Development of the Zeeman Slower for the Ultra-cold Atomic Interference Experiment

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Outline

- Introduction laser cooling, Zeeman slowers
- Design optimizing magnetic field
- Construction winding procedure and techniques
- Results acquisition of data, compare with expectations
- Simulation analyzing velocity profile and distribution

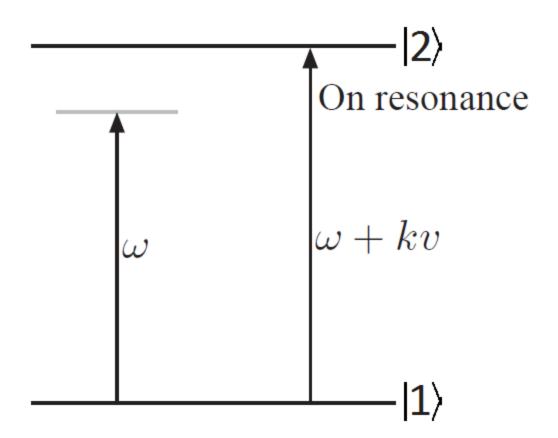
Introduction, scattering force

•
$$F_{scatt} = \hbar k \frac{\Gamma}{2} \frac{s}{1+s+4\delta^2/\Gamma^2}$$

• where $s = l/l_{sat}$
• $a_{max} = \frac{F_{max}}{m} = \frac{\Gamma}{2} \frac{\hbar k}{m}$
• $a = f a_{max}$
• Oven Laser
*Foot, 195

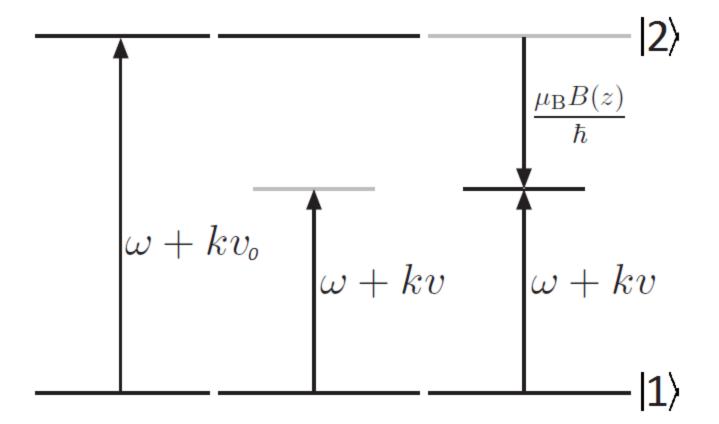
Introduction, Doppler shift

•
$$\delta = \delta_{lab} + \vec{k}\vec{v}$$



Introduction, Zeeman effect

•
$$\delta = \delta_{lab} + \vec{k}\vec{v} + \frac{\overrightarrow{\mu_B}\overrightarrow{B}}{\hbar}$$



Introduction, derivation

• Constant acceleration

•
$$v_0^2 = v^2 + 2az$$

• $v_0^2 = 2aL$
• $v = \sqrt{v_0^2 - 2az}$
• $v = v_0\sqrt{1 - z/L}$
• $\vec{k}\vec{v} = \frac{\overline{\mu}\vec{B}}{\hbar}$
• $B(z) = \frac{k\hbar v_0}{\mu_B}\sqrt{1 - z/L}$

