & Teslameter data collection process
- Improvements on multipole model

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