Development of the Zeeman Slower for the Ultra-cold Atomic Interference Experiment

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Outline

- Introduction laser cooling, Zeeman slowers
- Design optimizing magnetic field
- Construction winding procedure and techniques
- Results acquisition of data, compare with expectations
- Simulation analyzing velocity profile and distribution

Introduction, scattering force

•
$$
F_{scatt} = \hbar k \frac{\Gamma}{2} \frac{s}{1+s+4\delta^2/\Gamma^2}
$$

\n• where $s = I/I_{sat}$
\n• $a_{max} = \frac{F_{max}}{m} = \frac{\Gamma \hbar k}{2 m}$
\n• $a = f a_{max}$

Introduction, Doppler shift

•
$$
\delta = \delta_{lab} + \overline{k}\overline{\overline{v}}
$$

Introduction, Zeeman effect

•
$$
\delta = \delta_{lab} + \vec{k}\vec{v} + \frac{\vec{\mu_B}\vec{B}}{\hbar}
$$

Introduction, derivation

• Constant acceleration

•
$$
v_0^2 = v^2 + 2az
$$

\n• $v_0^2 = 2aL$
\n• $v = \sqrt{v_0^2 - 2az}$
\n• $v = v_0\sqrt{1 - z/L}$
\n• $k\vec{v} = \frac{\overline{\mu_B}\,\overline{B}}{\hbar}$
\n• $B(z) = \frac{k\hbar v_0}{\mu_B}\sqrt{1 - z/L}$

Introduction, slower equations

• Ideal Zeeman slower

•
$$
a_{max} = \frac{\Gamma h k}{2 m}
$$

\n• $v_{capt} = \sqrt{2 f a_{max} L}$
\n• $B_{max} = \frac{h k v_{capt}}{\mu_B}$

$$
\bullet \ \ B(z) = B_{max} \left(1 - \sqrt{1 - \frac{z}{L}} \right)
$$

Ideal magnetic field profile

⁽at 35 Amps)

Ideal magnetic field profile

*Mayera, Minarik, Shroyer, Mclntyre

Ideal velocity distributions

Ideal velocity distributions

Optimizing the design

• Axial Magnetic Field of a single coil:

•
$$
B(z) = \left(\frac{\mu_0 I}{d}\right) / \left(1 + \left(\frac{2z}{d}\right)^2\right)^{3/2}
$$

• Summary equation used for optimization:

•
$$
B(z) = \sum_{j=0}^{l} \sum_{i=0}^{n_j} \left(\frac{\mu_0 I}{d_j}\right) / \left(1 + \left(\frac{2 z_i}{d_j}\right)^2\right)^{3/2}
$$

Final design, geometry

• Dimensions in inches

- $\sqrt{}$ indicates compensation "reverse" coils
- indicates normal "forward" coils
- Indicates "offset" coils

Final design, magnetic field profile

Final design, magnetic field profile

Deviation from ideal magnetic field

Winding procedure, materials

- Specifications of the wire used:
	- Insulated hollow square copper wire
	- Dimensions in inches:

• General notes on winding:

• Segments of wire, for separate cooling lines

• Assembly of all layers, drying on the lathe

- Unwrap and label the lead wires
- Check for material flaws

Recall geometric design and terms

- Dimensions in inches
	- $\cdot \nabla$ indicates compensation "reverse" coils
	- indicates normal "forward" coils
	- I indicates "offset" coils

Reverse layers:

Relative positions of the above three:

Testing, magnetic field profiles Simultaneous forward and reverse layers: (at 3.00A and ~1.2V)Axial Magnetic Field / Gauss $\mathbf{\hat{10}}$ $\overline{2}$ Position / inches

• Simultaneous forward and reverse layers:

Simulations, velocity profiles • Position dependent velocity profiles 500 Gauss 400 Axial Velocity / (m/s) Axial Magnetic Field 300 200 100 detuning = -7 Γ $current = 35 A$ 60 30 10 20 40 50 Postion / cm $offset = 20 A$

Simulations, velocity distributions

Simulations, velocity distributions

Conclusions and Future Work

- **Conclusions**
	- Zeeman slower works as predicted
	- Offset field works as expected
- Future work
	- Optimized currents and detuning
	- Additional components for the apparatus
	- Ultra-cold atomic interference experiment

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