Introduction, slower equations

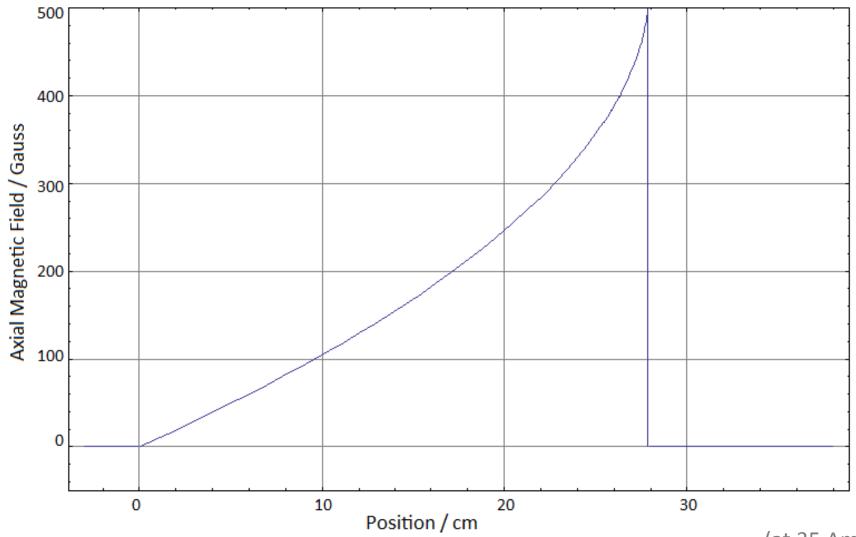
Ideal Zeeman slower

•
$$a_{max} = \frac{\Gamma}{2} \frac{\hbar k}{m}$$

• $v_{capt} = \sqrt{2 f a_{max} L}$
• $B_{max} = \frac{\hbar k v_{capt}}{\mu_B}$

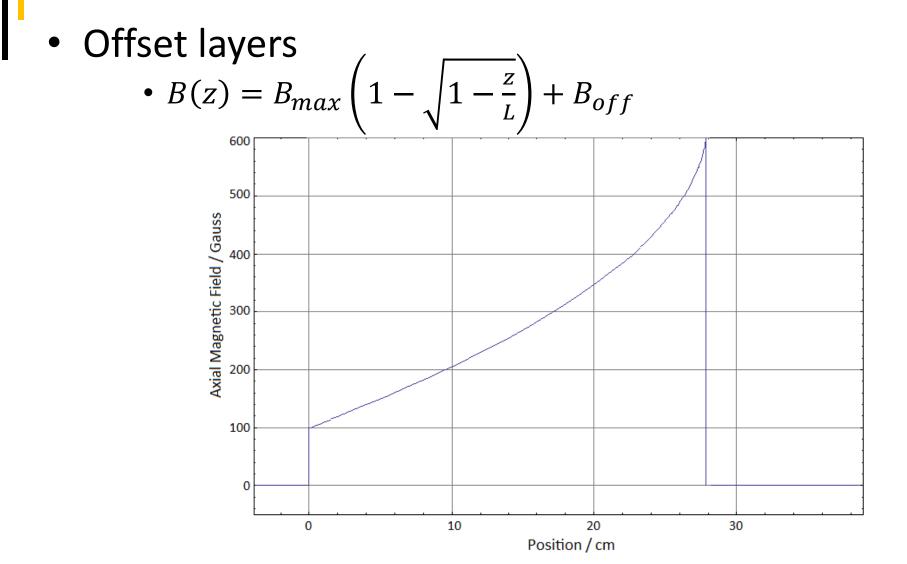
•
$$B(z) = B_{max} \left(1 - \sqrt{1 - \frac{z}{L}} \right)$$

Ideal magnetic field profile



⁽at 35 Amps)

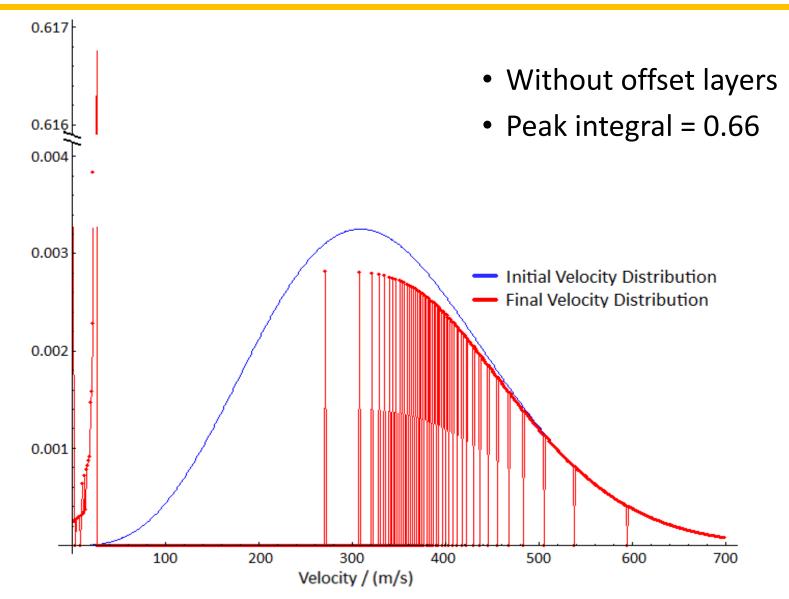
Ideal magnetic field profile



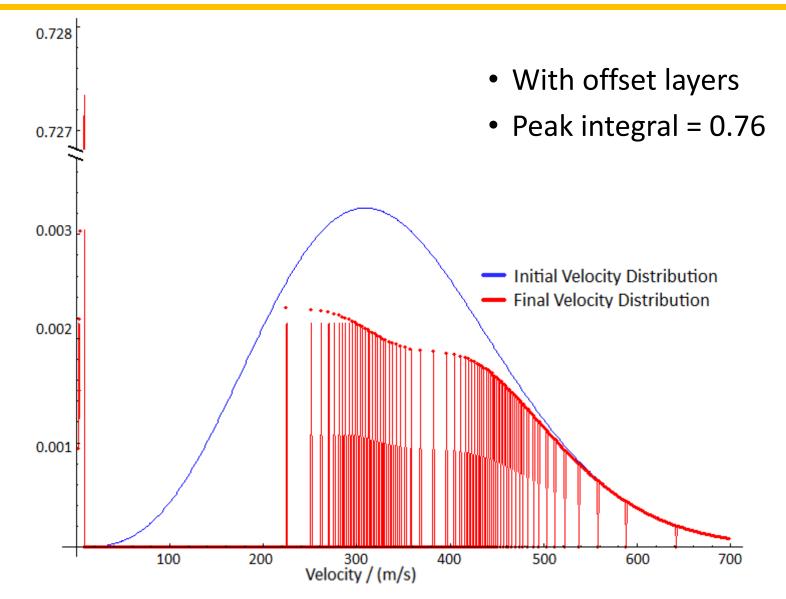
Ideal velocity distributions Velocity (m/s)

*Mayera, Minarik, Shroyer, McIntyre

Ideal velocity distributions



Ideal velocity distributions



Optimizing the design

• Axial Magnetic Field of a single coil:

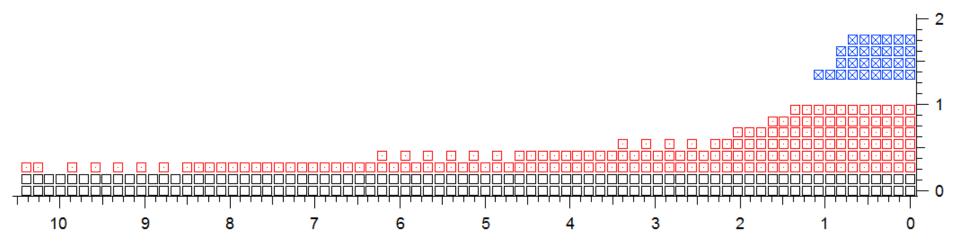
•
$$B(z) = \left(\frac{\mu_0 I}{d}\right) / \left(1 + \left(\frac{2 z}{d}\right)^2\right)^{3/2}$$

• Summary equation used for optimization:

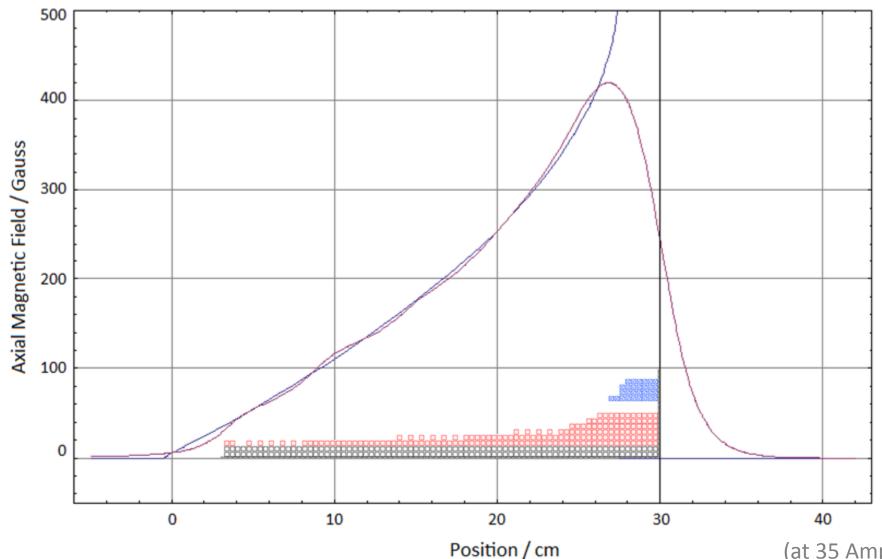
•
$$B(z) = \sum_{j=0}^{l} \sum_{i=0}^{n_j} \left(\frac{\mu_0 I}{d_j} \right) / \left(1 + \left(\frac{2 z_i}{d_j} \right)^2 \right)^{3/2}$$

Final design, geometry

- Dimensions in inches
 - indicates compensation "reverse" coils
 - indicates normal "forward" coils
 - indicates "offset" coils



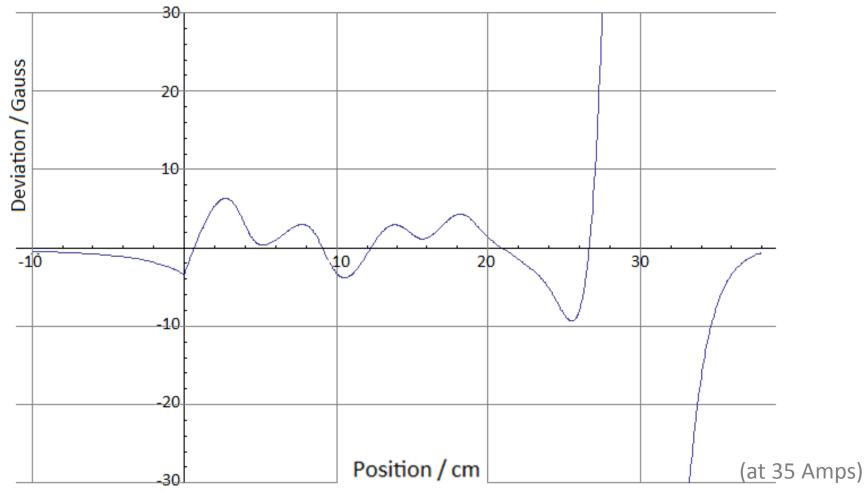
Final design, magnetic field profile



⁽at 35 Amps)

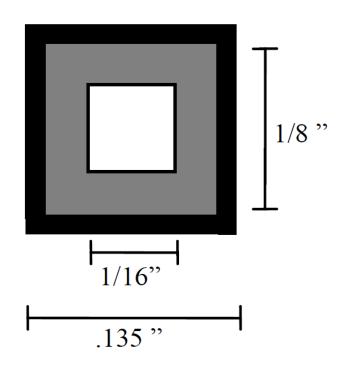
Final design, magnetic field profile

• Deviation from ideal magnetic field

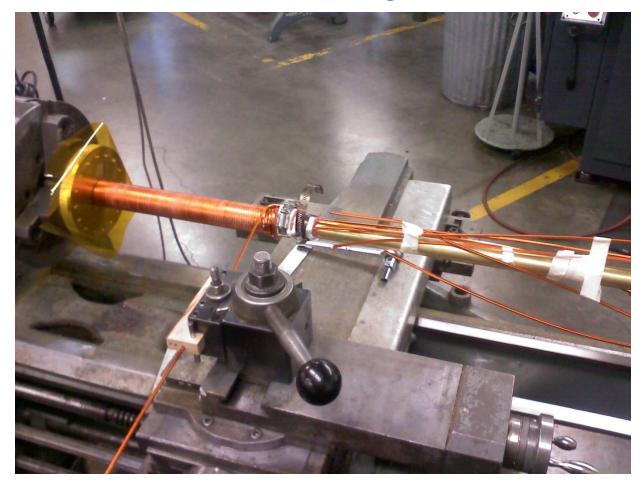


Winding procedure, materials

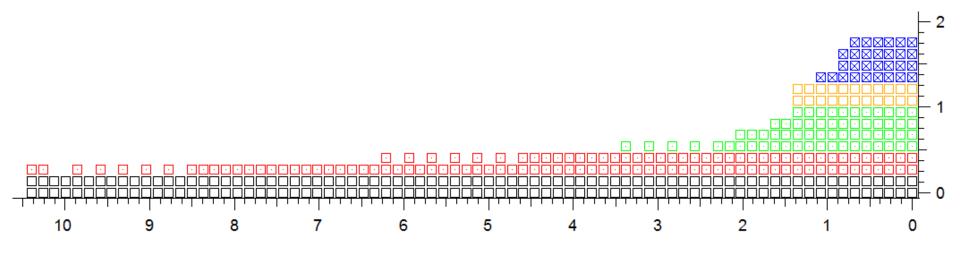
- Specifications of the wire used:
 - Insulated hollow square copper wire
 - Dimensions in inches:

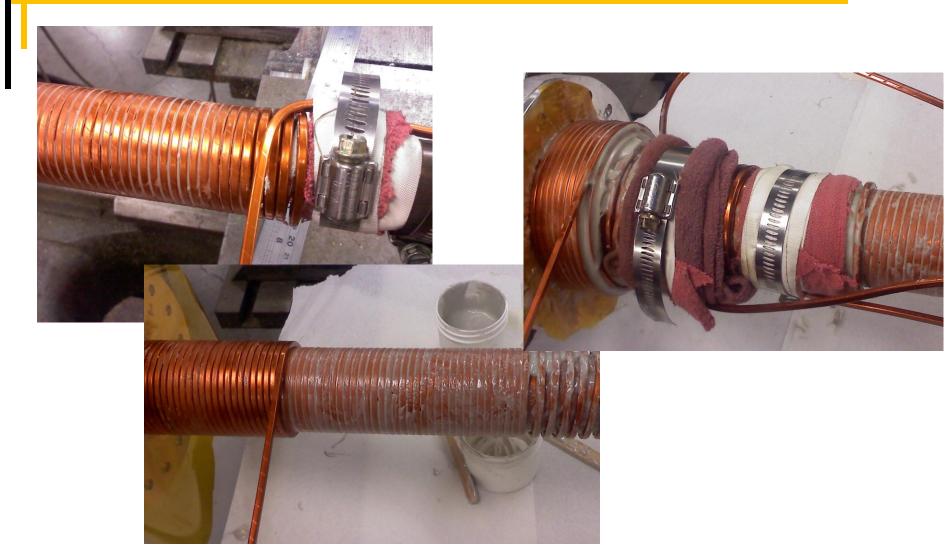


• General notes on winding:

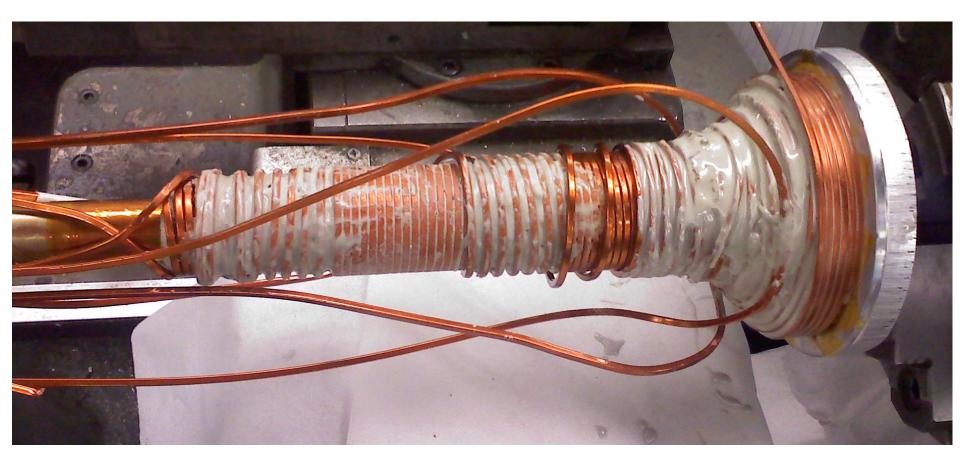


• Segments of wire, for separate cooling lines

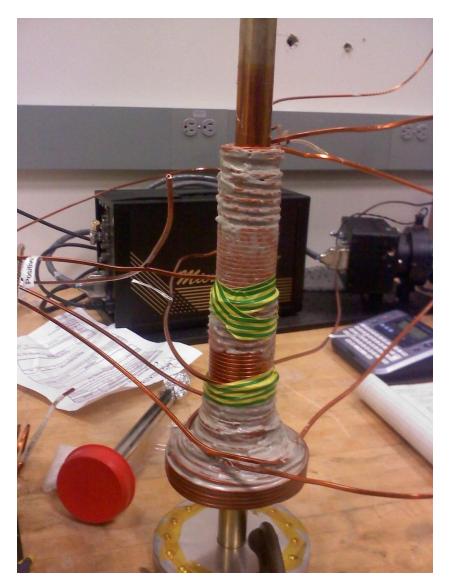




• Assembly of all layers, drying on the lathe

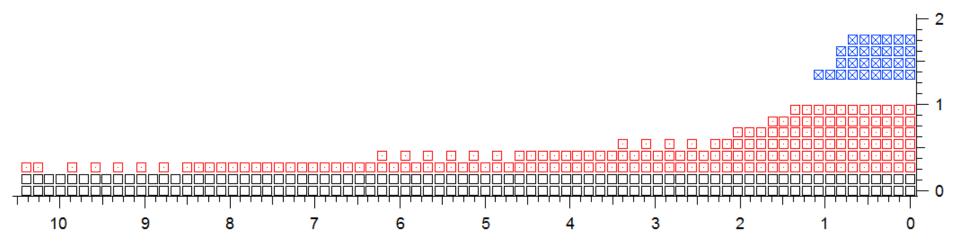


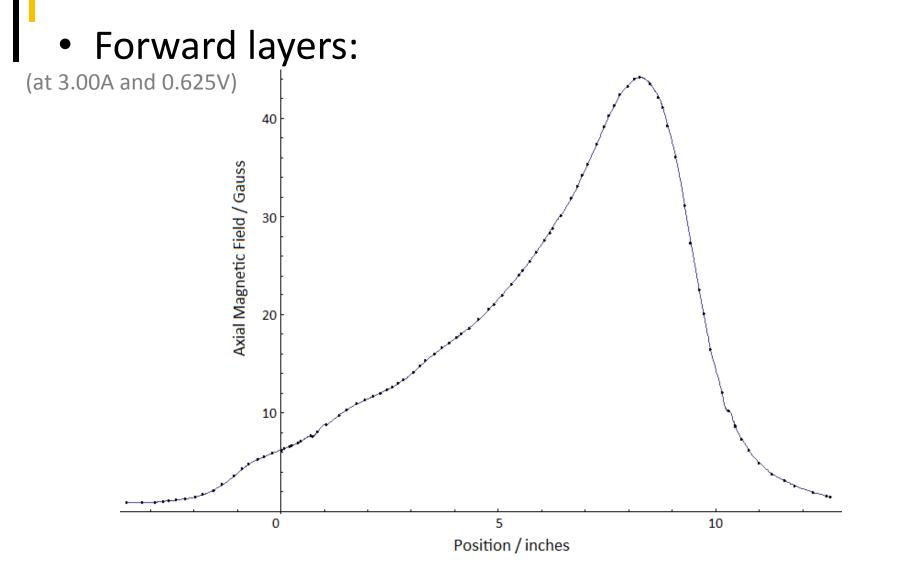
- Unwrap and label the lead wires
- Check for material flaws



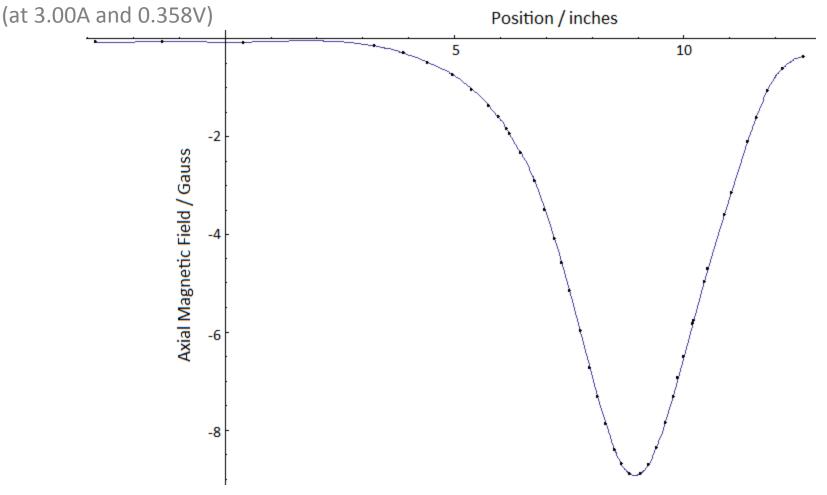
Recall geometric design and terms

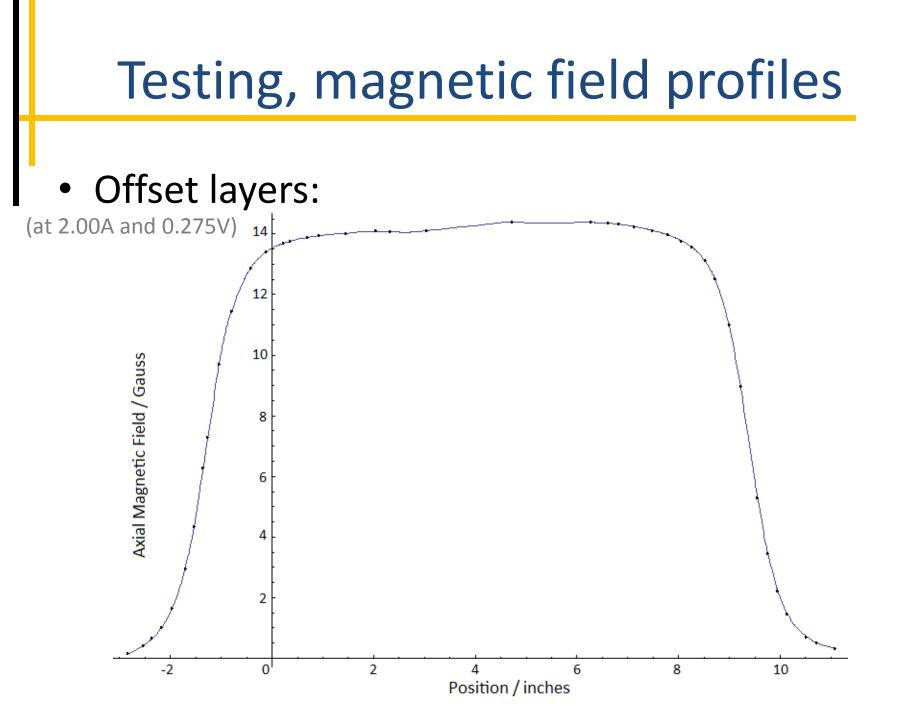
- Dimensions in inches
 - indicates compensation "reverse" coils
 - indicates normal "forward" coils
 - indicates "offset" coils



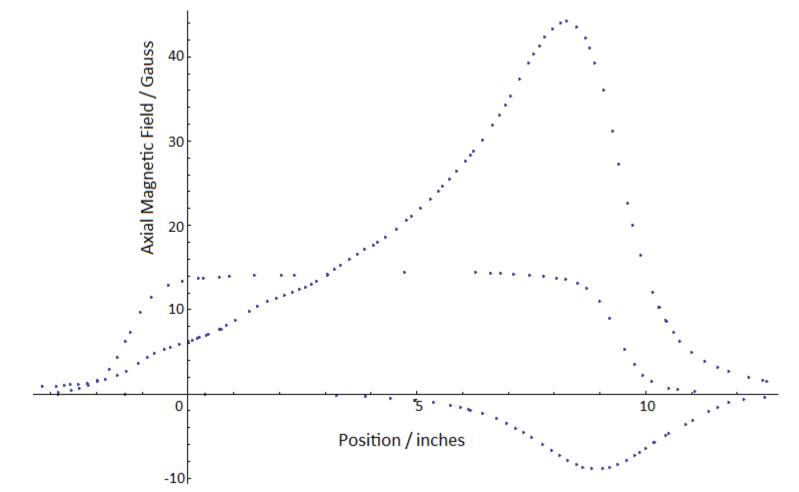


• Reverse layers:

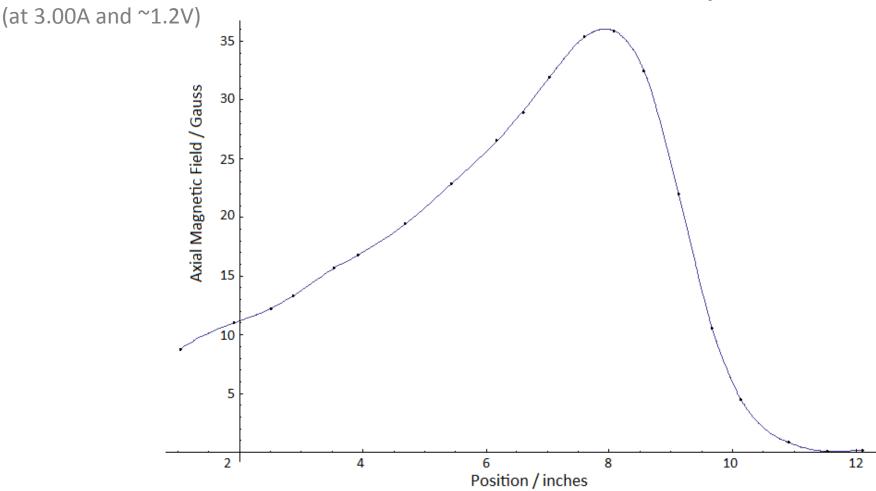




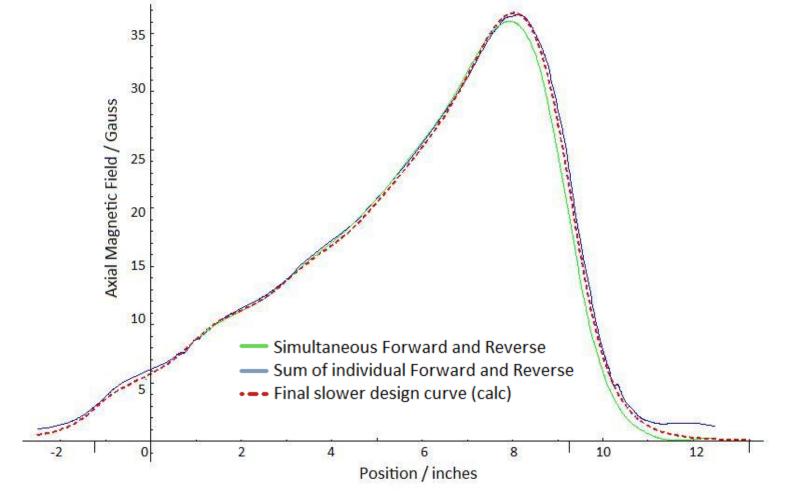
• Relative positions of the above three:



• Simultaneous forward and reverse layers:



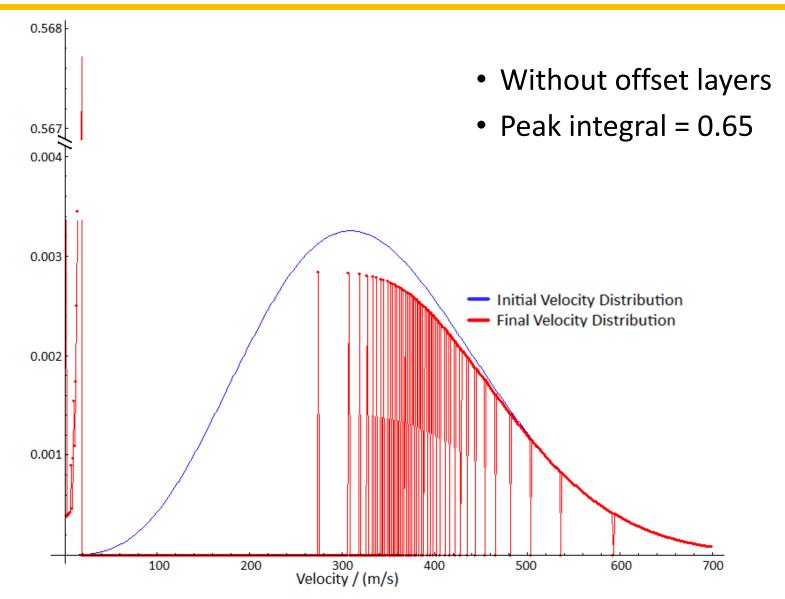
• Simultaneous forward and reverse layers:



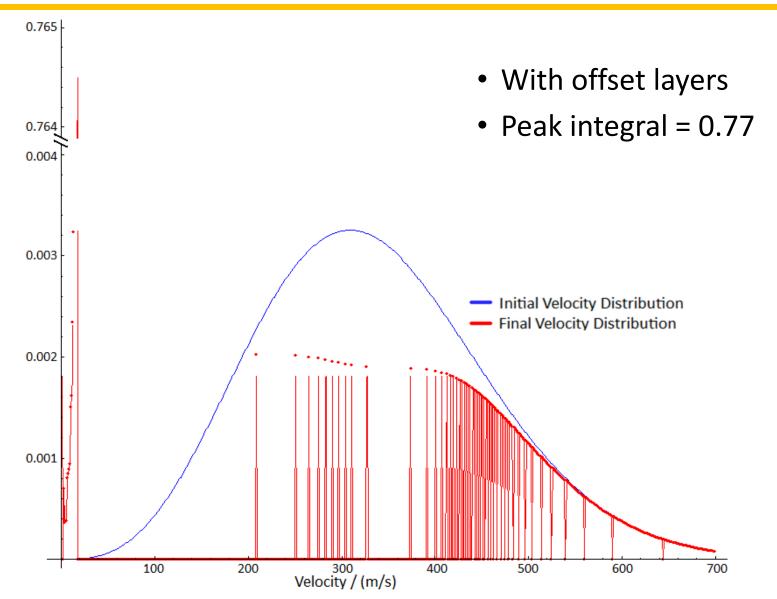
Simulations, velocity profiles Position dependent velocity profiles 400 Axial Magnetic Field / Gauss 300 Axial Velocity / (m/s) 200 100 detuning = 0Γ current = 35 A30 10 20 60 40 50 Position / cm offset = 0 A

Simulations, velocity profiles Position dependent velocity profiles 500 Gauss 400 Axial Velocity / (m/s) Axial Magnetic Field 300 200 100 detuning = -7Γ current = 35 A60 30 10 20 50 40 Postion / cm offset = 20 A

Simulations, velocity distributions



Simulations, velocity distributions



Conclusions and Future Work

- Conclusions
 - Zeeman slower works as predicted
 - Offset field works as expected
- Future work
 - Optimized currents and detuning
 - Additional components for the apparatus
 - Ultra-cold atomic interference experiment

References and Bibliography

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